## Annotation

- Directive forward
- Standard units,
- Pointers.

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- This directive is placed after the function prototype:

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- Cyclic dependence seems unsolvable...
- until we find the forward directive!
- This directive is placed after the function prototype:
- procedure two(a:integer);forward;

# Forward example:

```
program qq;
procedure two(a:integer);forward;
procedure one(a:integer);
begin
      two(a);
end;
procedure two(a:integer);
begin
      one(a);
end;
begin
      one(1):
      {Let us ignore that this program does
not make a good sense!}
```

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- bidirectional (pointers next and prev).

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- It is possible to implement them using array,...
- but it is much better to use linear lists!



## Buffer

Implementation I/III

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Implementation II/III

```
type pbuf=^buf;
buf=record
     val:integer;
     next:pbuf;
end;
var head:pbuf;
procedure push(what:integer);
var tmp:pbuf;
begin
     new(tmp);
     tmp^.val:=what;
     tmp^.next:=head;
     head:=tmp;
end:
```

## Buffer

#### Implementation III

```
function pop:integer;
var tmp:pbuf;
begin
     tmp:=head;
     if head<>nil then
     begin pop:=head^.val;
          head:=tmp^.next;
          dispose(pom);
     end else
     begin writeln('Error!');
          pop:=-1;
     end;
```

# Queue

#### Implementation

```
type=pq=^queue;
queue=record
    val:integer;
    next:pq;
end;
var head,tail:pq;
procedure init;
begin
    head:=nil; tail:=nil; end;
```

```
procedure enqueue(what:integer);
var tmp:pq;
begin if head=nil then
     begin new(head);
          tail:=head;
          head \.next:=nil;
          head . val := what;
     end else
     begin new(tmp);
          tmp^.next:=nil;
          tmp^.val:=what;
          head \.next:=tmp;
          head:=tmp;
     end;
end;
```

```
function dequeue:integer;
var tmp:pq;
begin if head=nil then
      begin dequeue:=-1;
      end else
      begin if head=tail then
            begin dequeue:=tail^.val;
                  dispose(tail);
                  head:=nil; tail:=nil;
            end else
            begin dequeue:=tail^.val;
                  tmp:=tail;
                  tail:=tail^.next;
                  dispose(tmp);
            end;
      end;
```

# Switch two neighboring elements

Switch an element in a linear list with its neighbor

```
procedure swap(var head:11; what:11);
var tmp:ll;
begin tmp:=head;
      if head=what then
      begin head:=head^.next;
            tmp^.next:=head^.next;
            head \.next:=tmp;
      end else
      begin while(tmp^.next<>what) do
                  tmp:=tmp^.next;
            tmp^.next:=what^.next;
            what^.next:=tmp^.next^.next;
            tmp^.next^.next:=what;
```

# Dynamic data structures

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- The examples sometimes omit singularities (empty list, an element not in the list, one-element-list...). All this would be implemented by several tests for nil.
- Good exercise: Bubblesort over linear list.
- Organizing (an ordered) linear list (functions insert, delete and member that are working with the ordered linear list).

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  - insert inserts an element into a list,
  - delete deletes an element from a list.
- Example see webpage (or we are going to write it here).

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- Move-front rule, transposition rule:
- When accessing a member, we move it to the beginning or change with its (immediate) predecessor, respectively.
- Idea: Usually we are accessing the same element repeatedly (in a short time) but our interests are changing.

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- How to implement it?
- Each element gets more than one ancestor (left, right).

# Tree representation

in Pascal

```
type tree=^vertex;
    vertex=record
        val:longint;
        left:tree;
        right:tree;
        ...
end;
```

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- If we build it well, it becomes more efficient than a linear-list.
- If we build it badly, it collapses into a linear-list.
- How to build a balanced binary search tree (and how to keep the tree balanced)?
- Balanced BST is a tree where for each element # elements in the left subtree (of this element) and # elements in the right subtree differ at most by 1.

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- build a balanced BST on larger elements (recursively),
- set these trees to be sibings of the root.

### BST - data structures

- We are going to build from an array (uninteresting [obvious])
- Dynamic data structure representing nodes [vertices] of the tree:

```
type pbst:^bst;
   bst=record
   val:longint;
   left:pbst;
   right:pbst;
```

(pseudocode)

```
function build(array):pbst;
begin
      if empty(array) then build:=nil; else begin
            med:=median(array);
            small:=smaller(med,array);
            large:=larger(med,array);
            new(root):
            root \`.hod:=med;
            root^.left:=build(small):
            root^.right:=build(large);
            build:=root:
      end;
end:
```

# Further operations on balanced BST

member, insert, delete

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Operation member is simple:

- end;
- Beware of the algorithm's side-effect using trichotomy (i.e., the third branch ensures that where `.val < what)</p>
- Function insert and delete are almost unimplementable (it would be necessary to destruct the whole tree).



far from being balanced!

```
procedure insert(what, where);
begin {Marginal cases!}
      while((( what<where .val) and
(where \cdot.left <> nil)) or
             ((what>where .val) and
(where .right <> nil)))
            if(what<where^.val) then
where:=where^.left.
            else where:=where^.right;
      if(what=where^.val) then error("Already
there!");
      if(what<where, val) then
      begin new(where^.left);
            kam:=where^.left:
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- What's wrong?
- In a short time the tree looks like a linear list.

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- We violate the property of a BST for a while!
- Now, the deleted vertex (on the incorrect location) has an out-degree at most  $1 \Rightarrow$
- delete it (bypass).
- Instead of the left-most element in the right subtree we may use the right-most element in the left subtree (as it has the closest value to the erased element). Thus both keep the pivoting properties of the erased element.



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- after insert and delete we perform the balance-renewing operations.
- For each vertex we define a value balance saying depth\_right depth\_left, permitted values are -1, 0 and 1.

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- We start solving on the bottom-most level with this balance.

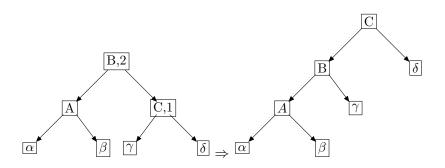
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- We start solving on the bottom-most level with this balance.
- We explore two possibilities, the remaining 2 are symmetric.
- The tree may be falling "to the side" or "to the interior".
- In the former case we use a rotation, in the latter a double-rotation.

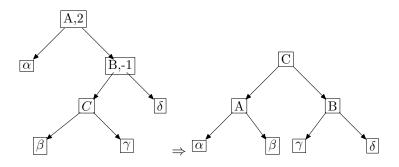
## Rotation

Tree is falling "to the side".



## Double-rotation

Tree is falling "to the interior".



rotation, double-rotation, depths

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## FIXME!!!

A-B-trees, k-ary tree canonical representation.

Passing a function as an argument.

A queue and a buffer,

graph-searching algorithms (including graph representation).

Odstrasujici priklady (slidy10.tex for mathematicians).