

SSSP 

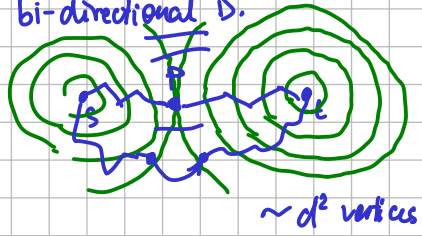
P+P SP

modified Dijkstra's

- stop when closing t



- bi-directional D.



- A* algorithm heuristic function $\psi: V \rightarrow \mathbb{R}$
lower bound on d. to target
 $\psi(v) \leq d(v, t)$

e.g. $\psi(v) := \xi_{\text{Euclid}}(v, t)$

close vertex (with min $h(v) + \psi(v)$)
want: $l(uv) - \psi(u) + \psi(v) \geq 0$
 $l(uv) - d(u, t) + d(v, t) \geq 0$
 $\geq d(uv)$ Δ ineq. \checkmark

Analysis of A*

A* with heuristics ψ

\Leftrightarrow D. on graph reduced by potential $-\psi$

recall: potential $\psi: V \rightarrow \mathbb{R}$
 $l_{\psi}(uv) := l(uv) + \psi(u) - \psi(v)$
want: $l_{\psi}(e) \geq 0$

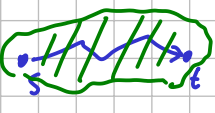
Theorem: If we run A* on G from s and D. on $G - \psi$ from s, then in every step we have:
 $h(v) = h^*(v) - \psi(s) + \psi(v)$.

assuming files are broken in the same way

Proof: A* minimizes $h^*(v) + \psi(v)$ } \rightarrow same v
D. min. $h(v)$

at the beginning: $h^*(s) = 0, h^*(t) = \infty$
 $0 = h(s) = 0 - \psi(s) + \psi(s) = 0$
 $h(t) = \infty$

In every step:
• both algs choose the same v



A*: set $h^*(v)$ to $h^*(u) + l(uv)$

D: set $h(v)$ to $h(u) + l(uv)$

$h^*(u) - \psi(s) + \psi(u) + l(uv) - \psi(u) + \psi(v)$
 $\rightarrow h^*(v) - \psi(s) + \psi(v)$
new

All-Pairs Shortest Paths

- given L (matrix of edge lengths) compute D (matrix of distances)

A*SP



- given A (adjacency matrix) compute R = A* (reachability matrix)

transitive closure (divided)

$A_{ij}^* = \begin{cases} 0 \\ 1 \end{cases}$ iff \exists path $i \rightarrow j$

Floyd-Warshall alg.

Def: $D_{ij}^k :=$ min. length of a ij -walk with internal vertices in $\{1 \dots k\}$



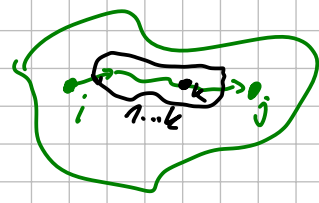
$D_{ij}^0 = l(ij)$ $D_{ii}^0 = 0 \dots D^0 = L$ (with 0 at diagonal)

$D_{ij}^n = D$

induction on k: $D^{k-1} \rightarrow D^k$ $O(n^2)$

$D_{ij}^k = \min \begin{cases} D_{ij}^{k-1} \\ D_{ik}^{k-1} + D_{kj}^{k-1} \end{cases}$

$O(1)$ time



$D^0 \rightarrow D^1 \rightarrow D^2 \rightarrow \dots \rightarrow D^n$ $O(n^3)$

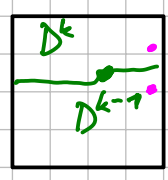
Repeated SSSP

A*: $n \times$ BFS $O(nm)$
D: $n \times$ Dijkstra $O(n(m + n \log n)) = O(nm + n^2 \log n)$

Best for sparse graphs
For dense ($m \sim n^2$): $O(n^3)$

reduce memory to $O(n^2)$

$D_{ij} \leftarrow \min(D_{ij}, D_{ik} + D_{kj})$



$D_{ik}^k = D_{ik}^{k-1}$
 $D_{kj}^k = D_{kj}^{k-1}$

do everything in-place

for $k=1$ to n
for $i=1$ to n
for $j=1$ to n
 $D_{ij} \leftarrow \min(D_{ij}, D_{ik} + D_{kj})$

Walk Algebra

Df: uv-bundle := set of uv-walks

\emptyset empty bundle

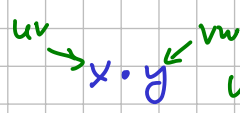
$E_{uv} \{uv\}$ for $uv \in E$, uv-bundle

E_u single-vertex walk, uv-bundle

elementary walks

$x \cup y$ uv-bundle, uv-bundle \rightarrow uv-bundle

set union



uv-bundle set of all concatenations of walk from x with walk from y

$u \rightarrow x^*$ uv-bundle

$x^* := E_u \cup x \cup x \cdot x \cup \underbrace{x \cdot x \cdot x}_{x^3} \cup \dots$

iteration

Similar to regular expression

$$f(x) := \min_{p \in x} l(p)$$

↑
uv-bundle

Distances

$$f(\emptyset) = +\infty$$

$$f(e_{uv}) = l(uv)$$

$$f(E_u) = 0$$

$$f(x \cup y) = \min(f(x), f(y))$$

$$f(x \cdot y) = f(x) + f(y)$$

$$f(x^*) = \begin{cases} 0 & \text{if } f(x) \geq 0 \\ -\infty & \text{if } f(x) < 0 \end{cases}$$

Widest path

$$f(\text{path}) := \min_{e \in \text{path}} \text{width}(e)$$

$$f(\text{bundle}) := \max_{\text{walk} \in \text{bundle}} f(\text{walk})$$

$$f(\emptyset) = -\infty$$

$$f(e_{uv}) = \text{width}(uv)$$

$$f(E_u) = +\infty$$

$$f(x \cup y) = \max(f(x), f(y))$$

$$f(x \cdot y) = \min(f(x), f(y))$$

$$f(x^*) = +\infty$$

$O(n^3)$ time

Generalized F-W

W_{ij}^k := bundle of all walks from i to j using 1-k

$W_{ij}^0 := E_{ij}$ for $i \neq j$ if $ij \in E$

$W_{ij}^0 := E_i \cup E_{ij}$ if exists otherwise $W_{ij}^0 := \emptyset$

$W^n \dots$ output

Single step: $W^{k-1} \rightarrow W^k$

$$W_{ij}^k = W_{ij}^{k-1} \cup W_{ik}^{k-1} \cdot (W_{kk}^{k-1})^* \cdot W_{kj}^{k-1}$$

Representation: walk expressions (exponentially large)

expression DAG

of size $O(n^3)$

$(\emptyset, e_{uv}, E_u, \cup, \cdot, *)$

hom.

$(f(\emptyset), f(e_{uv}), f(E_u), \oplus, \ominus, \odot)$

