

Review: our goal! For a given lin. trans. $f: V \rightarrow V$

- to find a basis B s.t. ${}_B[f]_B$ is simple (\sim diagonal)
- to find directions unaffected by f


Def: Square matrices A and A' are similar if \exists an invertible R s.t. $A' = R \cdot A \cdot R^{-1}$

Def: $A \in T^{n \times n}$ is diagonalizable if similar to diagonal mat.

Def: For $A \in T^{n \times n}$ $\lambda \in T$ is an eigenvalue of A if $\exists v \in T^n, v \neq 0$ s.t. $Av = \lambda v$.

An eigenvector corresp. to λ is every $v \in V, v \neq 0$, s.t. $Av = \lambda v$.

Similarly for lin. trans. $f: V \rightarrow V$.

 For an eigenvalue λ of LT f (or of a matrix A), the set $U = \{u : f(u) = \lambda \cdot u\}$ is a vector subspace.
set of all eigenvectors corresponding to λ and 0 !

Proof: We have to check that U is closed under $+$, \cdot .

For any $u, v \in U, t \in T$, it holds:

$$f(t \cdot u) = t \cdot f(u) = t \cdot \lambda \cdot u = \lambda \cdot (t \cdot u), \text{ i.e., } t \cdot u \in U$$

$$f(u+v) = f(u) + f(v) = \lambda \cdot u + \lambda \cdot v = \lambda(u+v), \text{ i.e., } u+v \in U$$

Theorem A (Characterization of eigenvalues & determinants)

For $A \in T^{n \times n}$, λ is an eigenvalue of $A \Leftrightarrow \det(A - \lambda I) = 0$.

Proof: λ is eigenvalue $\Leftrightarrow \exists v \neq 0$ s.t. $Av = \lambda v = \lambda I v$

$$\Leftrightarrow \exists v \neq 0 (A - \lambda I)v = 0 \Leftrightarrow A - \lambda I \text{ is singular}$$

$$\Leftrightarrow \det(A - \lambda I) = 0 \quad \square$$

Def: Characteristic polynomial of the matrix $A \in T^{n \times n}$

is the polynomial $p_A(t) = \det(A - t \cdot I)$ where $I = \begin{pmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{pmatrix}$.

 Roots of $p_A(t)$ are the eigenvalues of A .
by THM LA2 7/1

Ex. $A = \begin{pmatrix} 1 & 2 \\ 3 & 2 \end{pmatrix}$, $P_A(t) = \det \begin{pmatrix} 1-t & 2 \\ 3 & 2-t \end{pmatrix} = (1-t)(2-t) - 2 \cdot 3 = t^2 - 3t - 4 = (t-4)(t+1)$

Theorem: Let $f: V \rightarrow V$ be a linear transformation. There exists a basis B of V s.t. ${}_B[f]_B$ is diagonal \iff there exists a basis of V consisting of eigenvectors of f .

Proof: \Rightarrow Let $B = (b_1, \dots, b_n)$ be a basis s.t. ${}_B[f]_B$ diagonal,

i.e.,
$$\left(\begin{matrix} \downarrow_B \\ [f(b_1)]_B \\ \downarrow_B \end{matrix} \quad \dots \quad \begin{matrix} \downarrow_B \\ [f(b_n)]_B \\ \downarrow_B \end{matrix} \right) = \begin{pmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{pmatrix}$$
 for some $\lambda_1, \dots, \lambda_n$,

thus, $\forall i, f(b_i) = \lambda_i \cdot b_i$ - B consists of eigenvectors. \square

\Leftarrow Let $B = (b_1, \dots, b_n)$ be a basis s.t. each b_i is an eigenvector,

i.e., $\forall i \exists \lambda_i$ s.t. $f(b_i) = \lambda_i \cdot b_i$.

thus,
$${}_B[f]_B = \begin{pmatrix} \begin{matrix} \text{---} \\ [f(b_1)]_B \\ \text{---} \end{matrix} & \dots & \begin{matrix} \text{---} \\ [f(b_n)]_B \\ \text{---} \end{matrix} \end{pmatrix} = \begin{pmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{pmatrix} \quad \square$$

Theorem (for matrices): $A \in T^{n \times n}$ is diagonalizable \iff

there exists a basis B of T^n consisting of eigenvectors of A .

Proof: $\Rightarrow \exists$ diagonal D and invertible R s.t.

HW? $D = R^{-1} \cdot A \cdot R \quad \Rightarrow \quad R \cdot D = A \cdot R$

Let b_i denote the i th column of R . Then $D_{ii} \cdot b_i = A \cdot b_i$,

i.e., each b_i is an eigenvector of A , and

$\{b_1, \dots, b_n\}$ is a basis of T^n .

\Leftarrow Let $R = \begin{pmatrix} b_1 & \dots & b_n \\ \vdots & & \vdots \end{pmatrix}$. Then $A \cdot R = R \cdot D$ where

D is a diagonal $n \times n$ and D_{ii} is the eigenvalue to b_i .

As R is invertible, R^{-1} exists and $A = R \cdot D \cdot R^{-1}$ \square

Note: A is diagonalizable - the matrix ${}_B[f]_B$ of $f(x) = Ax$ is diagonal for some basis B . LA 2 7/2

Theorem: If $\lambda_1, \dots, \lambda_n$ are pairwise distinct eigenvalues of a lin. transformation f (matrix A) and v_1, \dots, v_n eigenvectors corresponding to $\lambda_1, \dots, \lambda_n$, then v_1, \dots, v_n are lin. independent.

Proof: by induction on n : $n=1$ - OK
 inductive step $n-1 \rightarrow n$: Consider lin. comb $\sum_{i=1}^n \alpha_i v_i = 0$ (*)

$$\begin{aligned} \text{Then } 0 &= f(0) = f\left(\sum_{i=1}^n \alpha_i v_i\right) = \sum_{i=1}^n \alpha_i f(v_i) = \sum_{i=1}^n \alpha_i \lambda_i v_i = \\ &= \sum_{i=1}^n \alpha_i \lambda_i v_i - \underbrace{\lambda_n \left(\sum_{i=1}^n \alpha_i v_i\right)}_{=0} = \sum_{i=1}^{n-1} \alpha_i \underbrace{(\lambda_i - \lambda_n)}_{\neq 0} v_i \end{aligned}$$

by ind. assump., v_1, \dots, v_{n-1} are LI $\Rightarrow \alpha_i = 0 \quad i=1, \dots, n-1$

By (*), $\alpha_n = 0$ as well, i.e., v_1, \dots, v_n are LI. \square

Corollary 1: An $n \times n$ square matrix has at most n distinct eigenvalues.

Corollary 2: If an $n \times n$ matrix has n distinct eigenvalues, then it is diagonalizable. (the opposite implication does not hold ... I).
 (by the two previous THMs)

Theorem: If A and B are similar, then $p_A(t) = p_B(t)$.

Proof: by definition (simil.) $\exists R$ s.t. $B = R \cdot A \cdot R^{-1}$

$$\begin{aligned} p_B(t) &= \det(B - tI) = \det(R \cdot A \cdot R^{-1} - t \cdot R \cdot I \cdot R^{-1}) \\ &= \det(R \cdot (A - tI) \cdot R^{-1}) = \det(R) \det(A - tI) \det(R^{-1}) \\ &= \det(A - tI) = p_A(t). \quad \square \end{aligned}$$

Beware! The converse does not hold! E.g., for $A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$, $B = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$, $p_A(t) = p_B(t)$, but they are not similar: if they were, then $\exists R$ s.t. $A = \underbrace{R \cdot B \cdot R^{-1}}_{=I} = I$ - contradiction

Def: Characteristic polynomial of the lin. trans. $f: V \rightarrow V$ is the char. poly. of the matrix of f w.r.t. any basis.

Note: any two such matrices are similar, and by the previous

THM they all have the same char. polyn.

\Rightarrow definition makes sense!

IMPORTANT COEFFICIENTS OF CHAR. POLYN. OF A

Consider $p_A(t) = b_n \cdot t^n + b_{n-1} \cdot t^{n-1} + \dots + b_1 t + b_0 = \det(A - tI)$

• $b_n = (-1)^n \dots$ the t^n can be obtained only from the product $\prod_{i=1}^n (a_{ii} - t)$



• $b_{n-1} = (-1)^{n-1} \cdot \sum_{i=1}^n a_{ii}$... similarly, the t^{n-1} can be obtained only from the product $\prod_{i=1}^n (a_{ii} - t)$: pick $(-t)$ $(n-1)$ -times and a_{ii} once; by summing these n products we get b_{n-1}

• $b_0 = \det(A)$... use $t=0$ in $A - tI$, in $p_A(t)$
" $p_A(0)$

Theorem: A matrix A is singular $\Leftrightarrow 0$ is its eigenvalue.

Proof: we know: A is singul. $\Leftrightarrow \det(A) = 0 \Leftrightarrow$

$\Leftrightarrow \det(A - 0 \cdot I) = 0 \stackrel{\text{TH 17 A}}{\Leftrightarrow} 0$ is eigenvalue of A . \square

note: by coeff. b_0 of p_A we know whether A is invertible or not