

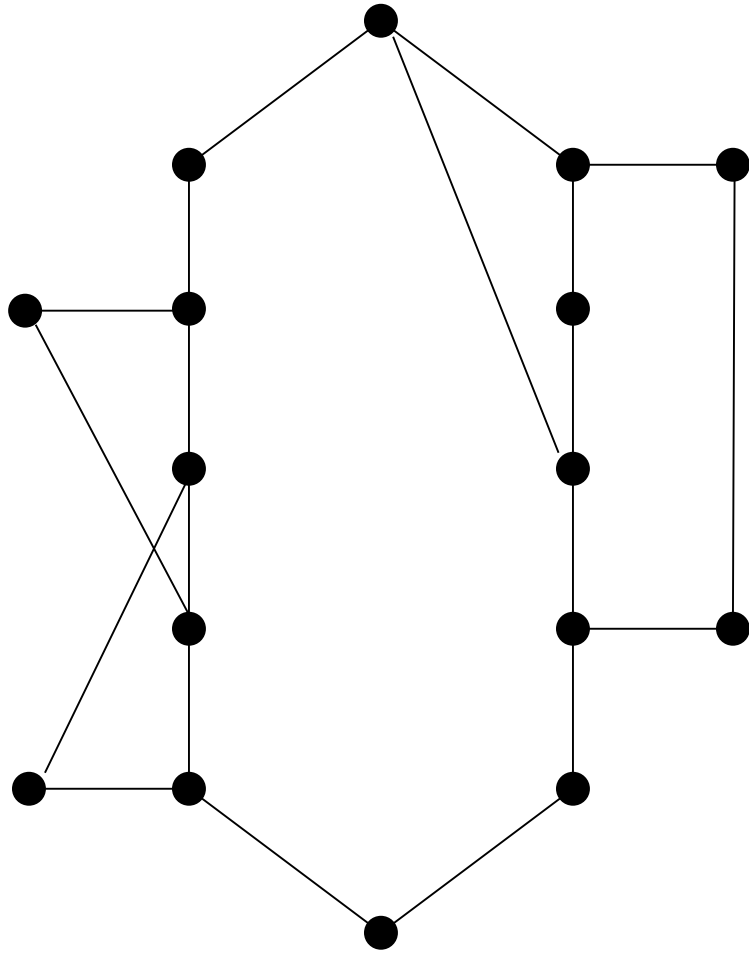
Hamiltonicity of Dense Graphs

Nikola Jedličková, Jan Kratochvíl,
Charles University, Prague, Czech Republic

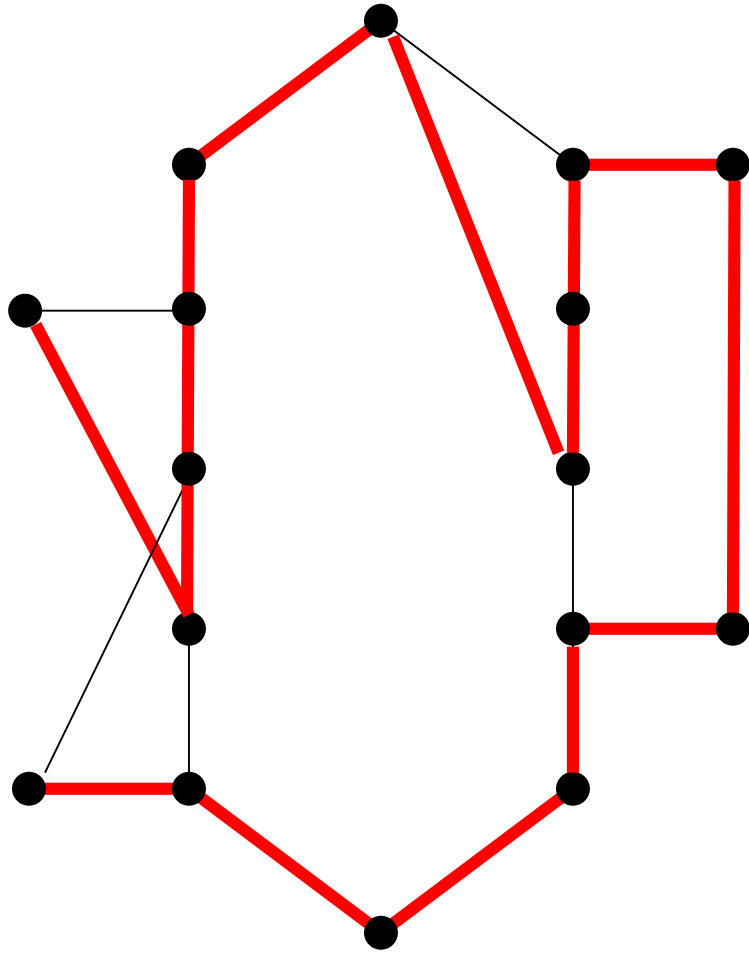


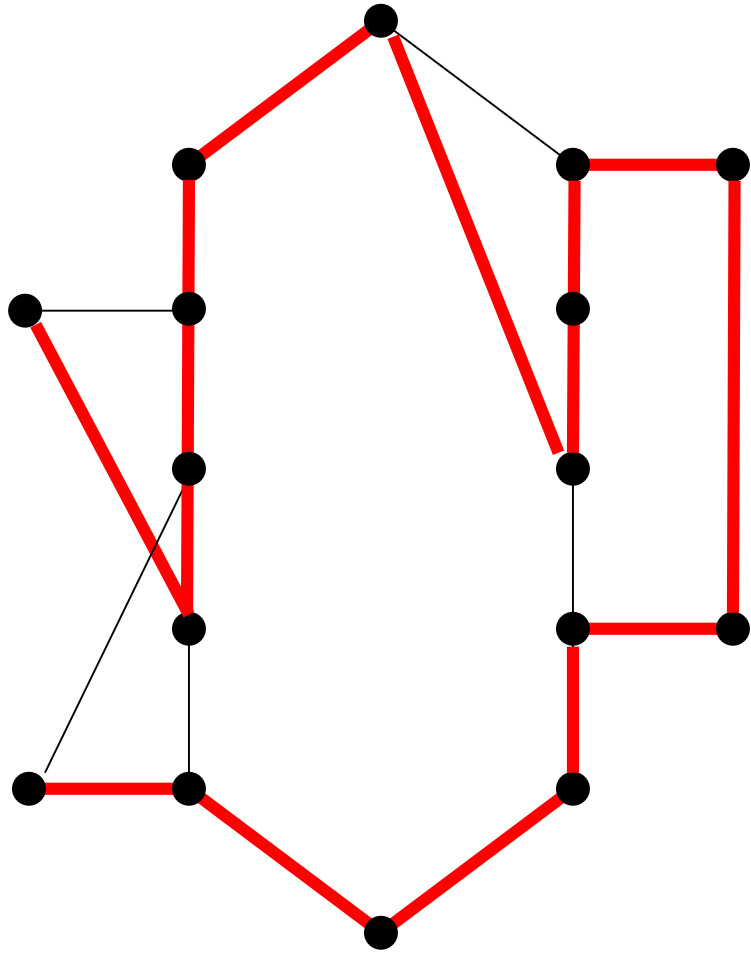
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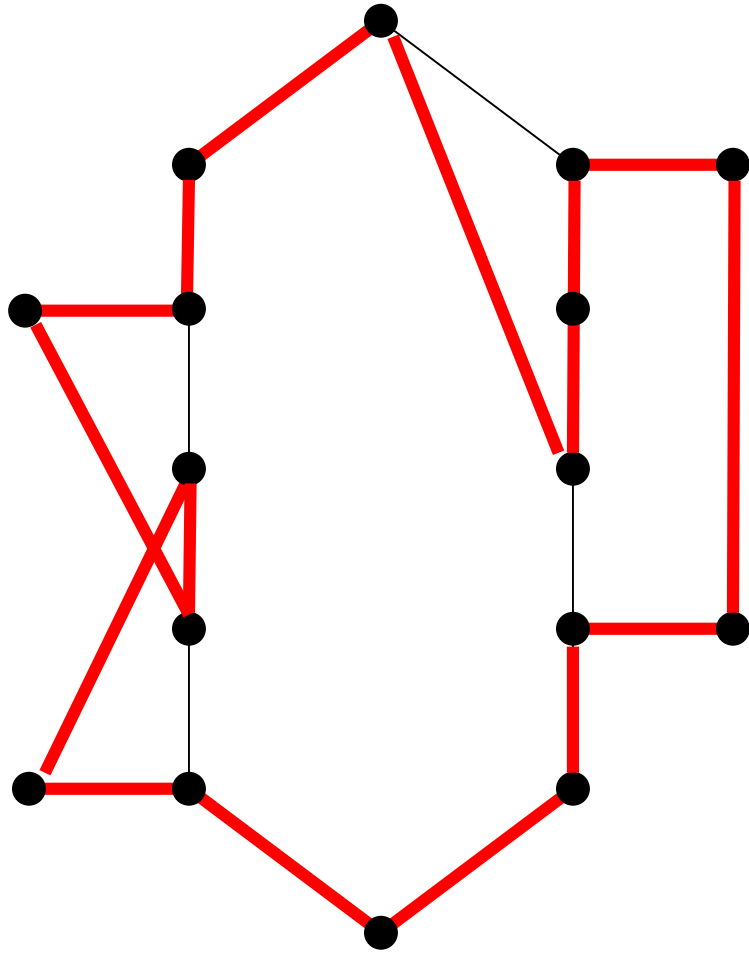
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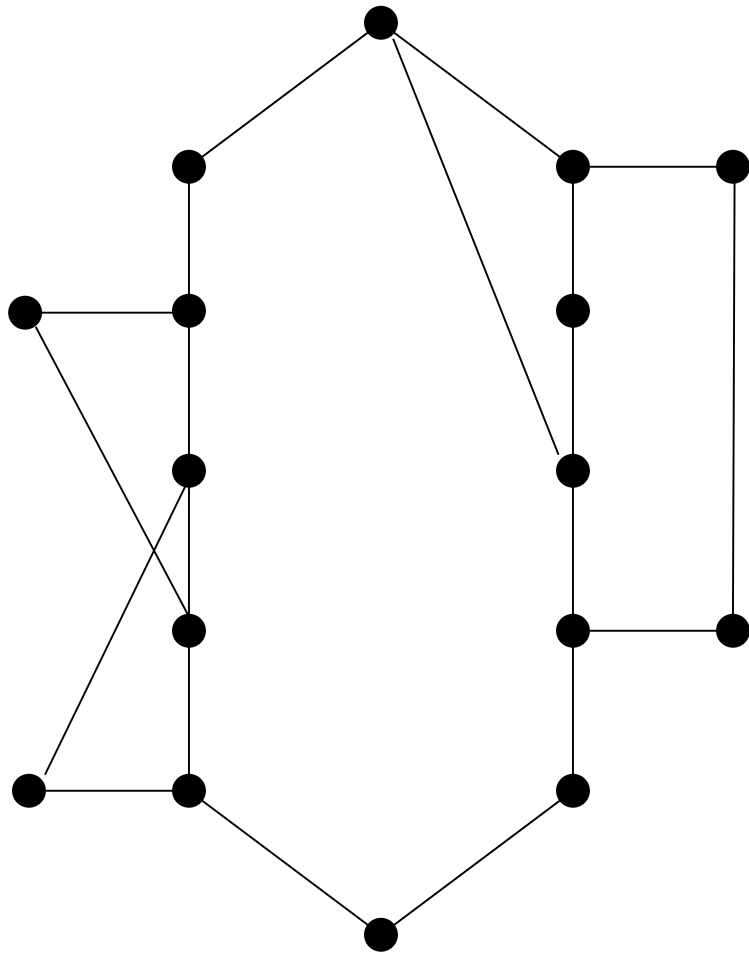
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Hamiltonian cycle – a cycle passing through every vertex exactly once = Hamiltonian path connecting two adjacent vertices



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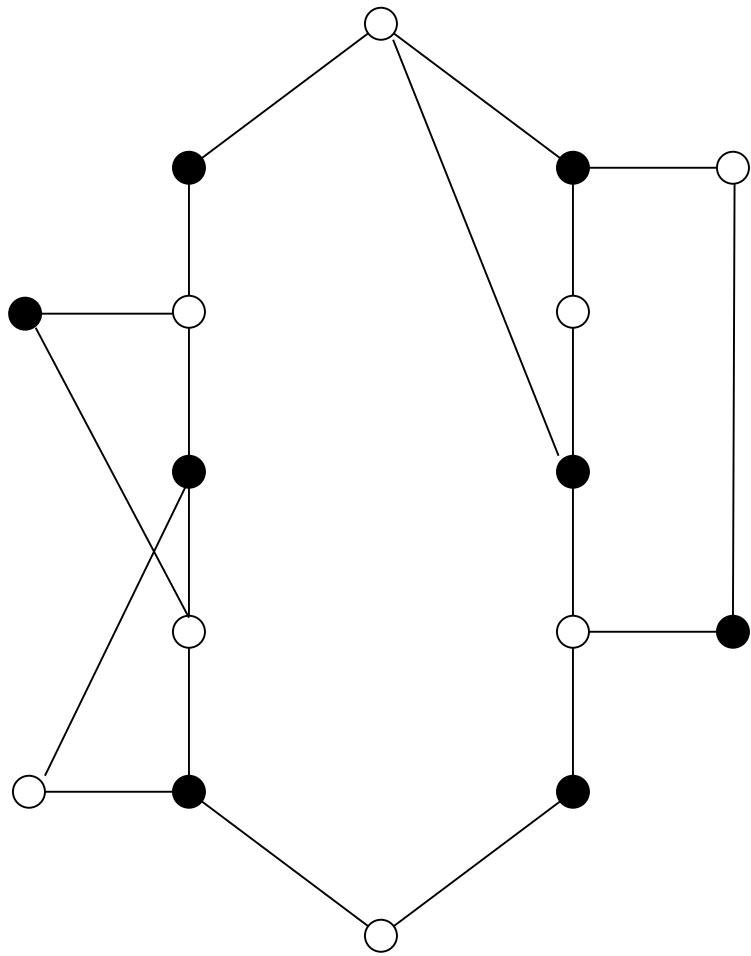
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The graph is **Hamilton connected** if every pair of vertices is connected by a Hamiltonian path



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The graph is **Hamilton connected** if every pair of vertices is connected by a Hamiltonian path

Theorem (Chvátal, Erdős 1972): Let G be a vertex- s -connected graph.
Then

- If $\alpha(G) < s+2$, then G has a Hamiltonian path
- If $\alpha(G) < s+1$, then G has a Hamiltonian cycle
- If $\alpha(G) < s$, then G is Hamilton connected.

Dense graphs = bounded $\alpha(G)$

Observation: $\alpha(G) < k$ iff G is kK_1 -free

-free = $3K_1$ -free = complement of a triangle-free graph

Our goal – complexity of HamPath and HamCycle for H -free graphs

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Our result [arXiv:2309.09228]: For every k , HamPath and HamCycle are polynomial time solvable on kK_1 -free graphs.

Path Cover and Hamiltonian Linkage

Def: The *path cover number* of a graph is the minimum number of paths that cover all vertices.

Observation: $pc(G)=1$ iff G has a Hamiltonian path

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Def: HamLinkage = PathCover with specified end-vertices of the paths

A graph is *Ham- ℓ -linkable* if it has a Ham linkage for every choice of 2ℓ end-vertices of the paths

Observation: G is Ham-1-linkable iff it is Hamiltonian connected

Theorem [[arXiv:2309.09228](#)]: For every k and ℓ , Ham- ℓ -Linkage and Ham- ℓ -Linkability are polynomial time solvable on kK_1 -free graphs.

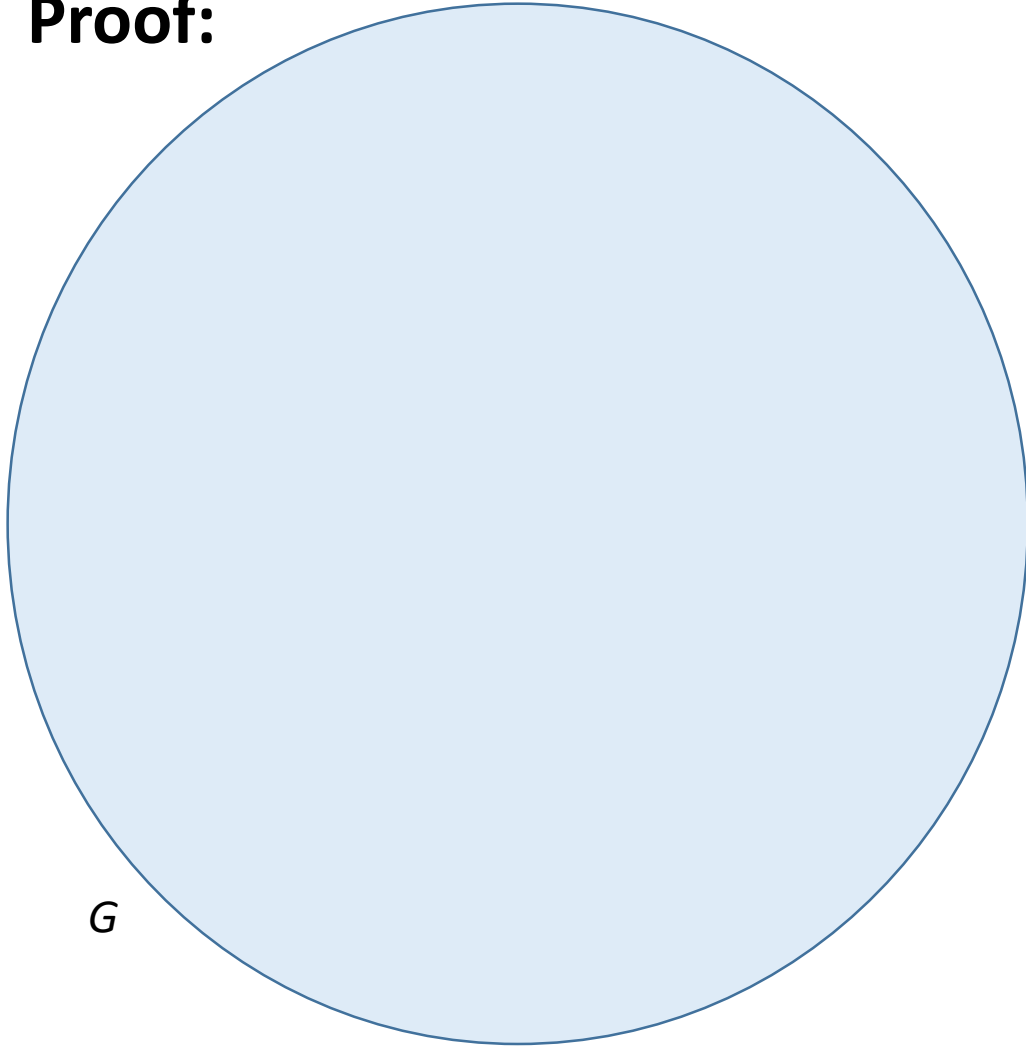
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i.e., Ham- ℓ -Linkage and Ham- ℓ -Linkability are in XP when parameterized by ℓ and $\alpha(G)$.

Theorem [[arXiv:2309.09228](#)]: For every k and ℓ , if a graph G satisfies $\alpha(G) < k$ and $c_v(G) \geq \max\{k\ell, 10\ell\}$, then G is Hamiltonian- ℓ -linkable.

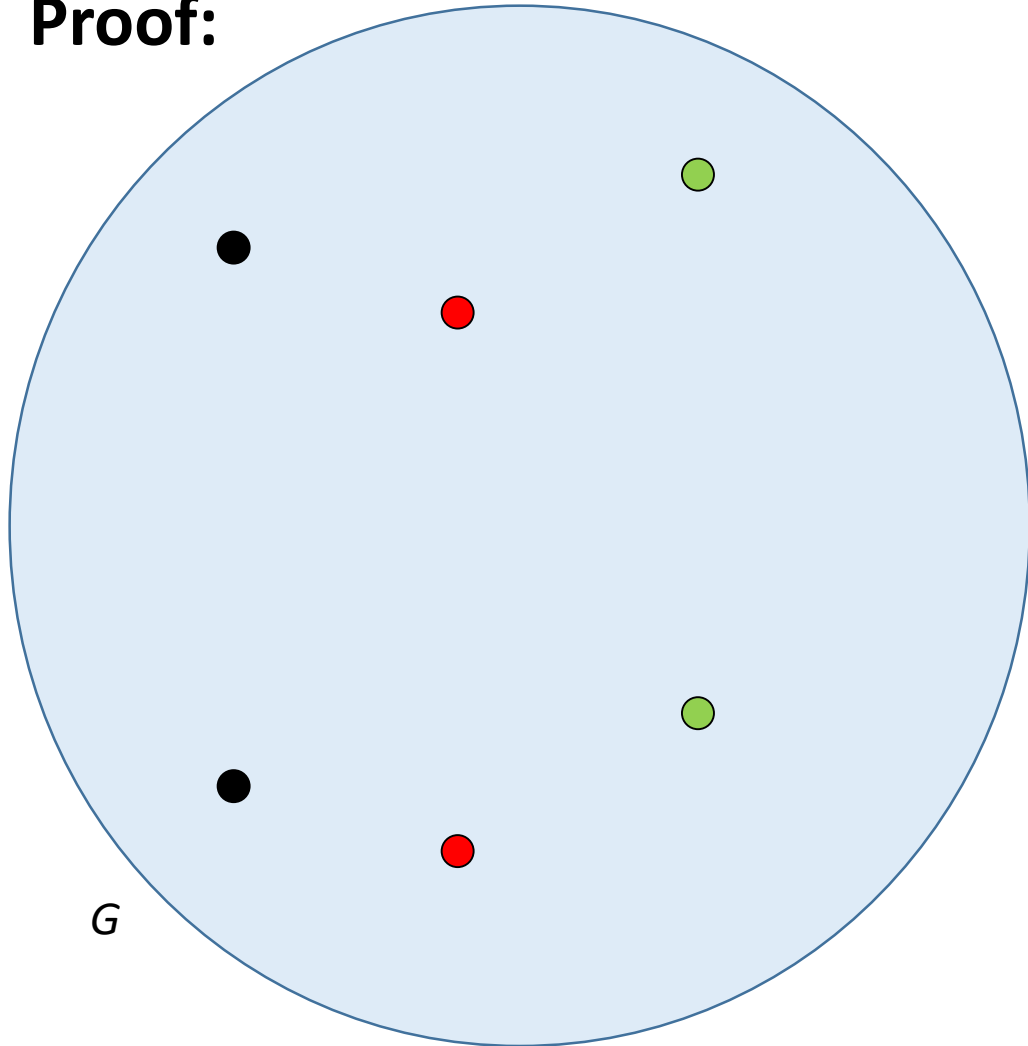
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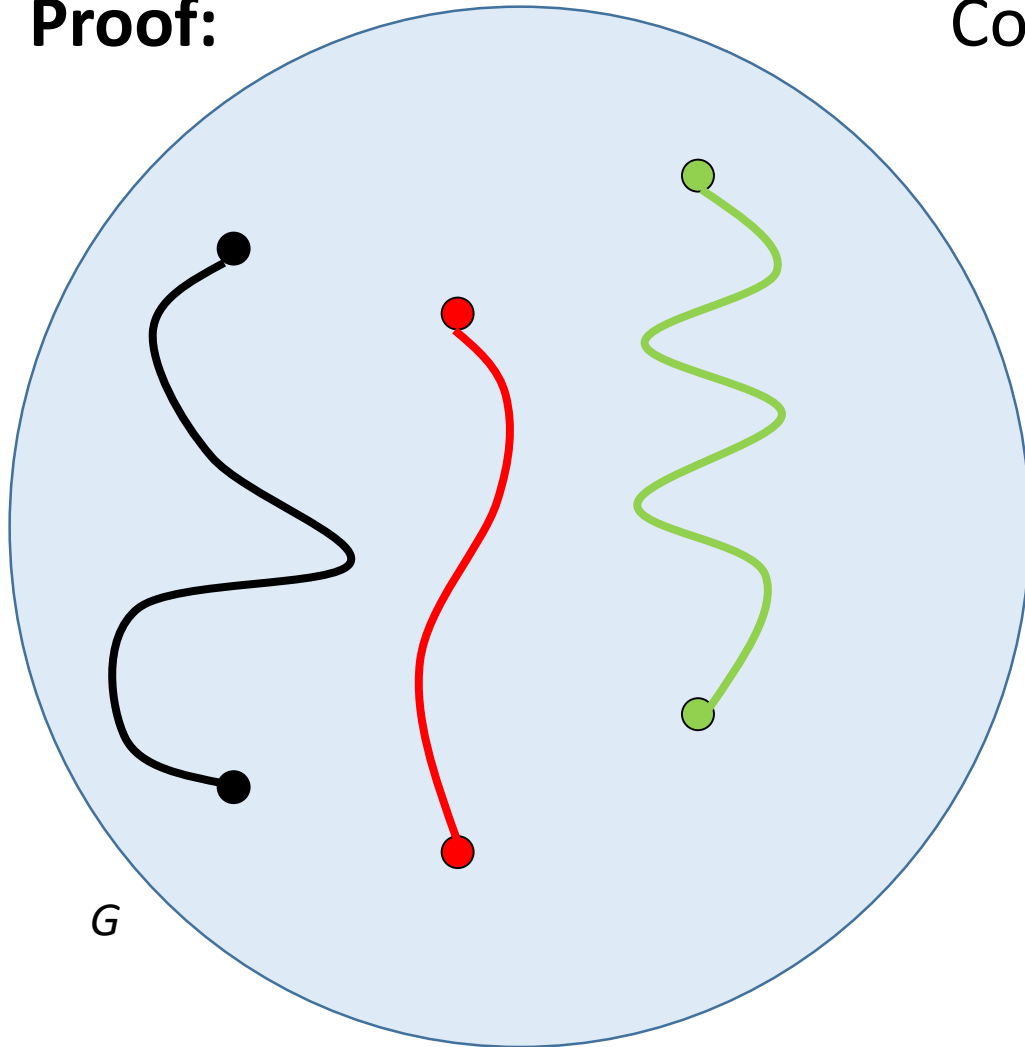
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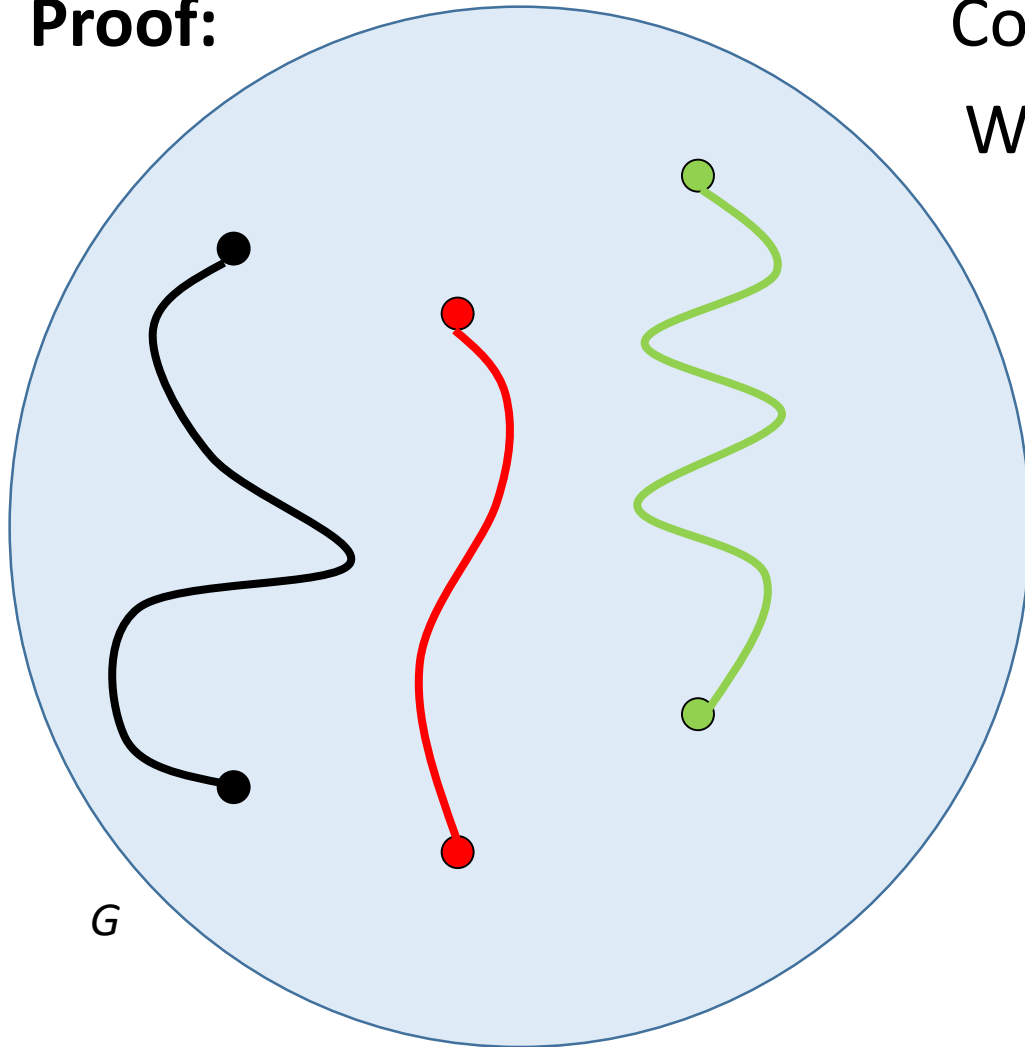
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We claim it is Hamiltonian



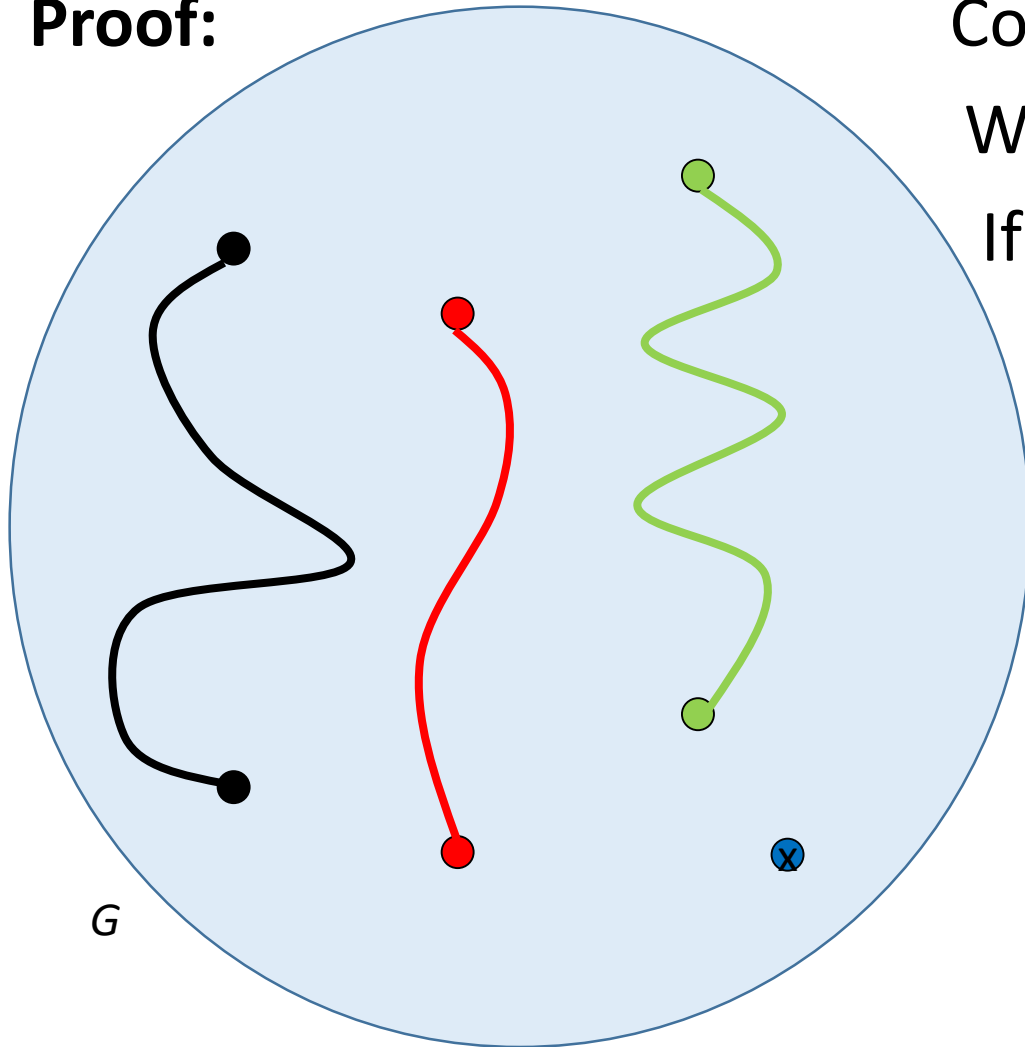
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If not, there is a vertex x that does not belong to the linkage.



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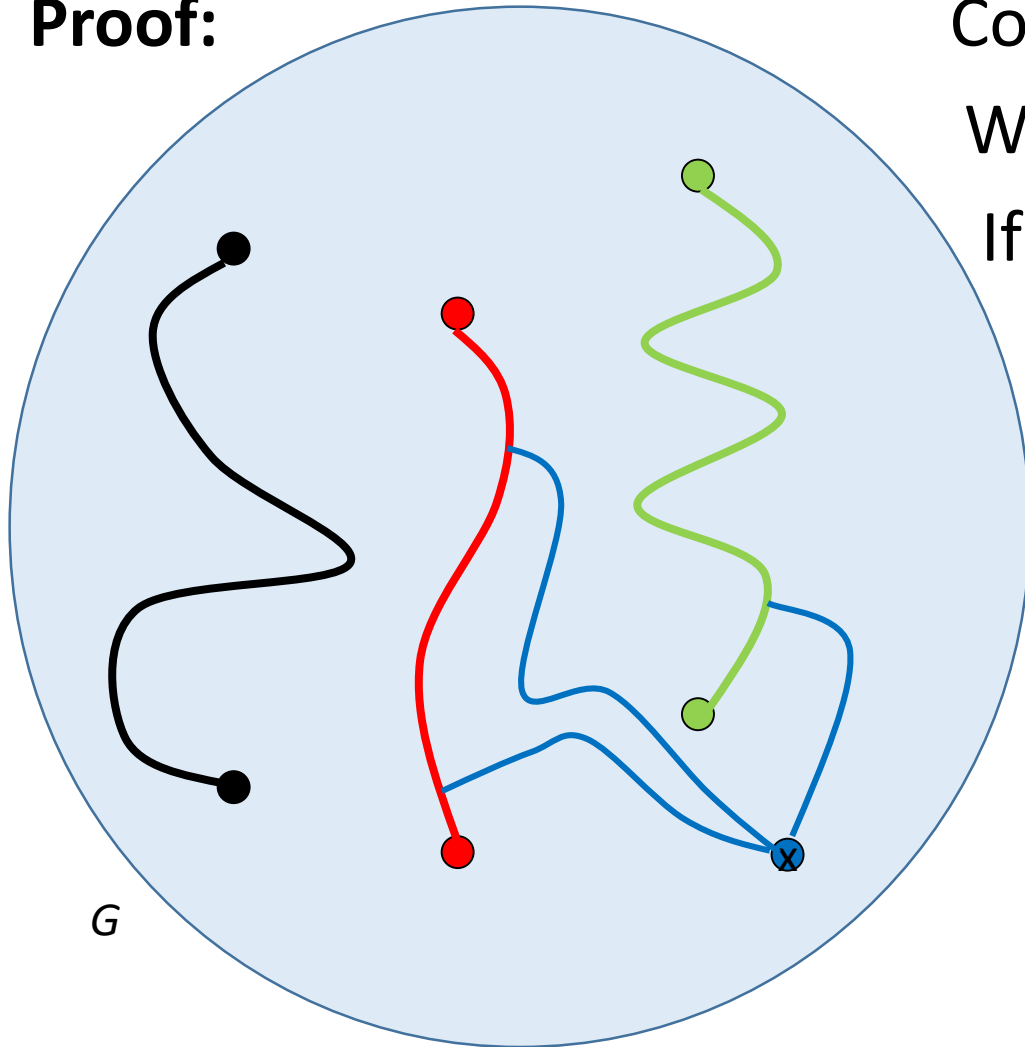
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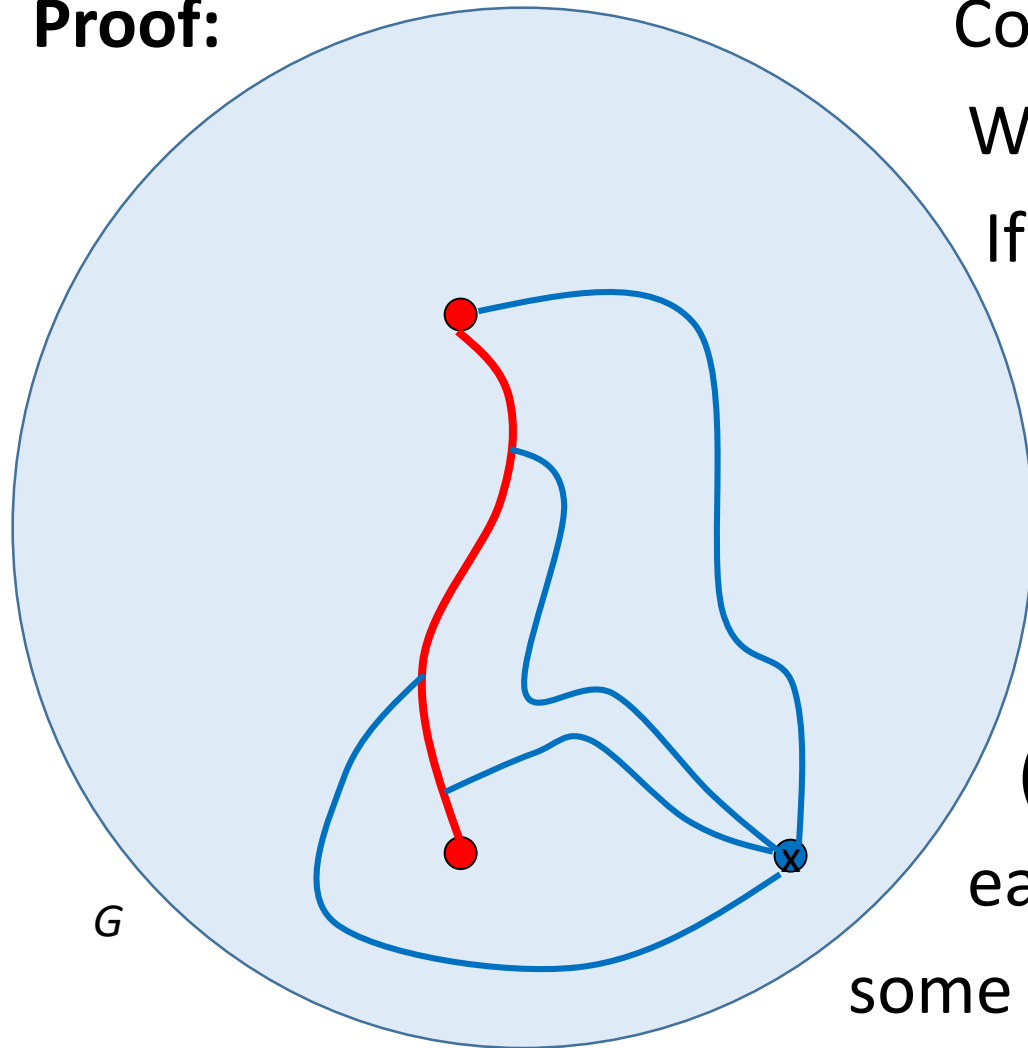
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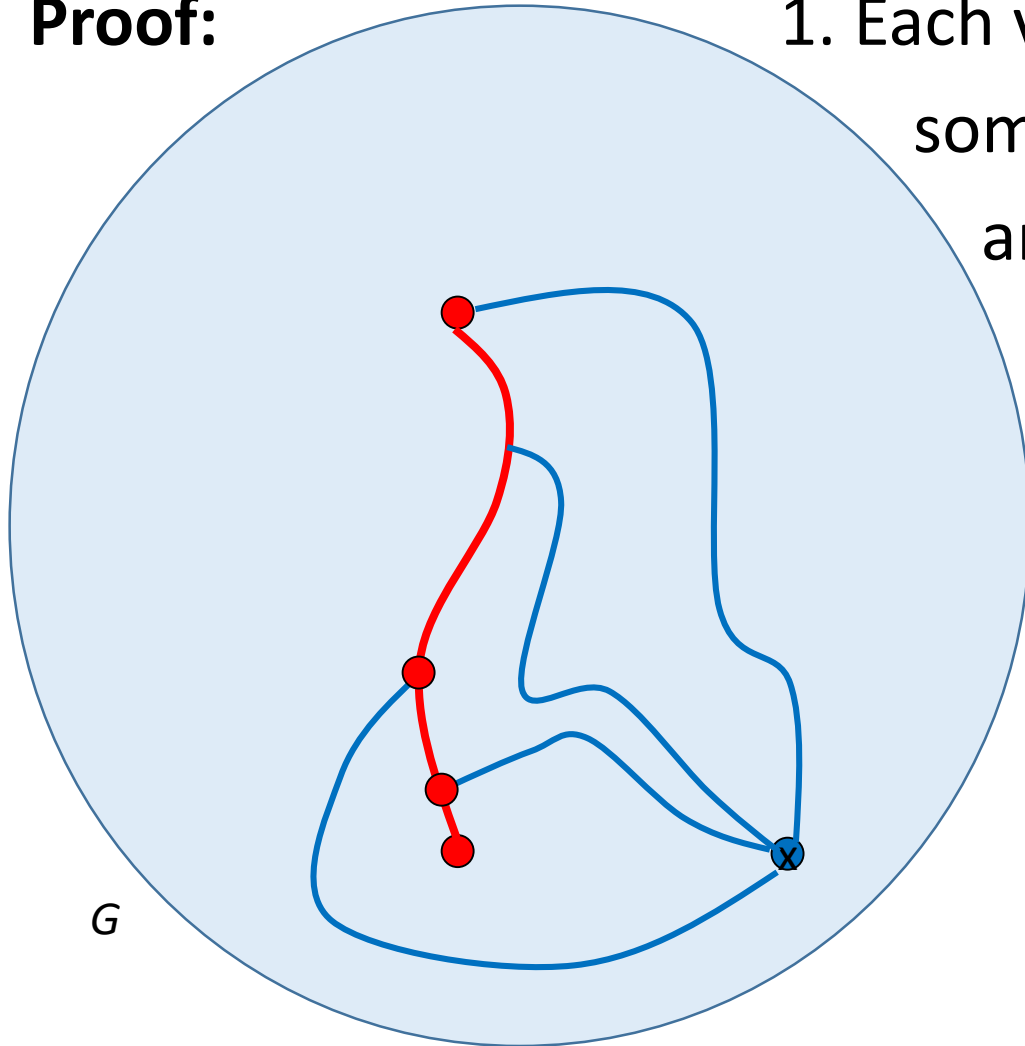
Since G is highly connected, there are many disjoint paths from x to the linkage. At least one link is saturated (at least k paths end on this link, or each vertex of this link is end-vertex of some path).



Theorem [arXiv:2309.09228]: For every k and ℓ , if a graph G satisfies $\alpha(G) < k$ and $c_v(G) \geq \max\{k\ell, 10\ell\}$, then G is Hamiltonian- ℓ -linkable.

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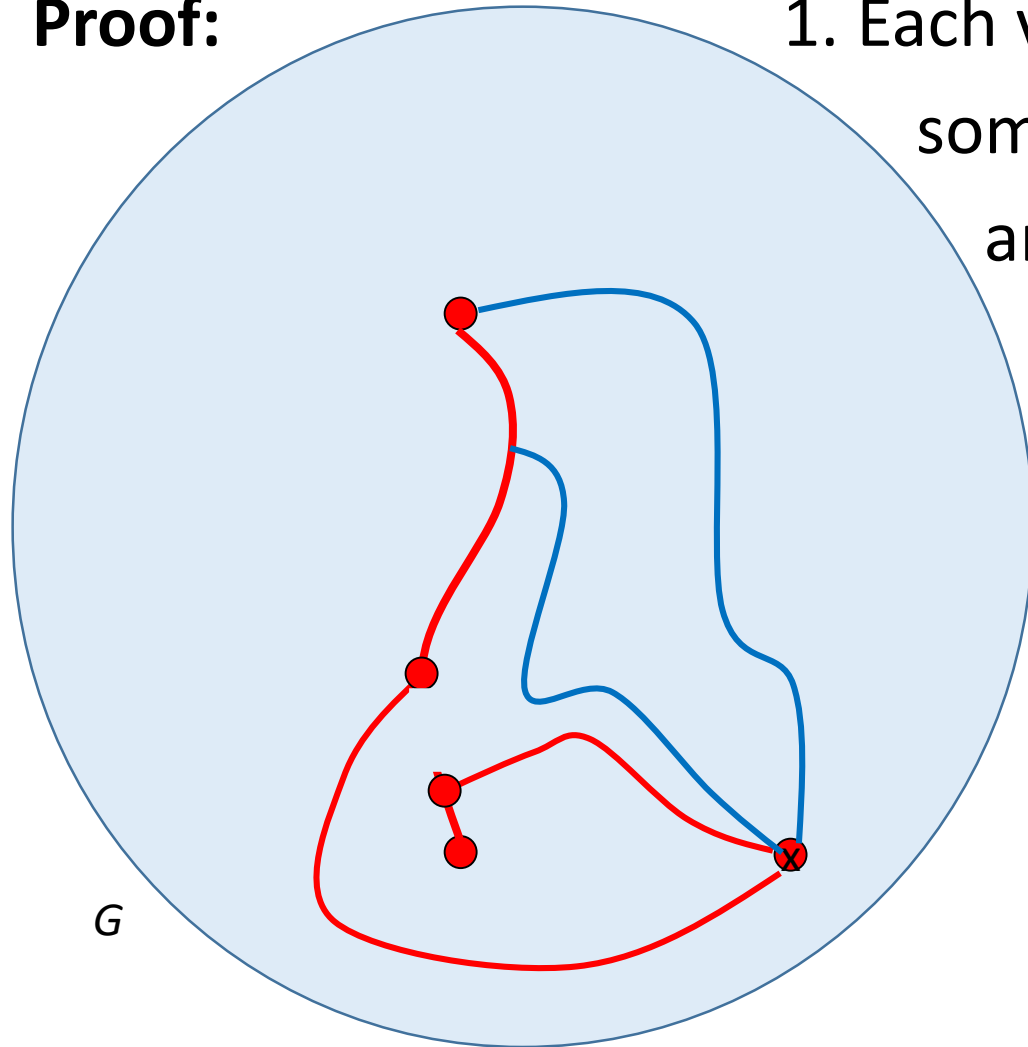
1. Each vertex of this link is end-vertex of some path, hence 2 consecutive vertices are end-vertices and the linkage can be extended. Contradicting its assumed maximality.



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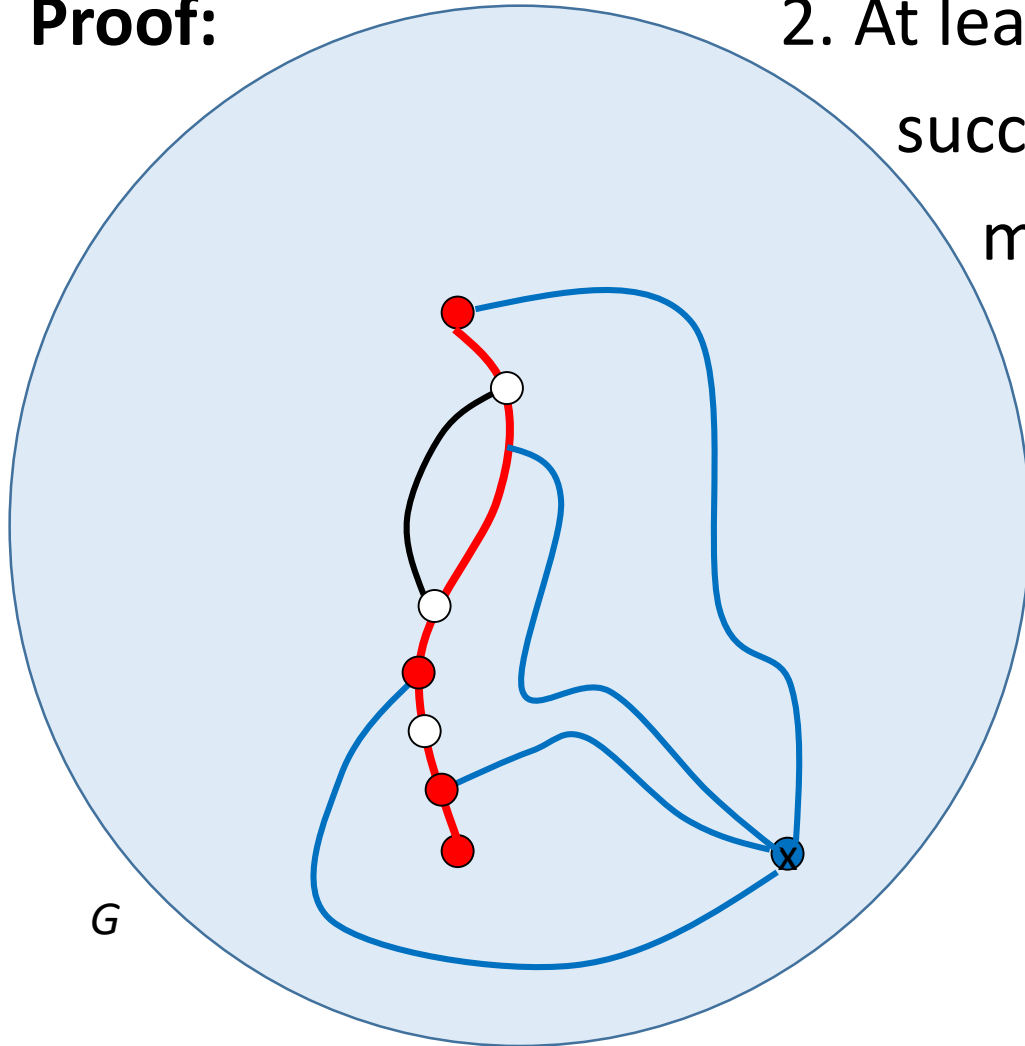
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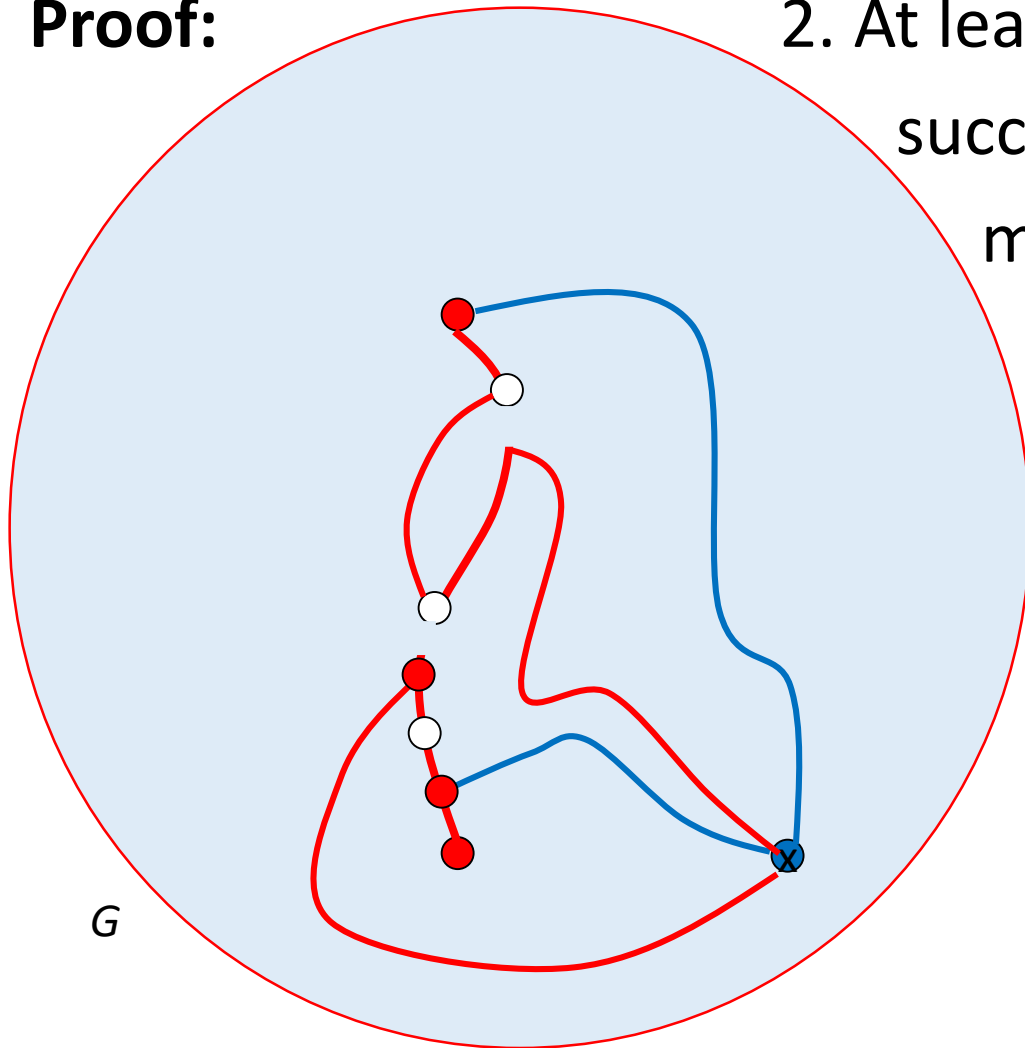
2. At least k paths end on this link. Consider successors of their end-points. Two of them must be adjacent (otherwise we have at least k independent vertices, contradicting $\alpha(G) < k$). Extend the link using this edge, contradicting the assumed maximality of the linkage.



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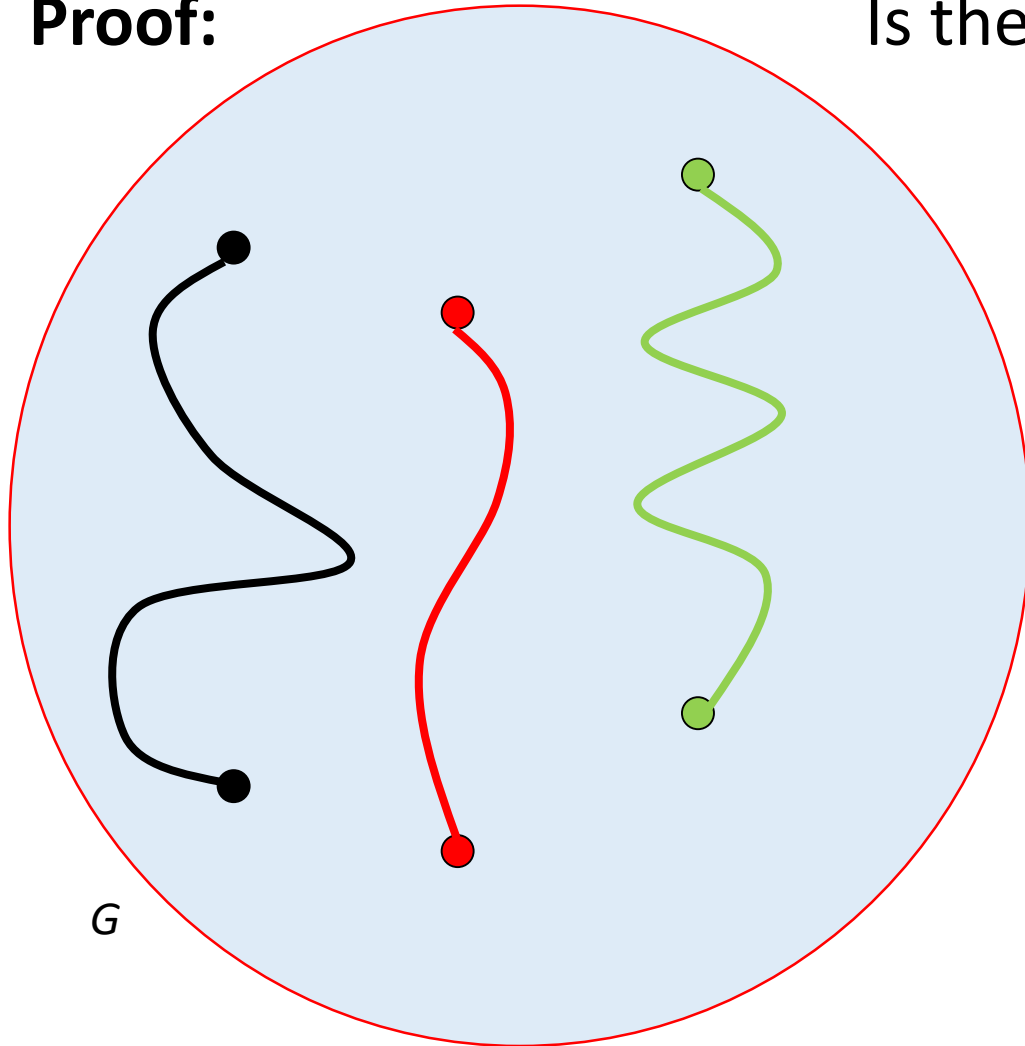


G

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Is there any linkage to start with?

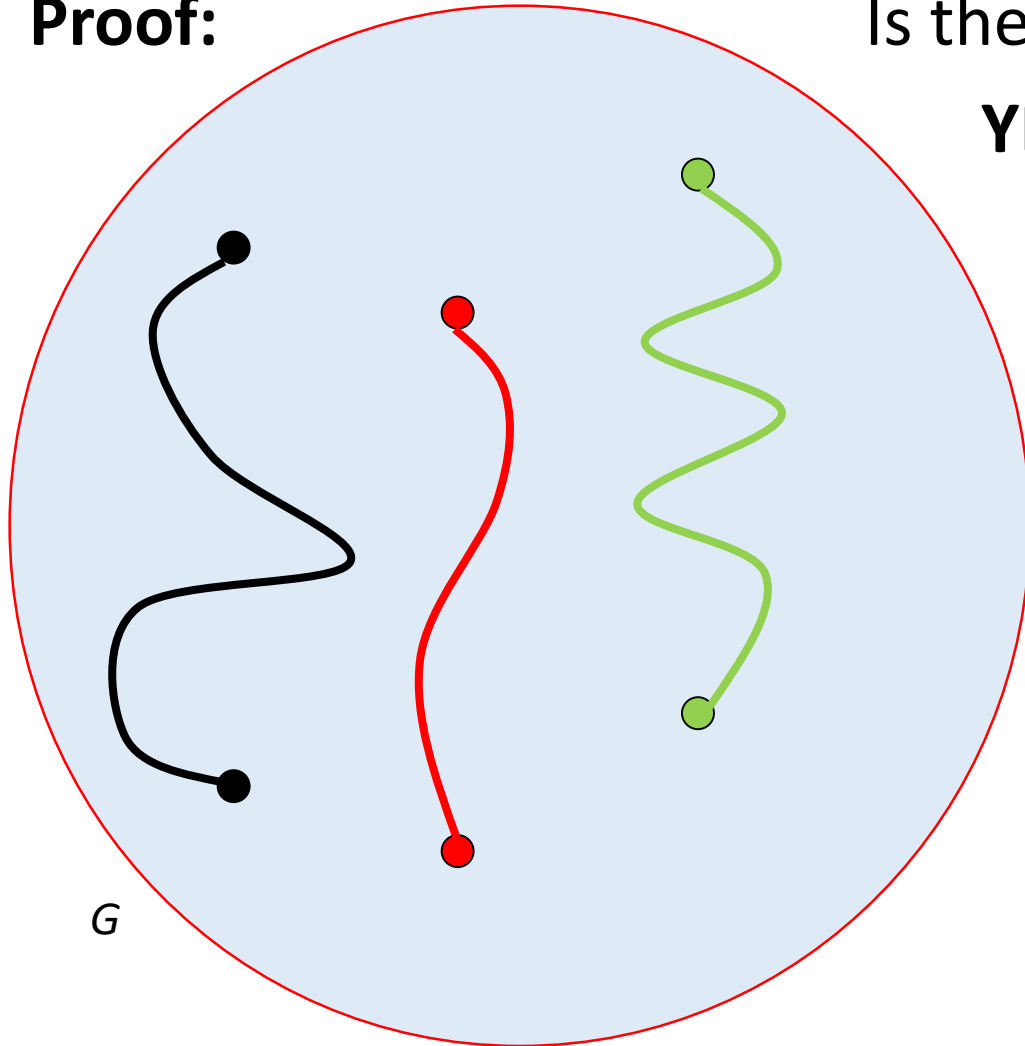


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YES Thomas, Wollan [EJC 2005]

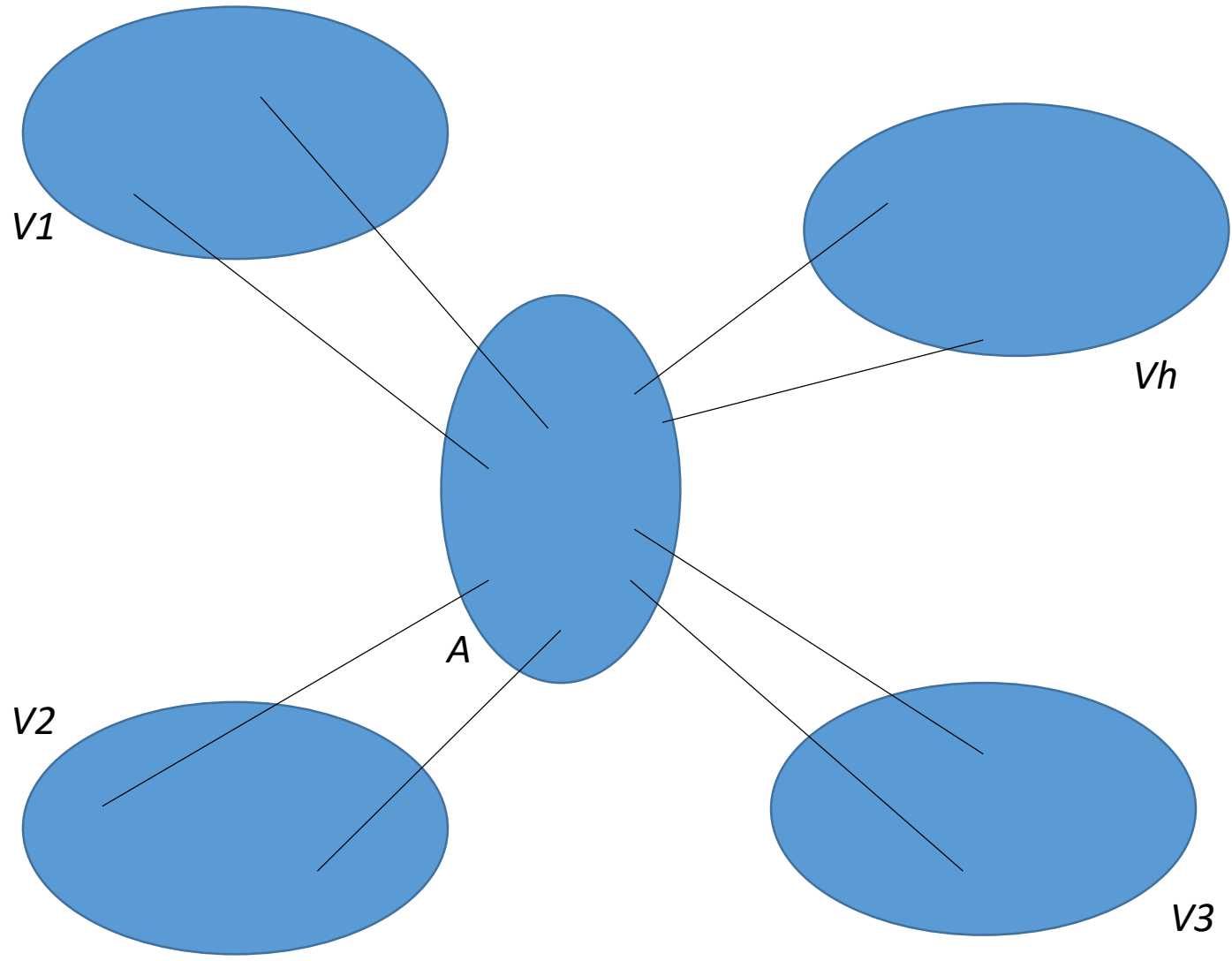


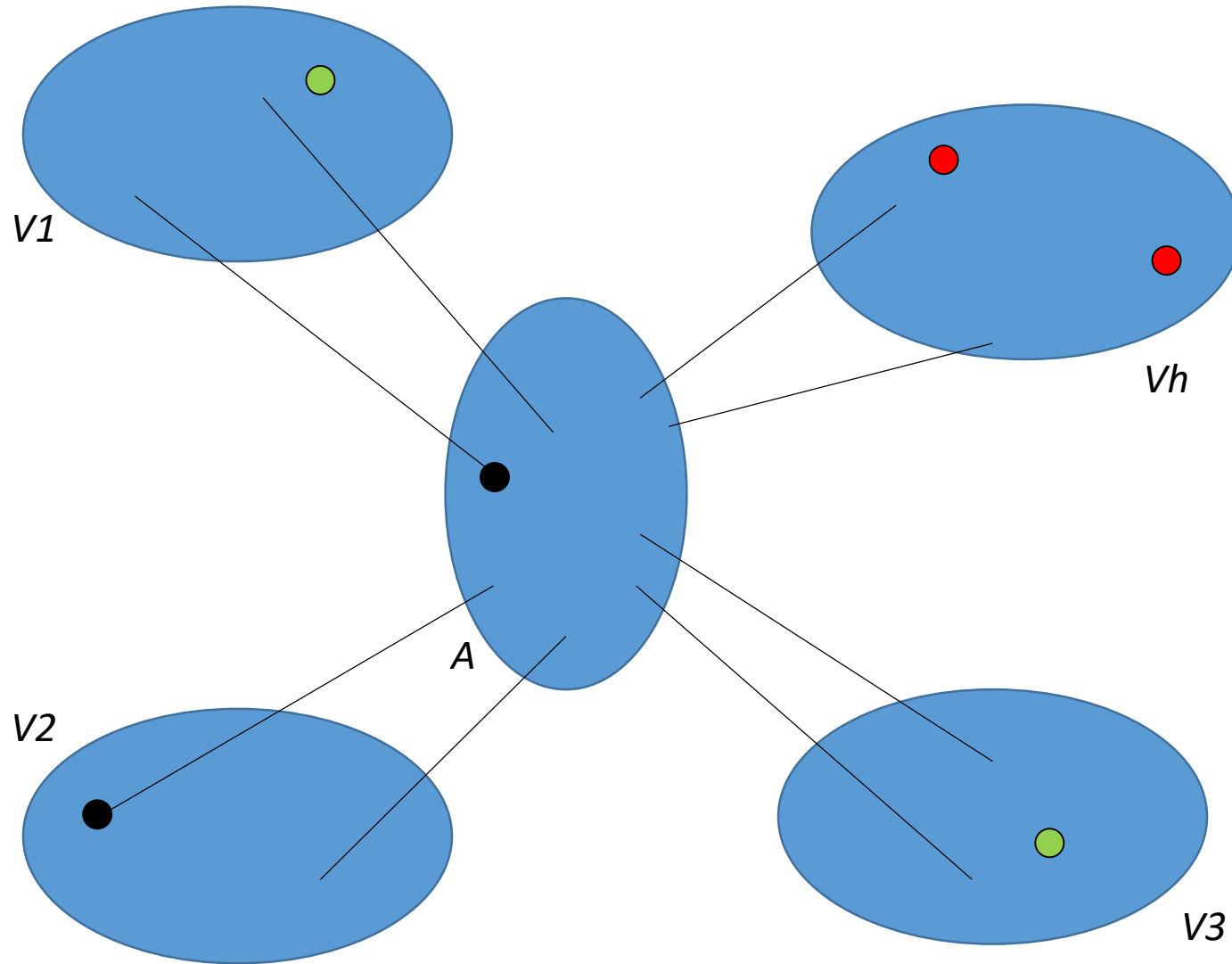
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Algorithm:

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2. **If** $c_v(G) \geq g(k, \ell) = \max\{k\ell, 10\ell\}$, **then** answer **yes**
else determine a small cut and iterate

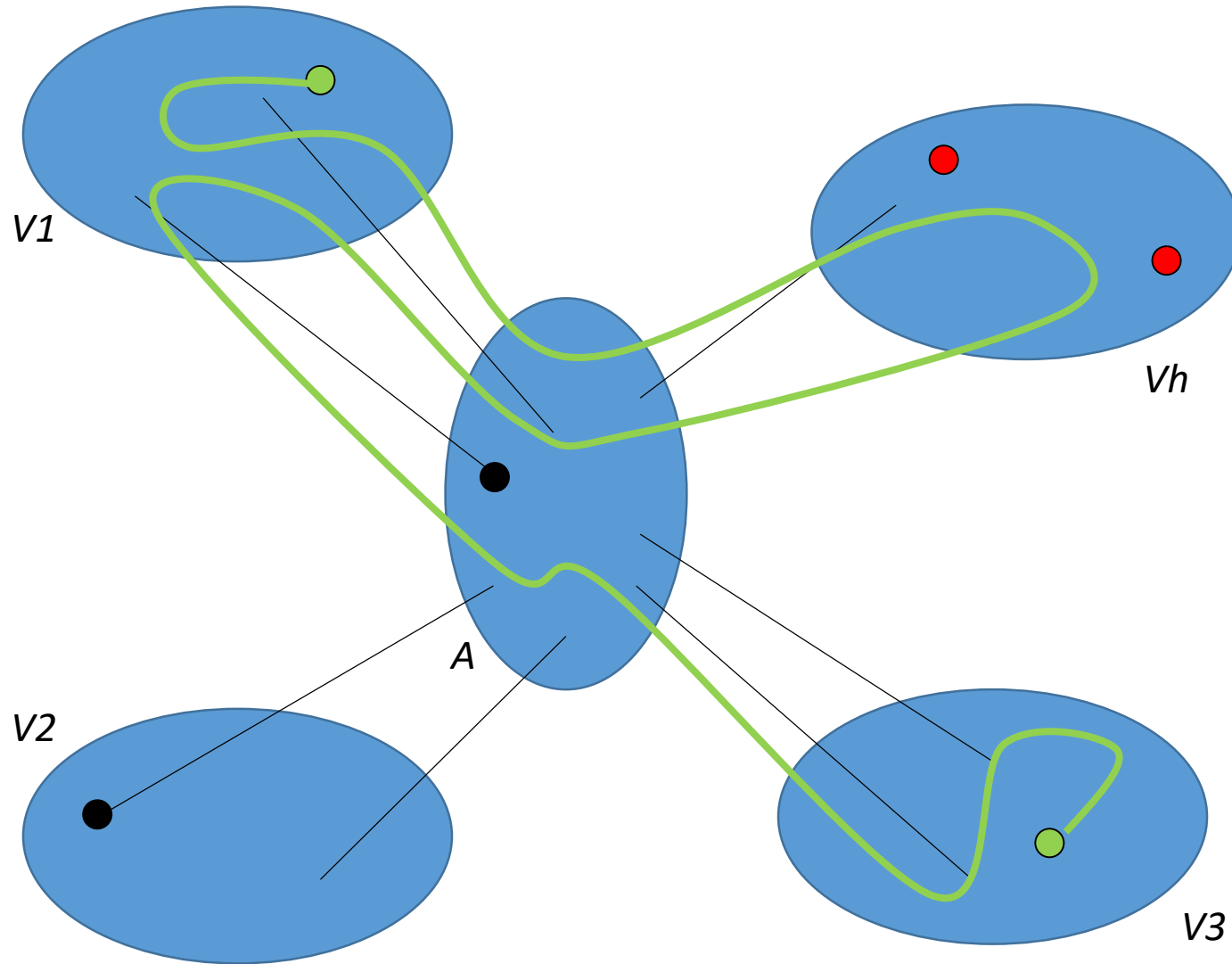
$|A| < g(k, \ell)$
Each $G[V_i]$ is $(k-1)K_1$ -free





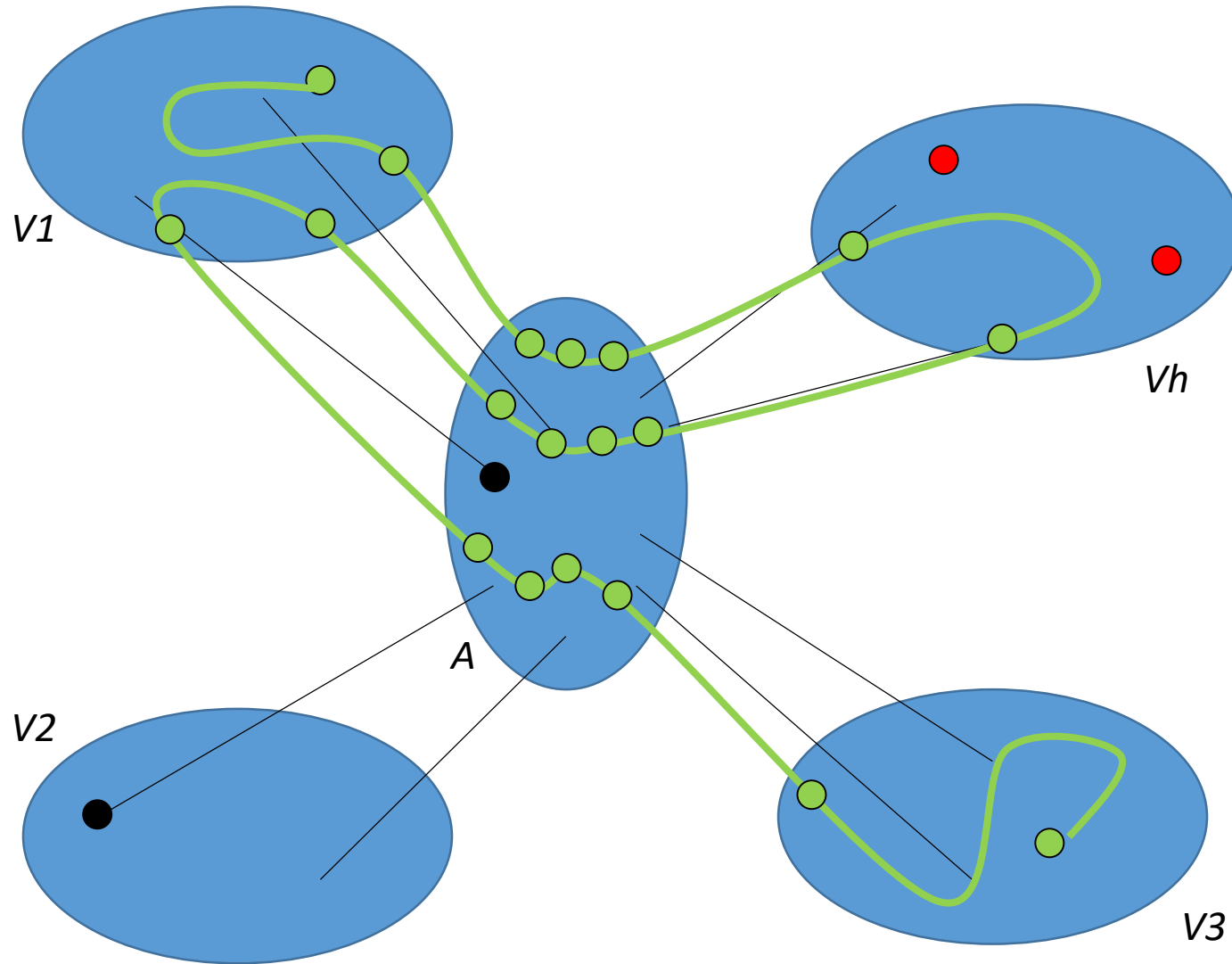
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 Consider all possible **scenarios** for the links
 And check their feasibility
 The number of scenarios is $O(n^{f(k, \ell)})$
 Recursive calls are for $(k-1)K_1$ -free components
 Induction on k

Theorem [arXiv:2309.09228]: For every k and ℓ , Ham- ℓ -Linkage and Ham- ℓ -Linkability are polynomial time solvable on kK_1 -free graphs.

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The running time can be bounded by $O(n2^{\ell k^{k+1}})$.

For small values of k , HamPath can be solved in time

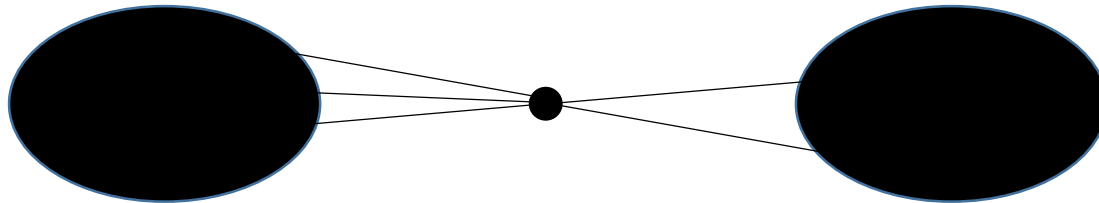
$O(n^{22})$ for $3K_1$ -free graphs

$O(n^{242})$ for $4K_1$ -free graphs

$O(n^{2662})$ for $5K_1$ -free graphs

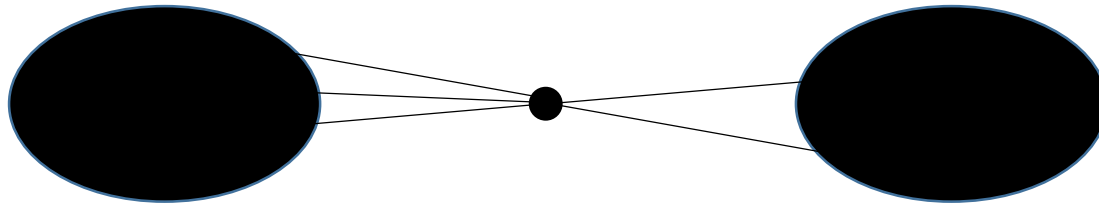
Forbidden configurations for Hamilton Path

Theorem 3 [IWOCA 2024]: A connected $3K_1$ -free graph always has a Hamiltonian path. It has a Hamiltonian path starting in a vertex u if and only if u is not an articulation point of the graph.



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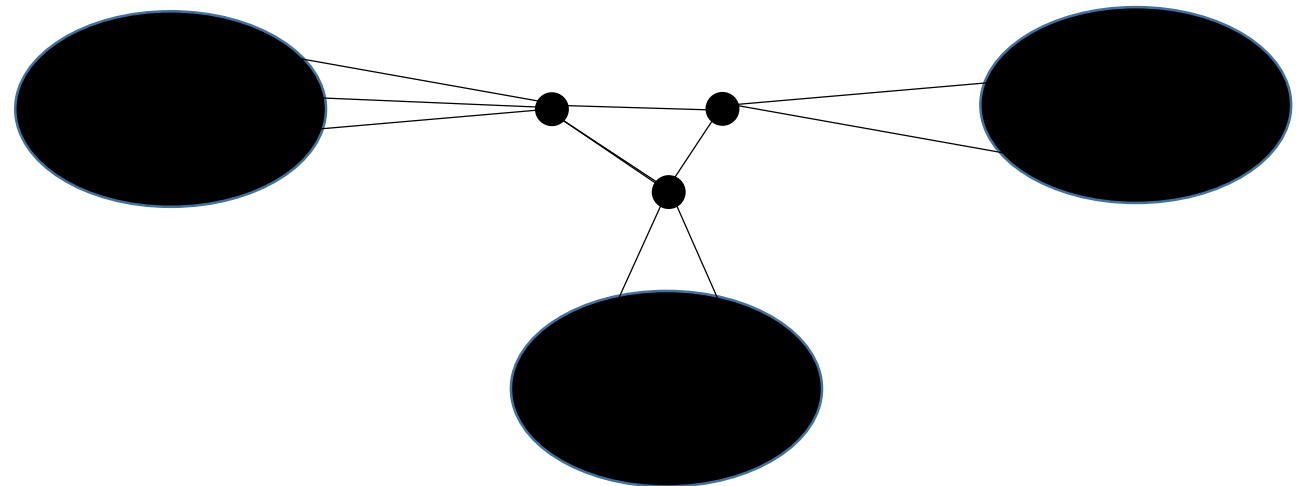
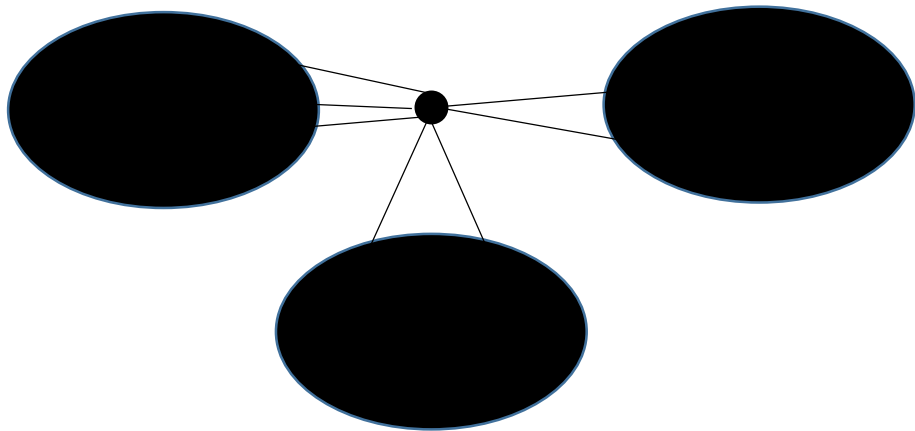
Proof: If G is 2-connected, then it has a Hamiltonian cycle [Chvátal, Erdős], and hence a Hamiltonian path starting in any vertex.

If it is not 2-connected and v is an articulation point, then $G-v$ has 2 connected components and both are cliques.

Forbidden configurations for Hamilton Path

Theorem 4 [IWOCA 2024]: A connected $4K_1$ -free graph has a Hamiltonian path if and only if

- (a) For every articulation point u , the graph $G-u$ has 2 connected components, and
- (b) There are no 3 articulation points inducing a triangle.



Forbidden configurations for Hamilton Path

Theorem 5 [IWOCA 2024]: A connected $5K_1$ -free graph G has a Hamiltonian path if and only if

- (a) For every articulation point u , the graph $G-u$ has 2 connected components, and
- (b) There are no 3 articulation points inducing a triangle.
- (c) If G is not 2-connected, and x is an articulation point such that one of the components of $G-x$, denoted by Q_1 , is a clique and the other one, denoted by Q_2 , induces a $4K_1$ -free graph, then there exists a vertex u in Q_2 adjacent to x such that $G[Q_2]$ has a Hamiltonian path starting in u .
- (d) If G is 2-connected, but not 3-connected, then for every minimum vertex cut $\{x,y\}$ in G , $G-\{x,y\}$ has at most 3 connected components.

Theorem [arXiv:2309.09228]: For every k and ℓ , Ham- ℓ -Linkage and Ham- ℓ -Linkability are polynomial time solvable on kK_1 -free graphs.

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Theorem [Fomin, Golovach, Sagunov, Simonov arXiv:2403.05943]:
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Our obstacles-for-small-independence-graphs paper won the **Best Paper Award at IWOCA 2024**.

Best Paper Award



On the Structure of Hamiltonian Graphs with Small
Independence Number

by

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Thank you

Best Paper Award



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