# Radius of Stability of Different Matrix Properties Related to Optimization Problems

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## Outline

## Matrix properties

- positive definiteness (relates to convexity of a function)
- P-matrix property (unique solvability of LCP)
- M-matrix property (Leontief's input-output model)
- H-matrix property
- total positivity
- inverse nonnegativity

#### Problem statement

Given  $A \in \mathbb{R}^{n \times n}$ , determine the radius of stability of a matrix property for a matrix norm (= distance to a nearest violated matrix).

## Matrix norms

Vector *p*-norms:  $||x||_p := \left(\sum_{i=1}^n |x|_i^p\right)^{\frac{1}{p}}, p \ge 1.$ 

#### Particular matrix norms

• The subordinate matrix norm

$$||A||_{\alpha,\beta} := \max_{\|x\|_{\alpha}=1} ||Ax||_{\beta}$$

• The induced p-norm

$$||A||_p := \max_{||x||_p=1} ||Ax||_p$$

Spectral norm (induced 2-norm)

$$||A||_2 = \max_{||x||_2=1} ||Ax||_2 = \sigma_{\mathsf{max}}(A).$$

- Frobenius norm  $||A||_F := \sqrt{\sum_{i,j} a_{ij}^2}$
- max-norm  $||A||_{\max} := \max_{i,j} |a_{ij}| = ||A||_{1,\infty}$

## Matrix norms

## Properties of matrix norms

- (P1) consistent norm: if  $||AB|| \le ||A|| \cdot ||B||$  for every  $A, B \in \mathbb{R}^{n \times n}$  (for induced norms, Frobenius, but not for max-norm)
- (P2)  $\|I_n\| = 1$  (for induced norms and max-norm, not for Frobenius)
- (P3)  $||A'|| \le ||A||$  whenever A' is a submatrix of A (for induced p-norms, Frobenius and max-norm)
- (P4)  $\|e_i e_j^T\| = 1 \ \ \forall i,j$  (for induced p-norms, Frobenius and max-norm)

# Regularity radius

## Definition

Regularity radius of  $A \in \mathbb{R}^{n \times n}$  is the distance to the nearest singular matrix

$$r(A) := \min\{\|A - B\| : B \text{ is singular}\}.$$

## Particular cases

• For the spectral, Frobenius and some orthogonally invariant norms,

$$r(A) = \sigma_{\min}(A)$$

• For any induced matrix norm (Gastinel–Kahan theorem),

$$r(A) = ||A^{-1}||^{-1}$$

For the max-norm,

$$\mathsf{r}(A) = \|A^{-1}\|_{\infty,1}^{-1} = \frac{1}{\max_{y,z \in \{\pm 1\}^n} y^T A^{-1} z}$$

Its computation is NP-hard [Poljak and Rohn, 1993]

SDP approximation [Hartman and Hladík, 2016]

## Positive definiteness

#### **Definition**

Let  $A \in \mathbb{R}^{n \times n}$  be symmetric positive definite. Radius of positive definiteness of A is

$$\delta^* := \sup\{\delta \ge 0 : A + A' \text{ is positive definite } \forall A' : A' = A'^T, \|A'\| < \delta\}.$$

#### **Theorem**

For every consistent matrix norm satisfying (P2) (i.e.,  $||I_n|| = 1$ ) we have  $\delta^* = \lambda_{\min}(A)$ , the smallest eigenvalue of A.

#### For max-norm

- ullet co-NP-hard to check  $\delta^* > 1$ ,
- $\delta^* \geq \frac{1}{n} \lambda_{\min}(A)$ ,
- $\bullet \ \delta^* = \min_{y \in \{\pm 1\}^n} \frac{1}{v^T A^{-1} v},$
- If A is inverse nonnegative, then  $\delta^* = \frac{1}{e^T A^{-1} e}$ .

# P-matrix property

#### **Definition**

 $A \in \mathbb{R}^{n \times n}$  is a P-matrix if all its principal minors are positive.

• It guarantees a unique solution for each q of the LCP

$$q + Ax \ge 0, \quad x \ge 0, \quad (q + Ax)^T x = 0$$

[Cottle, Pang, and Stone, 2009; Murty, 1988]

- Checking P-matrix property is co-NP-hard [Coxson, 1994]
- Efficiently recognizable subclasses:
  - positive definite matrices,
  - M-matrices,
  - H-matrices with positive diagonal,
  - or totally positive matrices.

## P-matrix radius of a P-matrix A

$$\delta^* := \sup\{\delta \ge 0 \colon A + A' \text{ is an P-matrix } \forall A' \colon ||A'|| < \delta\}.$$

# P-matrix property

#### Theorem

For any matrix norm we have

$$\delta^* = \min\{r(\hat{A}) : \hat{A} \text{ is a principal submatrix of } A\}.$$

In particular, for the spectral or Frobenius norm we have

$$\delta^* = \min\{\sigma_{\min}(\hat{A}) : \hat{A} \text{ is a principal submatrix of } A\}.$$

#### **Theorem**

Suppose A is a symmetric positive definite or an M-matrix ( $a_{ij} \leq 0$ ,  $i \neq j$ , and  $A^{-1} \geq 0$ ). For the spectral or Frobenius norm we have

$$\delta^* = \sigma_{\min}(A).$$

#### **Theorem**

Suppose A is an M-matrix. For the max-norm we have

$$\delta^* = \frac{1}{e^T A^{-1} e}.$$

# M-matrix property

## Definition

 $A \in \mathbb{R}^{n \times n}$  is an M-matrix if  $a_{ij} \leq 0$  for every  $i \neq j$  and  $A^{-1} \geq 0$  (or, Av > 0 for certain v > 0). [Horn and Johnson, 1991]

- sub-class of P-matrices
- stability of Leontief's input-output analysis in economic systems, and others

## M-matrix radius of an M-matrix A

$$\delta^* := \sup \{ \delta \geq 0 \colon A + A' \text{ is an M-matrix } \forall A' \colon \|A'\| < \delta \}.$$

## Example

Consider the identity matrix  $A = I_n$  and the spectral norm:

- the P-matrix radius is 1
- the M-matrix radius is 0

## M-matrix property

#### **Theorem**

For every matrix norm satisfying (P3) and (P4) we have

$$\delta^* = \min_{i \neq j} \{-a_{ij}, \mathsf{r}(A)\}.$$

In particular, for the spectral or Frobenius norm, we have

$$\delta^* = \min_{i \neq j} \{ -a_{ij}, \sigma_{\min}(A) \}.$$

#### Max-norm

- The worst case is  $A \delta E$ , where E consists of ones.
- $\delta^*$  is maximal such that  $A \delta E$  is an M-matrix for all  $\delta \in [0, \delta^*)$ .
- Simple parametrization (linear constraints by Sherman–Morrison formula):

$$(A - \delta E)_{ij} \leq 0, \ i \neq j, \text{ and } (A - \delta E)^{-1} \geq 0.$$

# Total positivity

#### Definition

 $A \in \mathbb{R}^{n \times n}$  is totally positive if the determinants of all submatrices are positive.

- Sub-class of P-matrices.
- Only initial submatrices  $A^{(1)},\ldots,A^{(n^2)}$  needed to check: rows are indexed by  $\{1,\ldots,k\}$  and columns by  $\{\ell,\ldots,\ell+k-1\}$  or vice versa. [Fallat and Johnson, 2011]

## Totally positive radius of A

$$\delta^* := \sup \{ \delta \ge 0 : A + A' \text{ is totally positive } \forall A' : ||A'|| < \delta \}.$$

# Total positivity

#### **Theorem**

We have 
$$\delta^* = \min_{i=1,...,n^2} r(A^{(i)}).$$

In particular, for the spectral or Frobenius norm,  $\delta^* = \min_{i=1,\dots,n^2} \sigma_{\min}(A^{(i)})$ .

#### Max-norm

- The worst case is  $A \delta ss^T$  or  $A + \delta ss^T$ , where  $s := (1, -1, 1, -1, \dots)^T$  [Garloff, 1982]
- $\delta^*$  is thus computed by simple parametrization (Sherman–Morrison formula)

# Inverse nonnegativity

## **Definition**

 $A \in \mathbb{R}^{n \times n}$  is inverse nonnegative if  $A^{-1} \geq 0$ .

## Inverse nonnegativity radius of A

$$\delta^* := \sup \{ \delta \geq 0 \colon A + A' \text{ is inverse nonnegative } \forall A' \colon \|A'\| < \delta \}.$$

### **Theorem**

We have  $\delta^* = \min_{i,j=1,...,n} \{r(A), r(A^{ij})\}$ . In particular, for the spectral or Frobenius norm,  $\delta^* = \min_{i,j=1,...,n} \{\sigma_{\min}(A), \sigma_{\min}(A^{ij})\}$ .

#### Max-norm

- The worst case is  $A \delta E$  or  $A + \delta E$  [Kuttler, 1971]
- $\bullet$   $\delta^*$  is thus computed by simple parametrization (Sherman–Morrison formula)

## Conclusion

#### Conclusion

- stability radius for diverse matrix properties related to optimization
- typically reduced to several problems of regularity radius
- often for many norms tractable (spectral of Frobenius norm), sometimes NP-hard (max-norm)

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