# Tolerances, Robustness and Parametrization of Matrix Properties Related to Optimization Problems

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# Outline

## Matrix properties

- positive definiteness (relates to convexity of a function)
- P-matrix property (unique solvability of LCP)
- M-matrix property (Leontief's input-output model)
- H-matrix property
- total positivity
- inverse nonnegativity

## **Problem I statement**

Given  $A \in \mathbb{R}^{n \times n}$ , determine the radius of stability of a matrix property for a matrix norm (= distance to nearest violated matrix).

## Problem II statement

Stability in the direction  $A + \delta \tilde{A}$  with a parameter  $\delta$ .

# Matrix norms

Vector *p*-norms: 
$$||x||_p := \left(\sum_{i=1}^n |x|_i^p\right)^{\frac{1}{p}}, \ p \ge 1.$$

## Particular matrix norms

• The subordinate matrix norm

$$|A\|_{\alpha,\beta} := \max_{\|x\|_{\alpha}=1} \|Ax\|_{\beta}$$

• The induced *p*-norm

$$\|A\|_p := \max_{\|x\|_p=1} \|Ax\|_p$$

Spectral norm (induced 2-norm)

$$\|A\|_2 = \max_{\|x\|_2=1} \|Ax\|_2 = \sigma_{\max}(A).$$

• Frobenius norm  $||A||_F := \sqrt{\sum_{i,j} a_{ij}^2}$ 

• max-norm  $\|A\|_{\max} := \max_{i,j} |a_{ij}|$ 

## Properties of matrix norms

- (P1) consistent norm: if  $||AB|| \le ||A|| \cdot ||B||$  for every  $A, B \in \mathbb{R}^{n \times n}$  (for induced norms, Frobenius, but not for max-norm)
- (P2)  $||I_n|| = 1$ (for induced norms and max-norm, not for Frobenius)
- (P3)  $||A'|| \le ||A||$  whenever A' is a submatrix of A (for induced *p*-norms, Frobenius and max-norm)

(P4) 
$$\|e_i e_j^T\| = 1 \quad \forall i, j$$
  
(for induced *p*-norms, Frobenius and max-norm

# Regularity radius

### Definition

Regularity radius of  $A \in \mathbb{R}^{n \times n}$  is the distance to the nearest singular matrix

$$\mathsf{r}(A) := \min\{\|A - B\| : B \text{ is singular}\}.$$

### Particular cases

• For the spectral, Frobenius and some orthogonally invariant norms,

$$\mathsf{r}(A) = \sigma_{\min}(A)$$

• For any induced matrix norm (Gastinel-Kahan theorem),

$$r(A) = \|A^{-1}\|^{-1}$$

• For the max-norm,

$$\mathsf{r}(A) = \|A^{-1}\|_{\infty,1}^{-1} = \frac{1}{\max_{y,z \in \{\pm 1\}^n} y^T A^{-1} z}$$

Its computation is NP-hard SDP approximation

[Poljak and Rohn, 1993] [Hartman and Hladík, 2016]

# Positive definiteness

### Definition

Let  $A \in \mathbb{R}^{n \times n}$  be symmetric positive definite. Radius of positive definiteness of A is

 $\delta^* := \sup\{\delta \ge 0 \colon A + A' \text{ is positive definite } \forall A' : A' = A'^T, \ \|A'\| < \delta\}.$ 

#### Theorem

For every consistent matrix norm satisfying (P2) (i.e.,  $||I_n|| = 1$ ) we have  $\delta^* = \lambda_{\min}(A)$ , the smallest eigenvalue of A.

#### For max-norm

- co-NP-hard to check  $\delta^*>1,$
- $\delta^* \geq \frac{1}{n}\lambda_{\min}(A)$ ,

• 
$$\delta^* = \min_{y \in \{\pm 1\}^n} \frac{1}{y^T A^{-1} y}$$
,

• If A is inverse nonnegative, then  $\delta^* = \frac{1}{e^T A^{-1} e}$ .

# P-matrix property

## Definition

 $A \in \mathbb{R}^{n \times n}$  is a P-matrix if all its principal minors are positive.

• It guarantees a unique solution for each q of the LCP

$$q + Ax \ge 0, \ x \ge 0, \ (q + Ax)^T x = 0$$

[Cottle, Pang, and Stone, 2009; Murty, 1988]

• Checking P-matrix property is co-NP-hard

[Coxson, 1994]

- Efficiently recognizable subclasses:
  - positive definite matrices,
  - M-matrices,
  - H-matrices with positive diagonal,
  - or totally positive matrices.

P-matrix radius of a P-matrix A

 $\delta^* := \sup\{\delta \ge 0 \colon A + A' \text{ is an } \mathsf{P}\text{-matrix } \forall A' : \|A'\| < \delta\}.$ 

# P-matrix property

#### Theorem

For any matrix norm we have

 $\delta^* = \min\{r(\hat{A}) : \hat{A} \text{ is a principal submatrix of } A\}.$ 

In particular, for the spectral or Frobenius norm we have

 $\delta^* = \min\{\sigma_{\min}(\hat{A}) : \hat{A} \text{ is a principal submatrix of } A\}.$ 

#### Theorem

Suppose A is an symmetric positive definite or an M-matrix ( $a_{ij} \leq 0$ ,  $i \neq j$ , and  $A^{-1} \geq 0$ ). For the spectral or Frobenius norm we have

$$\delta^* = \sigma_{\min}(A).$$

#### Theorem

Suppose A is an M-matrix. For the max-norm we have

$$\delta^* = \frac{1}{e^T A^{-1} e}.$$

# M-matrix property

## Definition

 $A \in \mathbb{R}^{n \times n}$  is an M-matrix if  $a_{ij} \leq 0$  for every  $i \neq j$  and  $A^{-1} \geq 0$  (or, Av > 0 for certain v > 0). [Horn and Johnson, 1991]

- sub-class of P-matrices
- stability of Leontief's input-output analysis in economic systems, and others

### M-matrix radius of an M-matrix A

 $\delta^* := \sup\{\delta \ge 0 \colon A + A' \text{ is an M-matrix } \forall A' : \|A'\| < \delta\}.$ 

### Example

Consider the identity matrix  $A = I_n$  and the spectral norm:

- the P-matrix radius is 1
- the M-matrix radius is 0

# M-matrix property

### Theorem

For every matrix norm satisfying (P3) and (P4) we have

$$\delta^* = \min_{i \neq j} \{-a_{ij}, \mathbf{r}(A)\}.$$

In particular, for the spectral or Frobenius norm, we have

$$\delta^* = \min_{i \neq j} \{ -a_{ij}, \sigma_{\min}(A) \}.$$

#### Max-norm

- The worst case is  $A \delta E$ , where E consists of ones.
- $\delta^*$  is maximal such that  $A \delta E$  is an M-matrix for all  $\delta \in [0, \delta^*)$ .
- Simple parametrization (linear constraints by Sherman–Morrison formula):

 $(A - \delta E)_{ij} \leq 0, \ i \neq j, \text{ and } (A - \delta E)^{-1} \geq 0.$ 

## Definition

 $A \in \mathbb{R}^{n \times n}$  is totally positive if the determinants of all submatrices are positive.

- Sub-class of P-matrices.
- Only initial submatrices A<sup>(1)</sup>,..., A<sup>(n<sup>2</sup>)</sup> needed to check: rows are indexed by {1,..., k} and columns by {l,..., l + k 1} or vice versa. [Fallat and Johnson, 2011]

Totally positive radius of A

$$\delta^* := \sup\{\delta \ge 0 \colon A + A' \text{ is totally positive } \forall A' : \|A'\| < \delta\}.$$

### Theorem

We have 
$$\delta^* = \min_{i=1,\dots,n^2} r(A^{(i)}).$$

In particular, for the spectral or Frobenius norm,  $\delta^* = \min_{i=1,...,n^2} \sigma_{\min}(A^{(i)})$ .

### Max-norm

• The worst case is 
$$A - \delta s s^T$$
 or  $A + \delta s s^T$ , where  $s := (1, -1, 1, -1, \dots)^T$  [Garloff, 1982]

•  $\delta^*$  is thus computed by simple parametrization (Sherman–Morrison formula)

# Inverse nonnegativity

## Definition

 $A \in \mathbb{R}^{n \times n}$  is inverse nonnegative if  $A^{-1} \ge 0$ .

### Inverse nonnegativity radius of A

 $\delta^* := \sup\{\delta \ge 0 \colon A + A' \text{ is inverse nonnegative } \forall A' : \|A'\| < \delta\}.$ 

#### Theorem

We have 
$$\delta^* = \min_{i,j=1,...,n} \{r(A), r(A^{ij})\}$$
.  
In particular, for the spectral or Frobenius norm,  
 $\delta^* = \min_{i,j=1,...,n} \{\sigma_{\min}(A), \sigma_{\min}(A^{ij})\}$ .

#### Max-norm

• The worst case is  $A - \delta E$  or  $A + \delta E$ 

[Kuttler, 1971]

•  $\delta^*$  is thus computed by simple parametrization (Sherman–Morrison formula)

## Conclusion

- stability radius for diverse matrix properties related to optimization
- typically reduced to several problems of regularity radius
- often for many norms tractable (spectral of Frobenius norm), sometimes NP-hard (max-norm)

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