

# Positive Semidefiniteness and Positive Definiteness of a Linear Parametric Interval Matrix

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## Why positive (semi)definiteness of interval matrices?

In global optimization, for convexity checking:

- If a function is convex on a box, then a stationary point is a minimum.
- If a function is convex nowhere on a box, and the box is inside the feasible set, then there is no minimum inside.

Also:

- Hurwitz stability of dynamical systems.
- Schur stability of dynamical systems.

## Interval Matrix

An interval matrix

$$\mathbf{A} := [\underline{A}, \overline{A}] = \{A \in \mathbb{R}^{m \times n} \mid \underline{A} \leq A \leq \overline{A}\}.$$

The center and radius matrices

$$A^c := \frac{1}{2}(\overline{A} + \underline{A}), \quad A^\Delta := \frac{1}{2}(\overline{A} - \underline{A}).$$

The set of all  $m \times n$  interval matrices:  $\mathbb{IR}^{m \times n}$ .

## A Symmetric Interval Matrix

$$\mathbf{A}^S := \{A \in \mathbf{A} : A = A^T\}.$$

Without loss of generality assume that  $\underline{A} = \underline{A}^T$ ,  $\overline{A} = \overline{A}^T$ , and  $\mathbf{A}^S \neq \emptyset$ .

# Positive Semidefiniteness and Positive Definiteness

$\mathbf{A}^S$  is *positive (semi)definite* if every  $A \in \mathbf{A}^S$  is positive (semi)definite.

## Theorem (Rohn, 1994)

*The following are equivalent*

- 1  $\mathbf{A}^S$  is *positive semidefinite*,
- 2  $A^c - \text{diag}(z)A^\Delta \text{diag}(z)$  is *positive semidefinite*  $\forall z \in \{\pm 1\}^n$ ,
- 3  $x^T A^c x - |x|^T A^\Delta |x| \geq 0$  for each  $x \in \mathbb{R}^n$ .

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- 3  $x^T A^c x - |x|^T A^\Delta |x| > 0$  for each  $0 \neq x \in \mathbb{R}^n$ ,
- 4  $A^c$  is *positive definite* and  $\mathbf{A}$  is *regular*.

## Theorem (Nemirovskii, 1993)

*Checking positive semidefiniteness of  $\mathbf{A}^S$  is co-NP-hard.*

## Theorem (Rohn, 1994)

*Checking positive definiteness of  $\mathbf{A}^S$  is co-NP-hard.*

## Theorem (Jaulin and Henrion, 2005)

*Checking whether there is a positive semidefinite matrix in  $\mathbf{A}^S$  is a polynomial time problem.*

## Proof.

By reduction to semidefinite programming. □

# Sufficient Conditions

## Theorem

- 1  $\mathbf{A}^S$  is positive semidefinite if  $\lambda_{\min}(A^c) \geq \rho(A^\Delta)$ .
- 2  $\mathbf{A}^S$  is positive definite if  $\lambda_{\min}(A^c) > \rho(A^\Delta)$ .
- 3  $\mathbf{A}^S$  is positive definite if  $A^c$  is positive definite and  $\rho(|(A^c)^{-1}|A^\Delta) < 1$ .

## Proof.

- 1  $\mathbf{A}^S$  is positive semidefinite iff  $\lambda_{\min}(A) \geq 0 \forall A \in \mathbf{A}^S$ .

Now, employ the smallest eigenvalue set enclosure

$$\lambda_{\min}(A) \in [\lambda_{\min}(A^c) - \rho(A^\Delta), \lambda_{\min}(A^c) + \rho(A^\Delta)] \quad \forall A \in \mathbf{A}^S.$$

- 2 Analogous.
- 3 Use Beek's sufficient condition for regularity of  $\mathbf{A}$ . □

# Application: Convexity Testing

## Theorem

*A function  $f : \mathbb{R}^n \mapsto \mathbb{R}$  is convex on  $\mathbf{x} \in \mathbb{R}^n$  iff its Hessian  $\nabla^2 f(\mathbf{x})$  is positive semidefinite  $\forall \mathbf{x} \in \text{int } \mathbf{x}$ .*

## Corollary

*A function  $f : \mathbb{R}^n \mapsto \mathbb{R}$  is convex on  $\mathbf{x} \in \mathbb{R}^n$  if  $\nabla^2 f(\mathbf{x})$  is positive semidefinite.*

# Application: Convexity Testing

## Example

Let

$$f(x, y, z) = x^3 + 2x^2y - xyz + 3yz^2 + 8y^2,$$

on  $x \in \mathbf{x} = [2, 3]$ ,  $y \in \mathbf{y} = [1, 2]$  and  $z \in \mathbf{z} = [0, 1]$ . The Hessian of  $f$  reads

$$\nabla^2 f(x, y, z) = \begin{pmatrix} 6x + 4y & 4x - z & -y \\ 4x - z & 16 & -x + 6z \\ -y & -x + 6z & 6y \end{pmatrix}$$

Evaluation the Hessian matrix by interval arithmetic results in

$$\nabla^2 f(\mathbf{x}, \mathbf{y}, \mathbf{z}) \subseteq \begin{pmatrix} [16, 26] & [7, 12] & -[1, 2] \\ [7, 12] & 16 & [-3, 4] \\ -[1, 2] & [-3, 4] & [6, 12] \end{pmatrix}$$

Now, both sufficient conditions for positive definiteness succeed.

Thus, we can conclude that  $f$  is convex on the interval domain.



# Parametric Interval Matrices

## Parametric Interval Matrix

Consider

$$A(p) = \sum_{k=1}^K A^{(k)} p_k,$$

where  $A^{(1)}, \dots, A^{(K)} \in \mathbb{R}^{n \times n}$  are fixed symmetric matrices and  $p_1, \dots, p_K$  are parameters varying respectively in  $\mathbf{p}_1, \dots, \mathbf{p}_K \in \mathbb{I}\mathbb{R}$ .

## Definition

- $A(p)$ ,  $p \in \mathbf{p}$ , is *strongly positive (semi)definite* if  $A(p)$  is positive (semi)definite for each  $p \in \mathbf{p}$ .
- It is *weakly positive (semi)definite* if  $A(p)$  is positive (semi)definite for at least one  $p \in \mathbf{p}$ .

# Parametric Interval Matrices

## Relaxation

Evaluation  $A(\mathbf{p}) = \sum_{k=1}^K A^{(k)} \mathbf{p}_k$  by interval arithmetic

- encloses the set of matrices  $A(p)$ ,  $p \in \mathbf{p}$ ,
- may lead to loss of strong positive (semi-)definiteness.

## Example

Let

$$A(p) = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} p, \quad p \in \mathbf{p} = [0, 1].$$

This parametric matrix is strongly positive semidefinite, but its relaxation

$$A(\mathbf{p}) = \begin{pmatrix} [0, 1] & [0, 1] \\ [0, 1] & [0, 1] \end{pmatrix}$$

is not as it contains, e.g., the indefinite matrix

$$\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}.$$

# Strong Positive Semidefiniteness

## Theorem

*The following are equivalent:*

- (1)  $A(p)$  is positive semidefinite for each  $p \in \mathbf{p}$ ,*
- (2)  $A(p)$  is positive semidefinite for each  $p$  such that  $p_k \in \{\underline{p}_k, \bar{p}_k\} \forall k$ ,*
- (3)  $x^T A(p^c) x - \sum_{k=1}^K |x^T A^{(k)} x| p_k^\Delta \geq 0$  for each  $x \in \mathbb{R}^n$ .*

- It reduces the problem to checking positive semidefiniteness of  $2^K$  real matrices.
- The number can be further decreased in some cases.

## Theorem

- (1) If  $A^{(i)}$  is positive semidefinite for some  $i$ , then we can fix  $p_i := \underline{p}_i$  for checking strong positive semidefiniteness.*
- (2) If  $A^{(i)}$  is negative semidefinite for some  $i$ , then we can fix  $p_i := \bar{p}_i$  for checking strong positive semidefiniteness.*

# Strong Positive Semidefiniteness – Sufficient Condition

## Theorem

For each  $k$ , split  $A^{(k)} = A_1^{(k)} - A_2^{(k)}$  such that both  $A_1^{(k)}, A_2^{(k)}$  are positive semidefinite. Then  $A(p), p \in \mathbf{p}$ , is strongly positive semidefinite if

$$\sum_{k=1}^K \left( A_1^{(k)} \underline{p}_k - A_2^{(k)} \overline{p}_k \right)$$

is positive semidefinite.

## How to Do the Splitting

- 1 Let  $A^{(k)} = Q\Lambda Q^T$  be a spectral decomposition of  $A^{(k)}$ .
- 2 Let  $\Lambda^+$  be the positive part of  $\Lambda$ .
- 3 Let  $\Lambda^-$  be the negative part of  $\Lambda$ .
- 4 Then  $A^{(k)} = Q\Lambda Q^T = Q\Lambda^+ Q^T - Q\Lambda^- Q^T$  and both  $Q\Lambda^+ Q^T, Q\Lambda^- Q^T$  are positive semidefinite.

Overall cost:  $K + 1$  spectral decompositions.

# Weak Positive Semidefiniteness

## Theorem

*Checking weak positive semidefiniteness is a polynomial problem.*

## Proof.

By reduction to semidefinite programming. Let  $M(p)$  be the block diagonal matrix with blocks

$$A(p), p_1 - \underline{p}_1, \dots, p_K - \underline{p}_K, \bar{p}_1 - p_1, \dots, \bar{p}_K - p_K.$$

- All entries of  $M(p)$  depends affinely on variables  $p$ .
- Positive definiteness of  $M(p)$  is equivalent to positive definiteness of  $A(p)$  and feasibility of variables  $p \in \mathbf{p}$ .

Therefore, by solving this semidefinite program we check whether  $A(p)$ ,  $p \in \mathbf{p}$ , is weakly positive semidefinite. □

# Strong Positive Definiteness

Theorem (The following are equivalent)

- (1)  $A(p)$ ,  $p \in \mathbf{p}$ , is strongly positive definite,
- (2)  $A(p)$  is positive definite for each  $p$  such that  $p_k \in \{\underline{p}_k, \bar{p}_k\} \forall k$ ,
- (3)  $x^T A(p^c) x - \sum_{k=1}^K |x^T A^{(k)} x| p_k^\Delta > 0$  for each  $0 \neq x \in \mathbb{R}^n$ .

Theorem

- (1) If  $A^{(i)}$  is positive semidefinite for some  $i$ , then we can fix  $p_i := \underline{p}_i$  for checking strong positive definiteness.
- (2) If  $A^{(i)}$  is negative semidefinite for some  $i$ , then we can fix  $p_i := \bar{p}_i$  for checking strong positive definiteness.

Theorem (Sufficient Condition)

For each  $k = 1, \dots, K$ , split  $A^{(k)} = A_1^{(k)} - A_2^{(k)}$  such that both  $A_1^{(k)}, A_2^{(k)}$  are positive semidefinite. Then  $A(p)$ ,  $p \in \mathbf{p}$ , is strongly positive definite if

$$\sum_{k=1}^K \left( A_1^{(k)} \underline{p}_k - A_2^{(k)} \bar{p}_k \right) \text{ is positive definite.}$$

# Strong Positive Definiteness and Regularity

## Definition

$A(p)$ ,  $p \in \mathbf{p}$ , is called *regular* if  $A(p)$  is nonsingular for each  $p \in \mathbf{p}$ .

## Theorem

*The parametric matrix  $A(p)$ ,  $p \in \mathbf{p}$ , is strongly positive definite if and only if  $A(p)$  is positive definite for some  $p \in \mathbf{p}$  and  $A(p)$ ,  $p \in \mathbf{p}$ , is regular.*

## Beeck sufficient regularity criterion

$A(p)$ ,  $p \in \mathbf{p}$ , is regular if

$$\rho(M^\Delta) < 1,$$

where

$$\mathbf{M} := \sum_{k=1}^K (CA^{(k)}) \mathbf{p}_k,$$

and  $C = A(p^c)^{-1}$  is the preconditioner.

Both sufficient conditions for strong positive definiteness are incomparable.

# Application in Convexity Testing

Consider a class of functions

$$f(\mathbf{x}) = \sum_{\ell=1}^L c_{\ell} x_{i_{\ell}} x_{j_{\ell}} x_{k_{\ell}},$$

where  $i_{\ell}, j_{\ell}, k_{\ell} \in \{0, \dots, n\}$  are not necessarily mutually different, and  $x_0 = 1$ .

## Problem

Check for convexity of  $f(\mathbf{x})$  on  $\mathbf{x} \in \mathbb{R}^n$ .

- The Hessian matrix has directly a linear parametric form.
- Each entry of the Hessian of  $f(\mathbf{x})$  is a linear function with respect to  $\mathbf{x} \in \mathbb{R}^n$ .
- The variables  $\mathbf{x}$  play the role of the parameters  $\mathbf{p}$ , and their domain  $\mathbf{x}$  works as  $\mathbf{p}$ .



# Application in Convexity Testing – Example

## Example

Check convexity of

$$f(x, y, z) = x^3 + 2x^2y - xyz + 3yz^2 + 5y^2,$$

on  $x \in \mathbf{x} = [2, 3]$ ,  $y \in \mathbf{y} = [1, 2]$  and  $z \in \mathbf{z} = [0, 1]$ . The Hessian of  $f$  reads

$$\nabla^2 f(x, y, z) = \begin{pmatrix} 6x + 4y & 4x - z & -y \\ 4x - z & 10 & -x + 6z \\ -y & -x + 6z & 6y \end{pmatrix}.$$






Relaxation leads to

$$\nabla^2 f(\mathbf{x}, \mathbf{y}, \mathbf{z}) \subseteq \begin{pmatrix} [16, 26] & [7, 12] & -[1, 2] \\ [7, 12] & 10 & [-3, 4] \\ -[1, 2] & [-3, 4] & [6, 12] \end{pmatrix},$$

which is not strongly positive semidefinite.

Nevertheless, the sufficient conditions for the parametric Hessian enclosure succeed in proving convexity!

- Extension of characterization of positive (semi)definiteness of interval matrices to parametric forms.
- Surprisingly, finite reduction is possible.
- Even more surprisingly, complexity needn't be worse (from  $2^n$  to  $2^K$ ).

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