Computing the tolerance in multiobjective linear programming

Milan Hladík

Department of Applied Mathematics Charles University, Prague

Joint EUROPT-OMS Meeting 2007 July 4–7, Prague

▲□▶▲□▶▲□▶▲□▶ ▲□ ● ● ●

Consider the multiobjective linear program

 $\max_{x\in\mathcal{M}} Cx,$

where

$$\mathcal{M} := \{ x \in \mathbb{R}^n : Ax \le b \}.$$

Consider the multiobjective linear program

 $\max_{x\in\mathcal{M}} Cx,$

where

$$\mathcal{M} := \{ x \in \mathbb{R}^n : Ax \le b \}.$$

Let x^* be an efficient solution.

Consider the multiobjective linear program

 $\max_{x\in\mathcal{M}} Cx,$

where

$$\mathcal{M} := \{ x \in \mathbb{R}^n : Ax \le b \}.$$

Let x^* be an efficient solution.

Definition

• Additive tolerance: any δ such that x^* remains efficient for all $\hat{C} : |C_{ij} - \hat{C}_{ij}| < \delta$;

Consider the multiobjective linear program

 $\max_{x\in\mathcal{M}} Cx,$

where

$$\mathcal{M} := \{ x \in \mathbb{R}^n \colon Ax \le b \}.$$

Let x^* be an efficient solution.

Definition

- Additive tolerance: any δ such that x^* remains efficient for all $\hat{C} : |C_{ij} \hat{C}_{ij}| < \delta$;
- Multiplicative tolerance: any δ such that x^* remains efficient for all $\hat{C} : |C \hat{C}| < \delta |G|$.

Computing the tolerances

Normal cone of \mathcal{M} at the point x^*

$$\mathcal{N}(x^*) := \{x \in \mathbb{R}^n \colon Dx \ge 0\}.$$

For a nondegenerate basic solution, $D = (A_B^{-1})^T$.

Computing the tolerances

Normal cone of $\mathcal M$ at the point x^*

$$\mathcal{N}(x^*) := \{x \in \mathbb{R}^n \colon Dx \ge 0\}.$$

For a nondegenerate basic solution, $D = (A_B^{-1})^T$.

Theorem (Additive tolerance, Hladík 2007)

Let (λ^*, δ^*) be an optimal solution to the linear program

 $\max \delta \text{ subject to } DC^{\mathsf{T}}\lambda - |D|e\delta \geq 0, \ \lambda, \delta \geq 0, \ e^{\mathsf{T}}\lambda = 1.$

Then δ^* is an additive tolerance.

Computing the tolerances

Normal cone of $\mathcal M$ at the point x^*

$$\mathcal{N}(x^*) := \{x \in \mathbb{R}^n \colon Dx \ge 0\}.$$

For a nondegenerate basic solution, $D = (A_B^{-1})^T$.

Theorem (Additive tolerance, Hladík 2007)

Let (λ^*, δ^*) be an optimal solution to the linear program

 $\max \delta \text{ subject to } DC^{\mathsf{T}}\lambda - |D|e\delta \geq 0, \ \lambda, \delta \geq 0, \ e^{\mathsf{T}}\lambda = 1.$

Then δ^* is an additive tolerance.

Theorem (Multiplicative tolerance, Hladík 2007) Let (λ^*, δ^*) be an optimal solution to the generalized linear fractional program

 $\max \delta \text{ subject to } DC^{\mathsf{T}}\lambda - \delta |D||G|^{\mathsf{T}}\lambda \geq 0, \ \lambda, \delta \geq 0, \ e^{\mathsf{T}}\lambda = 1.$

Then δ^* is a multiplicative tolerance.

Example (Hansen, Labbé, Wendell 1989) Consider

$$\begin{split} \mathcal{C} &= \begin{pmatrix} 0 & 10 & 0 & 80 \\ 0 & 10 & 10 & 20 \\ 10 & 10 & 10 & 10 \end{pmatrix}, \\ \mathcal{M} &= \{ x \in \mathbb{R}^4 : \, 4x_1 + 9x_2 + 7x_3 + 10x_4 \leq 6000, \\ & x_1 + x_2 + 3x_3 + 40x_4 \leq 4000, \\ & x \geq 0 \}, \end{split}$$

and the basic solution $x^* \simeq (1333.33, 0, 0, 66.67)^T$.

Example (Hansen, Labbé, Wendell 1989) Consider

$$egin{aligned} \mathcal{C} &= egin{pmatrix} 0 & 10 & 0 & 80 \ 0 & 10 & 10 & 20 \ 10 & 10 & 10 & 10 \end{pmatrix}, \ \mathcal{M} &= \{x \in \mathbb{R}^4: 4x_1 + 9x_2 + 7x_3 + 10x_4 \leq 6000, \ & x_1 + x_2 + 3x_3 + 40x_4 \leq 4000, \ & x \geq 0\}, \end{aligned}$$

and the basic solution $x^* \simeq (1333.33, 0, 0, 66.67)^T$.

• The linear program yields $\lambda^* \simeq (0.2343, 0, 0.7657), \ \delta^* \simeq 2.0749.$

Example (Hansen, Labbé, Wendell 1989) Consider

$$\begin{split} \mathcal{C} &= \begin{pmatrix} 0 & 10 & 0 & 80 \\ 0 & 10 & 10 & 20 \\ 10 & 10 & 10 & 10 \end{pmatrix}, \\ \mathcal{M} &= \{ x \in \mathbb{R}^4 : \, 4x_1 + 9x_2 + 7x_3 + 10x_4 \leq 6000, \\ & x_1 + x_2 + 3x_3 + 40x_4 \leq 4000, \\ & x \geq 0 \}, \end{split}$$

and the basic solution $x^* \simeq (1333.33, 0, 0, 66.67)^T$.

- The linear program yields $\lambda^* \simeq (0.2343, 0, 0.7657), \ \delta^* \simeq 2.0749.$
- The generalized linear fractional program (with G = C) yields $\lambda^* \simeq (0.2665, 0, 0.7335)$, $\delta^* \simeq 0.2195$.

Additive tolerance matrix

Compute upper matrix Δ^+ and lower matrix Δ^- such that x^* detains efficiency for every \hat{C} with $-\Delta^- < \hat{C} - C < \Delta^+$.

Additive tolerance matrix

Compute upper matrix Δ^+ and lower matrix Δ^- such that x^* detains efficiency for every \hat{C} with $-\Delta^- < \hat{C} - C < \Delta^+$.

Algorithm

Let (λ^*, δ^*) be an optimal solution to the linear program.

1. For each $i \in \{1, \ldots, s\}$ and $j \in \{1, \ldots, n\}$ set

$$\Delta_{ij}^+ := \inf_{\substack{k: \ D_{kj} < 0}} \frac{D_k \cdot C^T \lambda^*}{|D|_k \cdot e},$$
$$\Delta_{ij}^- := \inf_{\substack{k: \ D_{kj} > 0}} \frac{D_k \cdot C^T \lambda^*}{|D|_k \cdot e}.$$

Additive tolerance matrix

Compute upper matrix Δ^+ and lower matrix Δ^- such that x^* detains efficiency for every \hat{C} with $-\Delta^- < \hat{C} - C < \Delta^+$.

Algorithm

Let (λ^*, δ^*) be an optimal solution to the linear program.

1. For each $i \in \{1, \ldots, s\}$ and $j \in \{1, \ldots, n\}$ set

$$\Delta_{ij}^+ := \inf_{\substack{k: \ D_{kj} < 0}} \frac{D_k \cdot C^T \lambda^*}{|D|_k \cdot e},$$
$$\Delta_{ij}^- := \inf_{\substack{k: \ D_{kj} > 0}} \frac{D_k \cdot C^T \lambda^*}{|D|_k \cdot e}.$$

2. For each $i \in \{1, \ldots, s\}$ with $\lambda_i^* = 0$ set $\Delta_{ij}^+ := \infty \ \forall j \in \{1, \ldots, n\},$ $\Delta_{ij}^- := \infty \ \forall j \in \{1, \ldots, n\}.$

▲□▶▲□▶▲≡▶▲≡▶ ≡ のへで

Proof and example

Sketch of proof.

The possible deviations \hat{C} of C are determined so that the inequality $D\hat{C}^T\lambda^* > 0$ remains true.

Proof and example

Sketch of proof.

The possible deviations \hat{C} of C are determined so that the inequality $D\hat{C}^T\lambda^* > 0$ remains true.

Example

Reconsider our problem. The first step of Algorithm results in

$$\Delta^{+} = \begin{pmatrix} \delta^{*} & \delta^{*} & 2.2165 & \delta^{*} \\ \delta^{*} & \delta^{*} & 2.2165 & \delta^{*} \\ \delta^{*} & \delta^{*} & 2.2165 & \delta^{*} \end{pmatrix}, \quad \Delta^{-} = \begin{pmatrix} \delta^{*} & \infty & \infty & \delta^{*} \\ \delta^{*} & \infty & \infty & \delta^{*} \\ \delta^{*} & \infty & \infty & \delta^{*} \end{pmatrix},$$

where $\delta^* = 2.0749$.

Proof and example

Sketch of proof.

The possible deviations \hat{C} of C are determined so that the inequality $D\hat{C}^T\lambda^* > 0$ remains true.

Example

Reconsider our problem. The first step of Algorithm results in

$$\Delta^{+} = \begin{pmatrix} \delta^{*} & \delta^{*} & 2.2165 & \delta^{*} \\ \delta^{*} & \delta^{*} & 2.2165 & \delta^{*} \\ \delta^{*} & \delta^{*} & 2.2165 & \delta^{*} \end{pmatrix}, \quad \Delta^{-} = \begin{pmatrix} \delta^{*} & \infty & \infty & \delta^{*} \\ \delta^{*} & \infty & \infty & \delta^{*} \\ \delta^{*} & \infty & \infty & \delta^{*} \end{pmatrix},$$

where $\delta^* = 2.0749$. The second step yields

$$\Delta^{+} = \begin{pmatrix} \delta^{*} & \delta^{*} & 2.2165 & \delta^{*} \\ \infty & \infty & \infty & \infty \\ \delta^{*} & \delta^{*} & 2.2165 & \delta^{*} \end{pmatrix}, \quad \Delta^{-} = \begin{pmatrix} \delta^{*} & \infty & \infty & \delta^{*} \\ \infty & \infty & \infty & \infty \\ \delta^{*} & \infty & \infty & \delta^{*} \end{pmatrix},$$

▲□▶ ▲□▶ ▲目▶ ▲目▶ ▲目 ● ● ●

Multiplicative tolerance matrix

Compute matrices Δ^+ and Δ^- such that x^* detains efficiency for every \hat{C} with $-|G|_{ij}\Delta^-_{ij} < \hat{C}_{ij} - C_{ij} < |G|_{ij}\Delta^+_{ij}$.

Multiplicative tolerance matrix

Compute matrices Δ^+ and Δ^- such that x^* detains efficiency for every \hat{C} with $-|G|_{ij}\Delta^-_{ij} < \hat{C}_{ij} - C_{ij} < |G|_{ij}\Delta^+_{ij}$.

Algorithm

Let (λ^*, δ^*) be an optimal solution to the generalized linear fractional program.

1. For each $i \in \{1, \ldots, s\}$ and $j \in \{1, \ldots, n\}$ set

$$\Delta_{ij}^{+} := \inf_{k: \ D_{kj} < 0} \ \frac{D_k \cdot C^T \lambda^*}{|D|_k \cdot |G|^T \lambda^*},$$
$$\Delta_{ij}^{-} := \inf_{k: \ D_{kj} > 0} \ \frac{D_k \cdot C^T \lambda^*}{|D|_k \cdot |G|^T \lambda^*}.$$

2. For each $i \in \{1, \ldots, s\}$ with $\lambda_i^* = 0$ set

$$\begin{array}{l} \Delta_{ij}^+ := \infty \ \forall j \in \{1, \ldots, n\}, \\ \Delta_{ij}^- := \infty \ \forall j \in \{1, \ldots, n\}. \end{array}$$

Example

Reconsider our problem, G = C. The first step of Algorithm results in

$$\Delta^{+} = \begin{pmatrix} \delta^{*} & \delta^{*} & 0.2849 & \delta^{*} \\ \delta^{*} & \delta^{*} & 0.2849 & \delta^{*} \\ \delta^{*} & \delta^{*} & 0.2849 & \delta^{*} \end{pmatrix}, \quad \Delta^{-} = \begin{pmatrix} \delta^{*} & \infty & \infty & \delta^{*} \\ \delta^{*} & \infty & \infty & \delta^{*} \\ \delta^{*} & \infty & \infty & \delta^{*} \end{pmatrix},$$

and the second step yields

$$\Delta^{+} = \begin{pmatrix} \delta^{*} & \delta^{*} & 0.2849 & \delta^{*} \\ \infty & \infty & \infty & \infty \\ \delta^{*} & \delta^{*} & 0.2849 & \delta^{*} \end{pmatrix}, \quad \Delta^{-} = \begin{pmatrix} \delta^{*} & \infty & \infty & \delta^{*} \\ \infty & \infty & \infty & \infty \\ \delta^{*} & \infty & \infty & \delta^{*} \end{pmatrix},$$

where $\delta^* = 0.2195$.

<□> <□> <□> <□> <=> <=> <=> <=> <<

An interval MOLP problem

 $\max_{x\in\mathcal{M}} Cx,$

where C varies in $C' = \{C \subseteq \mathbb{R}^{s \times n} : \underline{C} \leq C \leq \overline{C}\}.$

◆□ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

An interval MOLP problem

 $\max_{x\in\mathcal{M}} Cx,$

where C varies in $C' = \{C \subseteq \mathbb{R}^{s \times n} : \underline{C} \leq C \leq \overline{C}\}.$

Definition

- A vector x ∈ M is possibly efficient if it is efficient for some C ∈ C^I.
- ► A vector x ∈ M is necessarily efficient if it is efficient for every C ∈ C¹.

An interval MOLP problem

 $\max_{x\in\mathcal{M}} Cx,$

where C varies in $C' = \{C \subseteq \mathbb{R}^{s \times n} : \underline{C} \leq C \leq \overline{C}\}.$

Definition

- A vector x ∈ M is possibly efficient if it is efficient for some C ∈ C^I.
- ► A vector x ∈ M is necessarily efficient if it is efficient for every C ∈ C'.

Let us denote $C^c := \frac{1}{2} \cdot (\overline{C} + \underline{C})$ and consider the MOLP problem

$$\max_{x \in \mathcal{M}} C^c x$$

An interval MOLP problem

 $\max_{x\in\mathcal{M}} Cx,$

where C varies in $C' = \{C \subseteq \mathbb{R}^{s \times n} : \underline{C} \leq C \leq \overline{C}\}.$

Definition

- A vector x ∈ M is possibly efficient if it is efficient for some C ∈ C^I.
- ► A vector x ∈ M is necessarily efficient if it is efficient for every C ∈ C'.

Let us denote $C^c := \frac{1}{2} \cdot (\overline{C} + \underline{C})$ and consider the MOLP problem

$$\max_{x \in \mathcal{M}} C^c x$$

Let (λ^*, δ^*) be an optimal solution to the linear (or generalized linear fractional) program.

Theorem

The vector x^* is necessarily efficient if $DC^{\prime}\lambda^* > 0$.

Theorem

The vector x^* is necessarily efficient if $DC^{\prime}\lambda^* > 0$.

Example

Consider the interval matrix

$$C' = \begin{pmatrix} [-1,1] & [8,12] & [-1,1] & [75,85] \\ [-1,1] & [8,12] & [8,12] & [17,23] \\ [8,12] & [8,12] & [8,12] & [8,12] \end{pmatrix}$$

The feasible set \mathcal{M} and its point x^* is defined as before.

Theorem

The vector x^* is necessarily efficient if $DC^{\prime}\lambda^* > 0$.

Example

Consider the interval matrix

$$\mathcal{C}' = egin{pmatrix} [-1,1] & [8,12] & [-1,1] & [75,85] \ [-1,1] & [8,12] & [8,12] & [17,23] \ [8,12] & [8,12] & [8,12] & [8,12] \end{pmatrix}$$

The feasible set \mathcal{M} and its point x^* is defined as before. The midpoint matrix is

$$C^{c} = \begin{pmatrix} 0 & 10 & 0 & 80 \\ 0 & 10 & 10 & 20 \\ 10 & 10 & 10 & 10 \end{pmatrix}.$$

Theorem

The vector x^* is necessarily efficient if $DC'\lambda^* > 0$.

Example

Consider the interval matrix

$$\mathcal{C}' = egin{pmatrix} [-1,1] & [8,12] & [-1,1] & [75,85] \ [-1,1] & [8,12] & [8,12] & [17,23] \ [8,12] & [8,12] & [8,12] & [8,12] \end{pmatrix}$$

The feasible set \mathcal{M} and its point x^* is defined as before. The midpoint matrix is

$$C^{c} = \begin{pmatrix} 0 & 10 & 0 & 80 \\ 0 & 10 & 10 & 20 \\ 10 & 10 & 10 & 10 \end{pmatrix}.$$

Then $\lambda^* \simeq (0.2343, 0, 0.7657)$ (or $\lambda^* \simeq (0.2665, 0, 0.7335)$), $DC'\lambda^* > 0$ and hence x^* is necessarily efficient.

The End.

< ロ > < 回 > < 三 > < 三 > < 三 > < ○ < ○