

Routing games

Setup

- $G = (V, E)$

- $(s_1, t_1) \dots (s_k, t_k) \rightarrow$ commodities
 ↳ source sink pairs

- r_1, \dots, r_k
 ↳ demands

P_i ... set of paths
 from s_i to t_i

$P \dots \bigcup_i P_i$



a flow f is a non-ve
vector indexed by P

ie. for each $P \in P_i$

f_P ... amt of traffic
sent from s_i to t_i
along P

feasible if

$$\forall i \quad \sum_{P \in P_i} f_P = r_i$$

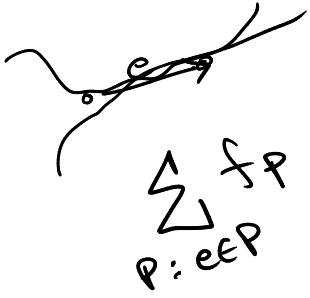
Cost.

Each edge $e \in E$ has a cost function

$$c_e : \mathbb{R}^+ \rightarrow \mathbb{R}^+$$

cts.
non-negative
non-decreasing

↳ for eg. maps amt of traffic → delay



$$c_e(0) \neq 0$$

cost of a path

$$C_p(f) = \sum_{e \in P} c_e(f_e)$$

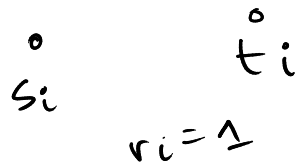
$$f_p \geq 0$$



$$\sum_{P \in \mathcal{P}: e \in P} f_p$$

Non-atomic

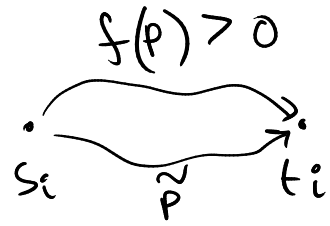
↳ each commodity is infinitely divisible



flow is equilibrium iff

$$\forall i \nexists P, \tilde{P} \in \mathcal{P}_i \text{ st } f_p > 0$$

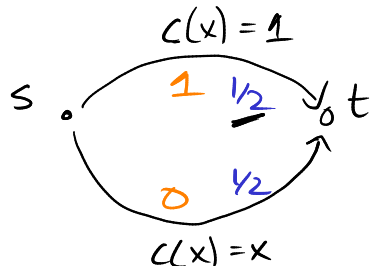
$$C_p(f) \leq C_{\tilde{P}}(f)$$



$$C_{\tilde{P}}(f) < C_P(f)$$

↳ "this is fastest route in current traffic"

Pigou's example



$$\frac{1}{2} \cdot 1 + \frac{1}{2} \cdot \frac{1}{2} = \frac{3}{4}$$

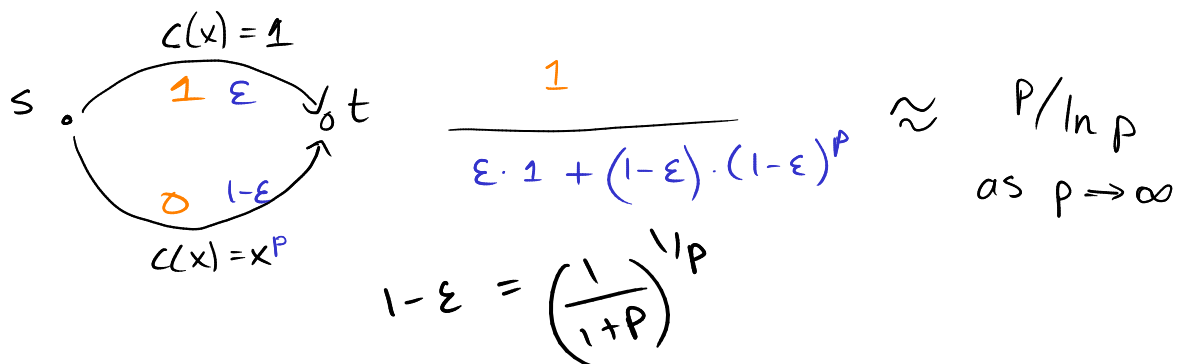
Social cost

$$\begin{aligned}
 C(f) &= \sum_{P \in P} C_P(f) \cdot f_P = \sum_{e \in E} c_e(f_e) \cdot f_e \\
 &= \sum_{P \in P} f_P \sum_{e \in P} c_e(f_e) \\
 &= \sum_e c_e(f_e) \sum_{\substack{P \in P \\ e \in P}} f_P \\
 C(f) &= \sum_e c_e(f_e) f_e
 \end{aligned}$$

Optimal flow: minimizes $C(f)$

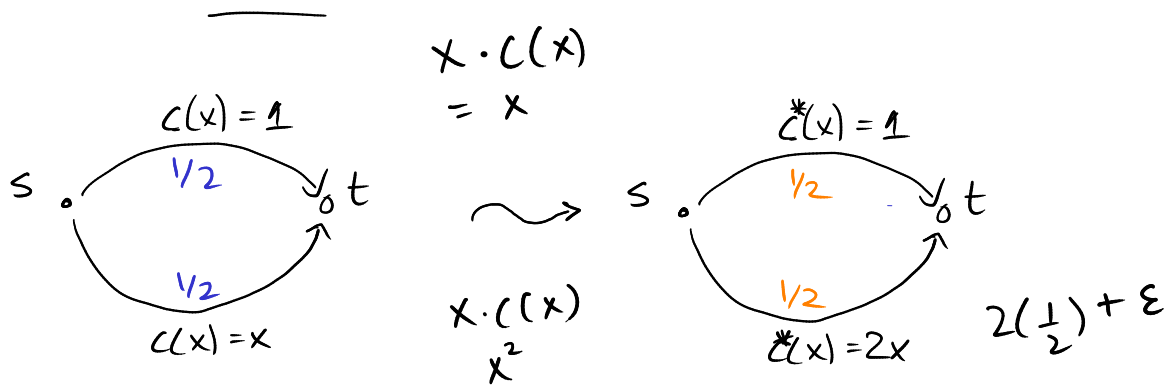
Price of anarchy

$\frac{\text{worst cost of equilibrium flow}}{\text{cost of optimal flow}}$
← can use any eq. flow since they all have same cost
} non-trivial



$$\text{then } C(\tilde{f}) \approx C(f) + \underbrace{(C_{\tilde{P}}^* - C_P^*)(f)}_{< 0} \cdot \varepsilon$$

$$\Rightarrow C(\tilde{f}) < C(f)$$



equilibrium flows are just opt. flows of a different network

👁️ invert claim which used first order derivative.

want $h_e(x) \rightarrow t \cdot h_e'(x) = c_e(x)$
 def: $h_e(x) = \int_0^x c_e(y) dy$



f is an equilibrium flow for (G, r, c) if it is global minima of:

$$\Phi(f) = \sum_{e \in E} \int_0^{f_e} c_e(x) dx$$

$\underbrace{\int_0^{f_e} c_e(x) dx}_{x \tilde{c}(x)}$

$\left. \vphantom{\int_0^{f_e} c_e(x) dx} \right\} (G, r, \tilde{c})$

$$f, \tilde{f}$$

$$\tilde{c}(f) = \tilde{c}(\tilde{f})$$

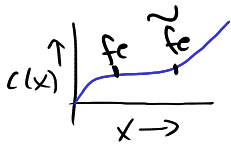
$$C(f) \stackrel{?}{=} C(\tilde{f})$$

Thm 1 a. Equilibrium always exists

b. It is "essentially unique". f, \tilde{f}

ie. for f, \tilde{f} eq

$$c(f) = c(\tilde{f})$$



$$c_e(f_e) = c_e(\tilde{f}_e) \quad \text{for each } e \in E$$

$$f_e = \tilde{f}_e$$

Pf.

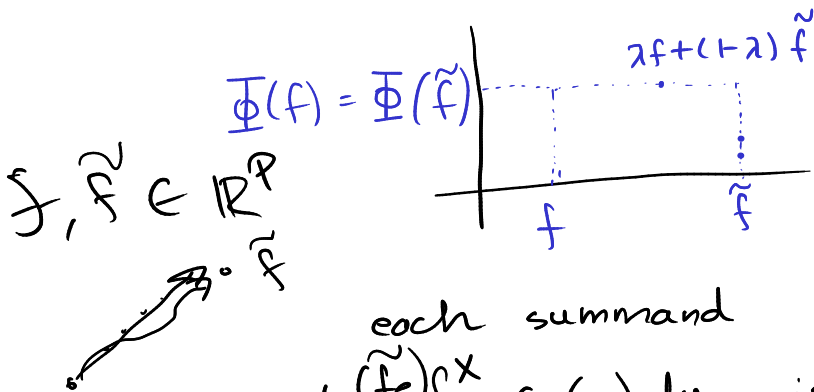
a. feasible solutions of (G, r, c) form a compact set

c_e cts $\Rightarrow \Phi$ cts

$\Rightarrow \Phi$ achieves minimum over set of feasible solutions

b. Φ is cvx., since $c_e(x)$ are non-decreasing

suppose f, \tilde{f} are two different equilibria



$$\Phi(\lambda f + (1-\lambda)\tilde{f})$$

$$\leq \approx =$$

$$\lambda \Phi(f) + (1-\lambda) \Phi(\tilde{f})$$

$$\Phi(f) = \Phi(\tilde{f})$$

each summand $c_e(\tilde{f}_e) \int_0^x c_e(y) dy$ is cvx.

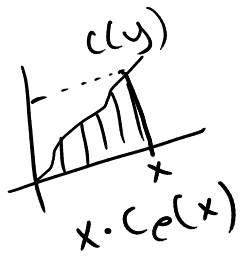
$\Rightarrow \int_0^x c_e(y) dy$ linear from f_e to \tilde{f}_e .

$\Rightarrow c_e(y)$ const. from f_e to \tilde{f}_e .

$$c_e(f_e) = c_e(\tilde{f}_e) \quad \square$$

Thm 2. (Potential fn upper bound) $\leq x \cdot c(x)$

(G, r, c) s.t. $x \cdot c(x) \leq \gamma \cdot \int_0^x c(y) dy$
 then price of anarchy $\leq \gamma$



Pf.

Let f, f^* be eq. and opt resp.

$$C(f) \leq \gamma \underbrace{\Phi(f)}_{\sum_{c \in E} \int_0^f c(x) dx}$$

$$\leq \gamma \underbrace{\Phi(f^*)}$$

$$\leq \gamma C(f^*) \quad \square$$

eg. if $c(x)$ is polynomial of degree p with non neg. coeff.

$$\int_0^x y^p dy = \frac{1}{p+1} \cdot x^{p+1}$$

$$x \cdot c(x) \leq (p+1) \int_0^x c(y) dy \text{ for } x \geq 0$$

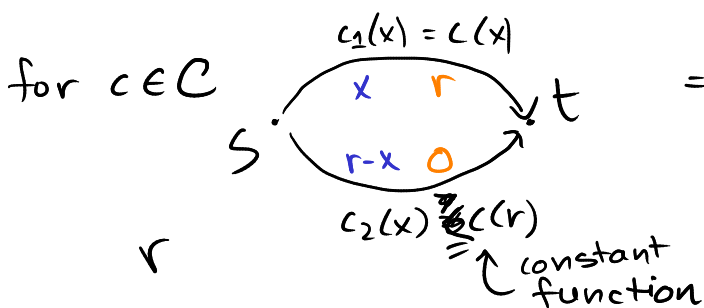
Thm 2 \Rightarrow price of anarchy $\leq p+1$.

$p / \ln p$

Defn. Pigou bound

for C a set of cost functions + must contain all constants

$$\alpha(C) = \sup_{c \in C} \sup_{x, r \geq 0} \frac{r \cdot c(r)}{x \cdot c(x) + (r-x)c(r)}$$



\Rightarrow lower bounds price of anarchy for cost functions chosen from C .

Prop. (Variational ineq. characterization)

f is eq. flow for (G, r, c) iff

$$\sum_{e \in E} c_e(f_e) f_e \leq \sum_{e \in E} c_e(f_e^*) f_e^*$$

for any feasible f^* .

Pf. $H_f(f^*) = \sum_{i=1}^k \sum_{P \in P_i} c_P(f) f_P^* = \sum_{e \in E} c_e(f_e) f_e^*$

want: f minimizes H_f

let f^* be opt for H_f .
 $f_p^* > 0 \Rightarrow c_P(f)$ minimum over $P \in P_i$

f satisfies these conditions iff it is an equilibrium flow.

Thm 3. \mathcal{C} ... set of cost fns. + constant fns.

$\alpha(\mathcal{C})$... price bound for \mathcal{C}

(G, r, c) ... nonatomic instance with $c_e \in \mathcal{C}$ for each $e \in E$.

Then price of anarchy $\leq \alpha(\mathcal{C})$

Pf. let f, f^* be eq., opt.

$$C(f^*) = \sum_{e \in E} c_e(f_e^*) f_e^*$$

$$\alpha(c) \geq \sup_{c_e} \sup_{x, r \geq 0} \frac{f_e \cdot c_e(f_e)}{f_e^* c_e(f_e^*) + (f_e - f_e^*) c_e(f_e)} \quad \left(\begin{array}{l} \text{subst.} \\ x = f_e^*, r = f_e \end{array} \right)$$

$$\Rightarrow \underbrace{f_e^* c_e(f_e^*)}_{C(f^*)} \geq \frac{1}{\alpha(c)} \underbrace{f_e c_e(f_e) + (f_e^* - f_e) c_e(f_e)}_{C(f)}$$

$$\Rightarrow C(f^*) = \sum_{e \in E} \dots \geq \sum_{e \in E} \dots \quad \left\{ \begin{array}{l} \sum_e f_e^* c_e(f_e) \\ - \sum_e f_e c_e(f_e) > 0 \end{array} \right.$$

$$C(f^*) \geq \frac{1}{\alpha(c)} C(f)$$

$$\frac{C(f)}{\alpha(c) C^*(f)} \leq 1$$

$$\frac{C(f)}{C(f^*)} \leq \alpha(c)$$

Reducing anarchy.

Marginal Cost pricing

Idea. $c_e \rightsquigarrow \tilde{c}_e^z(x) = c_e(x) + \tau_e$

Principle. τ_e should be $f_e \cdot c'_e(f_e)$
for f a feasible flow

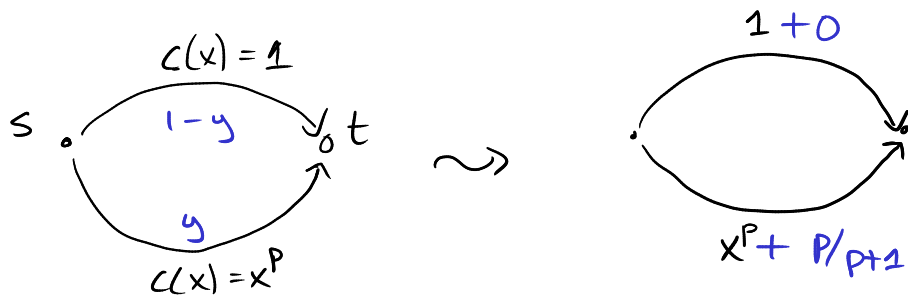
for f^* opt, $\tau_e = f_e^* \cdot c'_e(f_e^*)$
is "missing term" of marginal cost fn.

Thm. f^* opt. for (G, r, c) ,
let $\tau_e = f_e^* c'_e(f_e^*)$
Then f^* is eq. for $(G, r, c + \tau)$

$$C = \left\{ \begin{array}{l} \text{constants,} \\ ax + b, \text{ for } a, b > 0 \end{array} \right\}$$

$$\alpha(C) = \sup_{c \in C} \sup_{x, r \geq 0}$$

fg.



$$y = \left(\frac{1}{1+p}\right)^{1/p}$$

Thm: If f is an equilibrium flow for (G, r, c) and f^* is feasible for $(G, 2r, c)$ then $C(f) \leq C(f^*)$

Pf. Let $d_i = \min \text{ cost path from } s_i \text{ to } t_i \text{ under } f$.

$$C(f) = \sum_{i=1}^k d_i r_i$$

Idea. make new cost fns. \bar{c}_e s.t.

- i) can lower bound $\bar{C}(f^*)$ in terms of $C(f)$
- ii) \bar{c}_e apx c_e

$$\text{set } \bar{c}_e(x) = \max \{ c_e(f_e), c_e(x) \}$$

$$\text{Note that } \bar{C}(f^*) \geq C(f^*)$$

$$\text{while } \bar{C}(f) = C(f).$$

$$\forall e. \quad \bar{c}_e(x) - c_e(x) = 0 \quad \text{for } x \geq f_e$$

$$\quad \quad \quad \quad \quad \leq c_e(f_e) \quad \text{for } x < f_e$$

$$\text{so. } x (\bar{c}_e(x) - c_e(x)) \leq f_e c_e(f_e)$$

$$\text{for } x \geq 0.$$

Thus

$$\begin{aligned}\bar{C}(f^*) - C(f^*) &= \sum_{e \in E} f_e^* (\bar{c}_e(f_e^*) - c_e(f_e)) \\ &\leq \sum_{e \in E} f_e c_e(f_e) = C(f) \\ &\quad - \textcircled{1}\end{aligned}$$

Next, lower bound $\bar{C}(f^*)$

by definition

$$\bar{c}_e(x) \geq c_e(f_e)$$

\Rightarrow min-cost path from s_i to t_i costs $\geq d_i$

$$\begin{aligned}\text{Thus } \bar{C}(f^*) &= \sum_{P \in \mathcal{P}} \bar{C}_P(f^*) f_P^* \\ &\geq \sum_{i=1}^K \sum_{P \in \mathcal{P}_i} d_i f_P^* \\ &= \sum_{i=1}^K 2r_i d_i = 2C(f) \\ &\quad - \textcircled{2}\end{aligned}$$

Combining $\textcircled{1}$ and $\textcircled{2}$

$$\underbrace{\bar{C}(f^*) - C(f^*)}_{\geq 2C(f)} \leq C(f)$$

$$\Rightarrow C(f) \leq C(f^*) \quad \square$$

Corr. (G, r, c) instance

$$\tilde{c}_e(x) := c_e(x/2) / 2$$

Let \tilde{f} an equilibrium flow for (G, r, \tilde{c}) , with cost $\tilde{C}(\tilde{f})$

Let f^* be any feasible flow for (G, r, c)

$$\text{Then } \tilde{C}(\tilde{f}) \leq C(f^*)$$

Pf.

Double f^* to get feasible flow for $(G, 2r, \cdot)$

$$\text{Now } \tilde{C}(f) \leq \tilde{C}(2f^*)$$

$$\begin{aligned} \text{but } \tilde{C}(2f^*) &= \sum_e 2f_e^* \cdot \tilde{c}_e(2f_e^*) \\ &= \sum_e f_e^* c_e(f_e^*) \\ &= C(f^*) \end{aligned}$$

Atomic Selfish routing

$$(G, r, c)$$

but flows are now "all or nothing"

ie.

$$f_P^{(i)} = r_i \text{ for exactly one } P \in \mathcal{P}_i$$

and

$$f_{\tilde{P}}^{(i)} = 0 \quad \forall \tilde{P} \neq P$$

Equilibrium :

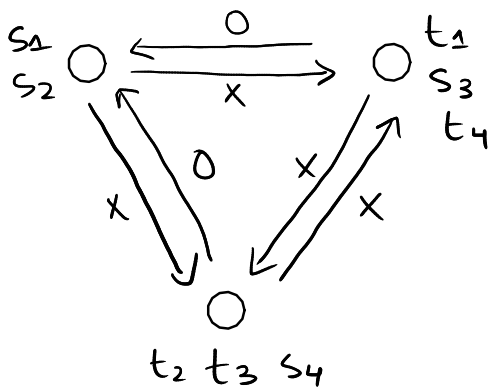
f is eq. flow iff

$$\forall i \quad \forall P \in \mathcal{P}_i \text{ st. } f_P > 0,$$

$$C_P(f) \leq C_{\tilde{P}}(\tilde{f})$$

where $\tilde{f} = f + \begin{pmatrix} 0 \\ \vdots \\ -r_i \\ +r_i \\ \vdots \\ 0 \end{pmatrix}$

$\leftarrow P$
 $\leftarrow \tilde{P}$

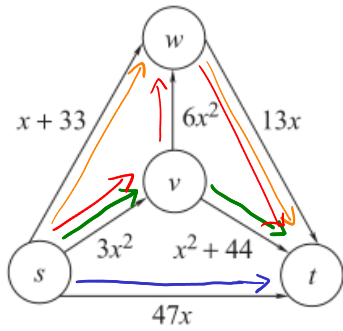


price of anarchy 2.5

opt.
every one uses
1-hop path
cost 4

bad eq.
everyone uses
2-hop path
cost 10

Equilibrium does not always exist.



$$P_1: s \rightarrow t$$

$$P_2: s \rightarrow v \rightarrow t$$

$$P_3: s \rightarrow w \rightarrow t$$

$$P_4: s \rightarrow v \rightarrow w \rightarrow t$$

two players

$$s \rightsquigarrow t, r_1 = 1$$

$$s \rightsquigarrow t, r_2 = 2$$

1. if player 2 takes P_1 or P_2
player 1 responds

P_4

2. if player 2 takes P_3 or P_4
player 1 responds

P_1

Thm.

Equilibrium exists if all $r_i = R$

Pf.

suppose $R = 1$

$$\Phi_a(f) = \sum_{e \in E} \sum_{i=1}^{f_e} c_e(i)$$

(discrete version of $\Phi(f) = \sum_{e \in E} \int_0^{f_e} c_e(x) dx$)

\rightarrow finite # of feasible f

$\Rightarrow \Phi_a$ is minimized by some f

claim. f is equilibrium for (G, r, c)

Pf.

suppose $\exists P, \tilde{P} \in P_i$

$$\text{s.t. } C_P(f) > C_{\tilde{P}}(\tilde{f})$$

then can reduce Φ_a by switching to \tilde{f} .

$$\begin{aligned} 0 &< c_P(f) - c_{\tilde{P}}(\tilde{f}) \\ &= \sum_{e \in \tilde{P} \setminus P} c_e(f_{e+1}) - \sum_{e \in \tilde{P} \setminus P} c_e(f_e) \end{aligned}$$

mysterious
remark: "best-response dynamics" converge

Thm: Eq. exists if cost functions are affine.

Thm: If (G, r, c) is atomic instance with affine costs,
price of anarchy $\leq \frac{3+\sqrt{5}}{2} \approx 2.618$

if affine + all r_i equal,
price of anarchy $\leq 5/2$ (matches example)