# **COOPERATIVE GAME THEORY**

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■  $C(v) = \{x \in I(v) \mid x(S) \ge v(S) \text{ pro } S \subseteq N\}$  ... core of a game ■ How to choose  $x \in C(v)$ ?

$$\begin{array}{l} x(S) \geq v(S) \\ x(S) + e = v(S) \\ e \leq 0 \\ \text{size of } e \text{ represents } dissatisfaction \text{ of players over } x \\ e(S,x) := v(S) - x(S) \dots \text{ excess of coalition } S \text{ over } x \\ \text{min } e(S,x) \implies \max x(S) \\ e(V) = \{x \in \mathcal{I}(V) \mid e(S,x) \leq 0 \text{ pro } S \subseteq N\} \end{array}$$

■ 
$$e(S, x) := v(S) - x(S)$$
 ... **excess** of coalition *S* over *x*  
■  $\theta(x) = (e(S_1, x), e(S_2, x), \dots, e(S_{2^n-1}, x))$  ... vector of excesses  
►  $e(S_i, x) \ge e(S_j, x)$  pro  $i \le j$   
■  $\theta(x) \preceq_{lex} \theta(y)$  ... lexicographic ordering  
1. exists  $k: \theta_k(x) < \theta_k(y)$   
2. for  $\ell < k: \theta_\ell(x) = \theta_\ell(y)$ 

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■ 
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 ... lexicographic ordering

## Nucleolus

For a cooperative game (*N*, *v*), the **nucleolus**  $\eta(v)$ 

$$\eta(\mathbf{v}) \coloneqq \{ \mathbf{x} \in \mathcal{I}(\mathbf{v}) \mid \theta(\mathbf{x}) \preceq_{lex} \theta(\mathbf{y}) \text{ for } \mathbf{y} \in \mathcal{I}(\mathbf{v}) \}.$$

Non-emptyness of the nucleolus

For a cooperative game (N, v), it holds  $\mathcal{I}(v) \neq \emptyset \implies \eta(v) \neq \emptyset.$ 

Proof: Iterative usage of the Extreme value theorem

#### Extreme value theorem

A continuous function over compact set  $\mathcal{M}$  attains its minimum. Moreover, the set of all minima forms a compact set  $\mathcal{M}$ .

- $e(S, \bullet)$  is continuous for  $S \subseteq N \implies \theta_t(\bullet)$  is continuous
- $\blacksquare X_{\mathsf{o}} \coloneqq \mathcal{I}(\mathsf{v})$
- $X_t := \{ x \in X_{t-1} \mid \theta_t(x) \le \theta_t(y) \text{ for } y \in X_{t-1} \}$  $t = 1, \dots 2^n - 1$

#### Uniqueness of the nucleolus

Nucleolus is a single-point solution concept.

Proof: " $\theta(\mathbf{x}) = \theta(\mathbf{y}) \implies \mathbf{x} = \mathbf{y}$ "  $\mathbf{0} \le \alpha \le 1$   $\mathbf{x}, \mathbf{y} \in \eta(\mathbf{v}) \implies \theta(\mathbf{x}) = \theta(\mathbf{y})$ 1.  $\theta(\alpha \mathbf{x} + (1 - \alpha)\mathbf{y}) \succeq_{lex} \theta(\mathbf{x}) = \theta(\mathbf{y})$ 2.  $\theta(\alpha \mathbf{x} + (1 - \alpha)\mathbf{y}) \preceq_{lex} \theta(\mathbf{x}) = \theta(\mathbf{y})$ 3.  $\theta(\alpha \mathbf{x} + (1 - \alpha)\mathbf{y}) = \theta(\mathbf{x}) = \theta(\mathbf{y})$ 4.  $\mathbf{x} = \mathbf{y}$ 

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$$\mathbf{x}, \mathbf{y} \in \eta(\mathbf{v}) \implies \theta(\mathbf{x}) = \theta(\mathbf{y})$$
1.  $\theta(\alpha \mathbf{x} + (1 - \alpha)\mathbf{y}) \succeq_{lex} \theta(\mathbf{x}) = \theta(\mathbf{y})$ 
2.  $\theta(\alpha \mathbf{x} + (1 - \alpha)\mathbf{y}) \preceq_{lex} \theta(\mathbf{x}) = \theta(\mathbf{y})$ 

$$\mathbf{b} \quad \theta(\alpha \mathbf{x} + (1 - \alpha)\mathbf{y}) \preceq_{lex} \alpha \theta(\mathbf{x}) + (1 - \alpha)\theta(\mathbf{y})$$

$$\mathbf{b} \quad home \text{ exercise}$$
3.  $\theta(\alpha \mathbf{x} + (1 - \alpha)\mathbf{y}) = \theta(\mathbf{x}) = \theta(\mathbf{y})$ 
4.  $\mathbf{x} = \mathbf{y}$ 

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1.  $\theta(\alpha \mathbf{x} + (1 - \alpha)\mathbf{y}) \succeq_{lex} \theta(\mathbf{x}) = \theta(\mathbf{y})$ 
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$$\succeq_{lex} \text{ is antisymmetric ordering}$$
4.  $\mathbf{x} = \mathbf{y}$ 

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Proof: " $\theta(\mathbf{x}) = \theta(\mathbf{y}) \implies \mathbf{x} = \mathbf{y}$ "  $\blacksquare$  0 <  $\alpha$  < 1  $\blacksquare \mathbf{X}, \mathbf{y} \in \eta(\mathbf{v}) \implies \theta(\mathbf{X}) = \theta(\mathbf{y})$ 1.  $\theta(\alpha \mathbf{X} + (1 - \alpha)\mathbf{y}) = \theta(\mathbf{X}) = \theta(\mathbf{y})$ 2. **X** = **V**  $\bullet \ \theta(\alpha \mathbf{X} + (1 - \alpha)\mathbf{V}) = \alpha \mathbf{a} + (1 - \alpha)\mathbf{b}$  $\blacksquare$  S<sub>1</sub>, S<sub>2</sub>,..., S<sub>2<sup>n</sup>-1</sub> ... pořadí koalic v  $\theta(\alpha \mathbf{X} + (1 - \alpha)\mathbf{V})$  $a = (e(S_1, \mathbf{X}), e(S_2, \mathbf{X}), \dots, e(S_{2^n-1}, \mathbf{X}))$  $b = (e(S_1, \mathbf{v}), e(S_2, \mathbf{v}), \dots, e(S_{2^n-1}, \mathbf{v}))$  $\blacktriangleright \theta(\mathbf{x}) = \mathbf{a}, \theta(\mathbf{y}) = \mathbf{b}$  $\alpha = 1, \alpha = 0$ •  $e(S_i, \mathbf{x}) = e(S_i, \mathbf{y})$  pro  $i = 1, ..., 2^n - 1$  $e(\{i\}, \mathbf{x}) = e(\{i\}, \mathbf{y})$  $\mathbf{v}(i) - \mathbf{x}_i = \mathbf{v}(i) - \mathbf{v}_i$  $\mathbf{X}_i = \mathbf{V}_i$ 

#### Nucleolus is a core selector

For a cooperative game (N, v), if it holds  $C(v) \neq \emptyset$  then  $\eta(v) \subseteq C(v)$ .

Proof:  $x \notin C(v)$  in contradiction with lexicographical minimality

- $\blacksquare \ \mathbf{X} \in \eta(\mathbf{V}) \setminus \mathcal{C}(\mathbf{V}) \implies \exists \mathbf{S} \subseteq \mathbf{N} : \mathbf{e}(\mathbf{S}, \mathbf{X}) > \mathbf{O}$
- pro  $\boldsymbol{y} \in \mathcal{C}(\boldsymbol{v}) : \boldsymbol{e}(\boldsymbol{S}, \boldsymbol{y}) \leq \boldsymbol{o}$
- $\bullet \theta(\mathbf{x}) \succ_{lex} \theta(\mathbf{y})$  $\bullet \theta_1(\mathbf{x}) > \theta_1(\mathbf{y})$

#### COMPUTATION OF THE NUCLEOLUS

We can use the proof of non-emptyness  $\blacktriangleright X_0 := \mathcal{I}(v)$  $X_t := \{ \mathbf{x} \in X_{t-1} \mid \theta_t(\mathbf{y}) \ge \theta_t(\mathbf{x}) \text{ pro } \mathbf{y} \in X_{t-1} \}$  $t = 1, \dots, 2^n - 1$  $\blacksquare LP(\mathbf{O}) = \begin{cases} \min_{\mathbf{x} \in X_{\mathbf{O}}, \alpha_{\mathbf{O}} \in \mathbb{R}} & \alpha_{\mathbf{O}} \\ \text{subject to} & \alpha_{\mathbf{O}} \ge \mathbf{x}(\mathbf{S}) - \mathbf{v}(\mathbf{S}) \\ & \forall \mathbf{S} \in 2^{N} \setminus \{\emptyset\} \end{cases}$  $\blacktriangleright$  X<sub>1</sub> ... set of optimal solutions LP(0)  $\blacktriangleright \mathcal{B}_1 = \{S \subseteq 2^N \setminus \{\emptyset\} \mid e(S, \mathbf{x}) = \alpha_0 \text{ pro } \forall \mathbf{x} \in \mathbf{X}_1\}$  $\blacksquare LP(t) = \begin{cases} \min_{\mathbf{x}\in X_t, \alpha_t \in \mathbb{R}} & \alpha_t \\ \text{subject to} & \alpha_t \ge \mathbf{x}(\mathbf{S}) - \mathbf{v}(\mathbf{S}) \\ & \forall \emptyset \neq \mathbf{S} \in 2^N \setminus \mathcal{B}_t \end{cases}$  $\blacktriangleright$  X<sub>t+1</sub> ... set of optimal solutions LP(t)  $\blacktriangleright \mathcal{B}_{t+1} = \{S \in 2^n \setminus (\mathcal{B}_t \cup \{\emptyset\}) \mid e(S, x) = \alpha_t \text{ pro } \forall x \in X_t\} \cup \mathcal{B}_t$ 

- $LP(0), LP(1), ..., LP(2^n 2)$ 
  - From the proof of non-emptyness theorem:  $X_t \neq \emptyset$
  - at most  $2^n 1$  LPs

if  $X_t$  contains single vector  $\implies$  it is the nucleolus

- there are more efficient algorithms for special classes of games
  - a lot of research in this nowadays

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#### Nucleolus

**Nucleolus** is a single-point solution concept, which is defined for every game with **non-empty imputation set**. Moreover, if the core of this game is non-empty, the nucleolus is contained by it. In general, it is possible to compute the nucleolus by a system of up to  $2^n - 1$  linear programs. Therefore, one of the most important open problem in cooperative game theory is to find efficient algorithms when restricted to special classes of games.