# Algorithmic game theory

#### Martin Balko

#### 4th lecture

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# Nash equilibria in bimatrix games

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- The best response condition: If x and y are mixed strategy vectors of players 1 and 2, respectively, then x is a best response to y iff

$$\forall i \in A_1 : x_i > 0 \Longrightarrow M_{i,*}y = \max\{M_{k,*}y : k \in A_1\}.$$

Analogously, y is a best response to x iff

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• Today, we reveal a geometric structure behind finding NE in bimatrix games and show one of the fastest known algorithms for this task.

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- Thus, points of  $\overline{P}$  and  $\overline{Q}$  are the mixed strategies with the "upper envelope" of expected payoffs of the other player.

Now, we define the labels of points from the best response polyhedra

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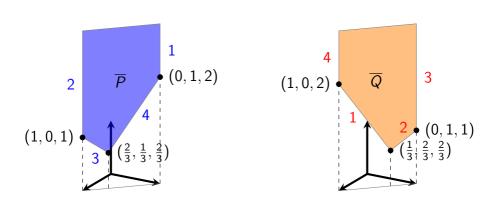
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- Each point from  $\overline{P}$  or  $\overline{Q}$  may have more labels.

Best response polyhedra  $\overline{P}$  and  $\overline{Q}$  for the Battle of sexes

# Best response polyhedra $\overline{P}$ and $\overline{Q}$ for the Battle of sexes



$$\overline{P} = \{ (x_1, x_2, v) \in \mathbb{R}^2 \times \mathbb{R} : x_1, x_2 \ge 0, x_1 + x_2 = 1, x_1 \le v, 2x_2 \le v \}$$

$$\overline{Q} = \{(y_3, y_4, u) \in \mathbb{R}^2 \times \mathbb{R} : y_3, y_4 \ge 0, y_3 + y_4 = 1, 2y_3 \le u, y_4 \le u\}.$$

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A strategy profile  $\underline{s}$  with  $\underline{u} = u_1(s)$  and  $\underline{v} = u_2(s)$  is NE of G iff the pair  $((x, v), (y, u)) \in \overline{P} \times \overline{Q}$  is completely labeled, that is, every label  $\underline{i} \in A_1 \cup A_2$  appears as a label of either (x, v) or (y, u).

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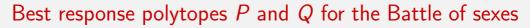
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Similarly, the best response polytope for player 2 in G is a polytope

$$Q = \{ y \in \mathbb{R}^n \colon y \ge \mathbf{0}, My \le \mathbf{1} \}.$$



## Best response polytopes P and Q for the Battle of sexes

$$(0, \frac{1}{2}) \xrightarrow{P} (1, \frac{1}{2})$$

$$(0, 0) \xrightarrow{Q} (\frac{1}{2}, 1)$$

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$$P = \{(x_1, x_2) \in \mathbb{R}^2 \colon x_1, x_2 \ge 0, x_1 \le 1, 2x_2 \le 1\}$$

$$Q = \{(y_3, y_4) \in \mathbb{R}^2 \colon y_3, y_4 \ge 0, 2y_3 \le 1, y_4 \le 1\}.$$

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#### Corollary 2.30

A strategy profile  $(s_1, s_2)$  with mixed strategy vectors x and y is NE of G if and only if the point  $(x/u_2(s), y/u_1(s)) \in P \times Q \setminus \{(\mathbf{0}, \mathbf{0})\}$  is completely labeled.

Recall that a bimatrix game is nondegenerate if there are at most k
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  - $\circ$  By Corollary 2.30, only vertices of P and Q can be NE.
- $\Rightarrow$  Algorithm for finding NE: check all pairs of vertices and their labels!

#### **Algorithm 0.2:** VERTEX ENUMERATION(G)

```
Input: A nondegenerate bimatrix game G.

Output: All Nash equilibria of G.

for each pair (x, y) of vertices from (P \setminus \{\mathbf{0}\}) \times (Q \setminus \{\mathbf{0}\})

\{for (x, y) \text{ is completely labeled}, for the return <math>(x/(\mathbf{1}^{\top}x), y/(\mathbf{1}^{\top}y)) \text{ as a Nash equilibrium}\}
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#### **Algorithm 0.3:** VERTEX ENUMERATION(G)

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Input: A nondegenerate bimatrix game G.

Output: All Nash equilibria of G.

for each pair (x, y) of vertices from (P \setminus \{\mathbf{0}\}) \times (Q \setminus \{\mathbf{0}\})

\{for (x, y) \text{ is completely labeled}, \}

then return (x/(\mathbf{1}^{\top}x), y/(\mathbf{1}^{\top}y)) as a Nash equilibrium
```

• All vertices of a simple polytope in  $\mathbb{R}^d$  with v vertices and N defining inequalities can be found in time O(dNv) (Avis and Fukuda).

#### Algorithm 0.4: VERTEX ENUMERATION(G)

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- All vertices of a simple polytope in  $\mathbb{R}^d$  with v vertices and N defining inequalities can be found in time O(dNv) (Avis and Fukuda).
- However, if m = n, the best response polytopes can have  $c^n$  vertices for some constant c with 1 < c < 2.9.

# Polytopes can be weird and complex!

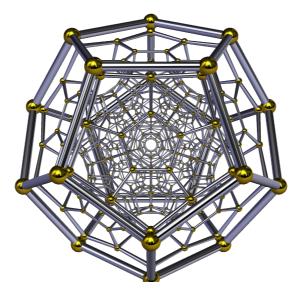


Figure: Schlegel diagram for the 120-cell.

Source: https://en.wikipedia.org/

#### **Algorithm 0.5:** Vertex enumeration(G)

```
Input: A nondegenerate bimatrix game G.

Output: All Nash equilibria of G.

for each pair (x, y) of vertices from (P \setminus \{\mathbf{0}\}) \times (Q \setminus \{\mathbf{0}\})

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- All vertices of a simple polytope in  $\mathbb{R}^d$  with v vertices and N defining inequalities can be found in time O(dNv) (Avis and Fukuda).
- However, if m = n, the best response polytopes can have  $c^n$  vertices for some constant c with 1 < c < 2.9.
- We can speed up the search by performing a walk on  $(P \setminus \{0\}) \times (Q \setminus \{0\})$  guided by the labels.

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Figure: Carlton E. Lemke (1920–2004) and J. T. Howson (1937–2022).

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- The algorithm starts at (0,0) and alternately follows edges of P and Q.
- At the first step, it chooses a label  $k \in A_1 \cup A_2$  and drops it.

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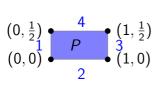
- Since P is simple and dim(P) = m, its vertices are incident to exactly m facets and m edges. So each vertex of P has m labels and each edge of P has m-1 labels. Similarly for Q and n.
- Dropping a label I ∈ A<sub>1</sub> ∪ A<sub>2</sub> in a vertex x of P means traversing the unique edge of P that is incident to x and has all m labels that x has besides I. The other endpoint of this edge has the same labels as x, only I is replaced with a new label, which is said to be picked up.
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- Duplicate label is either a new best response, which gets a positive probability, or a pure strategy whose probability became 0 and we move away from its best response facet.

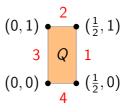
# The Lemke-Howson algorithm: pseudocode

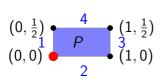
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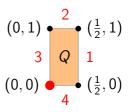
#### Algorithm 0.8: Lemke-Howson(G)

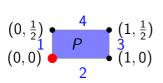
```
Input: A nondegenerate bimatrix game G.
Output: One Nash equilibrium of G.
(\mathbf{x}, \mathbf{y}) \leftarrow (\mathbf{0}, \mathbf{0}) \in \mathbb{R}^m \times \mathbb{R}^n
k \leftarrow \text{arbitrary label from } A_1 \cup A_2, l \leftarrow k,
while (true)
   do \begin{cases} \text{In } P, \text{ drop } I \text{ from } x \text{ and redefine } x \text{ as the new vertex,} \\ \text{redefine } I \text{ as the newly picked up label. Switch to } Q. \\ \text{If } I = k, \text{ stop looping.} \end{cases}
\begin{cases} \text{In } Q, \text{ drop } I \text{ from } y \text{ and redefine } y \text{ as the new vertex,} \\ \text{redefine } I \text{ as the newly picked up label. Switch to } P. \\ \text{If } I = k, \text{ stop looping.} \end{cases}
Output (x/(\mathbf{1}^{\top}x), y/(\mathbf{1}^{\top}y)).
```

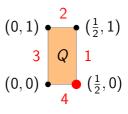


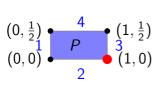


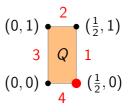












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- Is there an efficient algorithm to find NE?



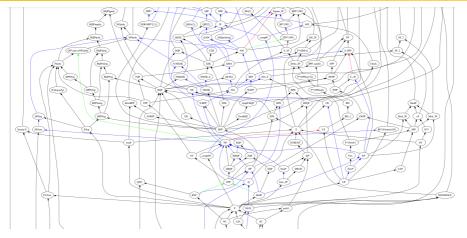


Figure: A view on the complexity classes classification.

Source: https://complexityzoo.uwaterloo.ca/Complexity\_Zoo

• "P=NP" is one of the most important problems in computer science. The website https://www.win.tue.nl/~gwoegi/P-versus-NP.htm contains a collection of over 100 attempts to solve it.

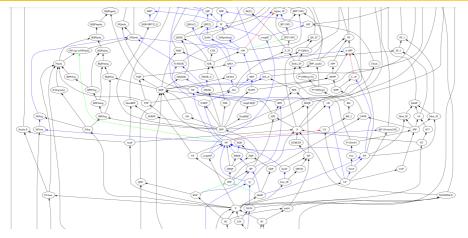


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# Thank you for your attention.