# Algorithmic game theory

Martin Balko

#### 5th lecture

November 1st 2024



# Nash equilibria in bimatrix games

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- Is there a chance to get an efficient algorithm?
- NASH = the problem of finding NE in bimatrix games.
- Today, we discuss the computational complexity of NASH.

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• Without proof (but you can find it in the lecture notes).

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## New complexity class

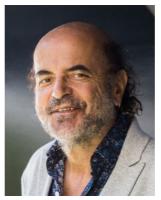
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• Let PPAD be a complexity class consisting of problems that admit a polynomial-time reduction to END-OF-THE-LINE.

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Source: https://cs.columbia.edu

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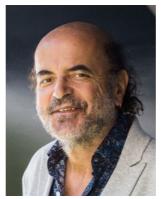


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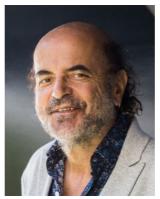


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- This complexity class contains a lot of well-known problems.

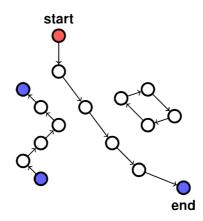
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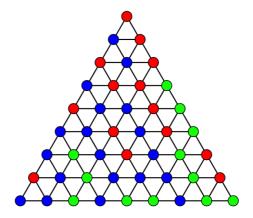
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Source: R. Savani "Polymatrix Games" Tutorial at WINE 2015

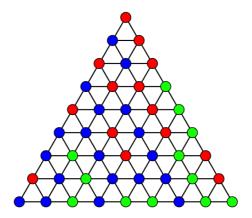
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• Discrete version of the Brouwer's fixed point theorem.

## Problems from PPAD: Brouwer's fixed point theorem

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An approximate version of the following theorem is in PPAD: For each d ∈ N, a non-empty compact convex set K in R<sup>d</sup>, and a continuous mapping f: K → K, there exists x<sub>0</sub> ∈ K such that f(x<sub>0</sub>) = x<sub>0</sub>.



#### Figure: L. E. J. Brouwer (1881–1966).

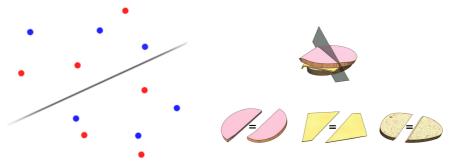
Source: https://arxiv.org/pdf/1612.06820.pdf



Source: https://www.seekpng.com/

 Given n sets of 2n points in ℝ<sup>n</sup>, find a hyperplane H that contains exactly n points from each of the sets in each open halfspace determined by H.

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Sources: https://ejarzo.github.io and https://curiosamathematica.tumblr.com

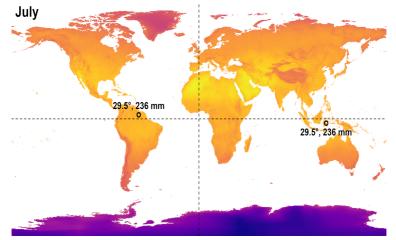
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Source: https://scientificgems.wordpress.com/

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- One of the main breakthroughs in algorithmic game theory.
- We omit the proof, as it is complicated (the papers have over 50 and 70 pages).

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- We introduce other solution concepts that possess some qualities of NE and yet are easier to compute.

# Other notions of equilibria

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For ε > 0, a strategy profile s = (s<sub>1</sub>,..., s<sub>n</sub>) in a normal-form game
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  - $\circ~$  Using  $\varepsilon$  as the "machine precision" we do not have to work with irrational numbers.

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#### Algorithmic aspects of $\varepsilon$ -Nash equilibria

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• I no longer present the proof (see the lecture notes).

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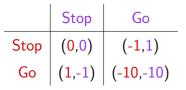
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	Stop	Go
Stop	( <mark>0</mark> ,0)	(-1,1)
Go	(1,-1)	(-10,-10)



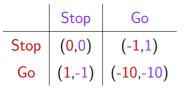
Sources: https://peakd.com/





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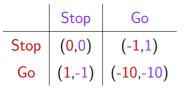
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  - By symmetry, driver 2 does not deviate as well.



Source: Students of MFF UK

	Football	Opera
Football	(2,1)	( <mark>0</mark> ,0)
Opera	( <mark>0</mark> ,0)	(1,2)



Sources: https://media.istockphoto.com/

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  - If the husband follows the suggestion "football", then he gets 2 while deviating gives him 0.

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  - Every NE is CE (Exercise). So CE always exist by Nash's theorem.
  - Each NE *s* is CE with the product distribution  $p = \prod_{i=1}^{n} s_i$ . So CE can give better payoffs than NE.

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$$\max \left\{ \sum_{i \in P} \left( \sum_{a \in A} u_i(a) p(a) \right) \right\} \text{ subject to, for all } i \in P, a_i, a'_i \in A_i,$$
$$\sum_{a_{-i} \in A_{-i}} u_i(a_i; a_{-i}) p(a_i; a_{-i}) \ge \sum_{a_{-i} \in A_{-i}} u_i(a'_i; a_{-i}) p(a_i; a_{-i})$$
$$\sum_{a \in A} p(a) = 1, p(a) \ge 0 \text{ for every } a \in A.$$

• The concept of correlated equilibria was introduced by Robert Aumann, who received a Nobel prize in economics for his work in game theory.





#### Figure: Robert Aumann (born 1930).

Sources: https://en.wikipedia.org and https://slideslive.com/38910863/strategic-information-theory

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# Thank you for your attention.