Algorithmic game theory

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4th lecture

October 25th 2024

Nash equilibria in bimatrix games

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- The best response condition: If x and y are mixed strategy vectors of players 1 and 2, respectively, then x is a best response to y iff

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\forall i \in A_1: x_i > 0 \Longrightarrow M_{i,*}y = \max\{M_{k,*}y: k \in A_1\}.
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Analogously, y is a best response to x iff

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• Today, we reveal a geometric structure behind finding NE in bimatrix games and show one of the fastest known algorithms for this task.

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- Thus, points of \overline{P} and \overline{Q} are the mixed strategies with the "upper envelope" of expected payoffs of the other player.

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• We say that a point $(x, v) \in \overline{P}$ has label $i \in A_1 \cup A_2$ if either $i \in A_1$ and $x_i = 0$ or if $i \in A_2$ and $N_{i,*}^{\top} x = v$.

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- Each point from \overline{P} or \overline{Q} may have more labels.

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 $\overline{Q} = \{(y_3, y_4, u) \in \mathbb{R}^2 \times \mathbb{R} \colon y_3, y_4 \ge 0, y_3 + y_4 = 1, 2y_3 \le u, y_4 \le u\}.$

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A strategy profile s is NE of G iff the pair $((x, v), (y, u)) \in \overline{P} \times \overline{Q}$ is completely labeled, that is, every label $i \in A_1 \cup A_2$ appears as a label of either (x, v) or (y, u) .

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- If all labels appear, then s_1 and s_2 are mutually best responses, as each pure strategy is a best response or is not in the support.

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- \bullet Then, we can divide each inequality $\mathcal{N}_{i,\ast}^\top x\leq \nu$ with ν , treating x_i/ν as a new variable, and do the same for Q. This normalizes the payoffs to 1 and we get the following polytopes.
- The (normalized) best response polytope for player 1 in G is a polytope

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P = \{x \in \mathbb{R}^m \colon x \geq \mathbf{0}, N^\top x \leq \mathbf{1}\}.
$$

- That is nice. But we will make it even nicer!
- The best response polyhedra have some unnecessary complications (they are unbounded and have u and v in their coordinates). We get rid of these under certain mild assumptions.
- $\bullet\,$ We assume that M and N^\top are non-negative and have no zero column. (simply add a large constant to the payoffs)
- \bullet Then, we can divide each inequality $\mathcal{N}_{i,\ast}^\top x\leq \nu$ with ν , treating x_i/ν as a new variable, and do the same for Q. This normalizes the payoffs to 1 and we get the following polytopes.
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Similarly, the best response polytope for player 2 in G is a polytope

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Q=\{y\in\mathbb{R}^n\colon y\geq 0, My\leq 1\}.
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Best response polytopes P and Q for the Battle of sexes

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\textbf{P} = \{(x_1,x_2) \in \mathbb{R}^2 \colon x_1,x_2 \geq 0, x_1 \leq 1, 2x_2 \leq 1\}
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 $Q = \{(y_3, y_4) \in \mathbb{R}^2 \colon y_3, y_4 \ge 0, 2y_3 \le 1, y_4 \le 1\}.$

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	- Projective transformations preserve incidences, so the labels stay the same.

Corollary 2.30

A strategy profile (s_1, s_2) with mixed strategy vectors x and y is NE of G if and only if the point $(x/u_2(s), y/u_1(s)) \in P \times Q \setminus \{(\mathbf{0}, \mathbf{0})\}$ is completely labeled.

• Recall that a bimatrix game is nondegenerate if there are at most k pure best responses to every mixed strategy with support of size k .

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	- \circ Thus, P and Q are both simple polytopes (each point of P or Q contained in more than m or n facets has more than m or n labels).
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	- \circ Since dim(P) = m and dim(Q) = n, only vertices of P and Q can have m and n labels.
	- \circ By Corollary 2.30, only vertices of P and Q can be NE.
- $\bullet \Rightarrow$ Algorithm for finding NE: check all pairs of vertices and their labels!

Algorithm 0.2 : VERTEX ENUMERATION(G)

 $Input: A$ nondegenerate bimatrix game G . Output : All Nash equilibria of G. for each pair (x, y) of vertices from $(P \setminus \{0\}) \times (Q \setminus \{0\})$ \int if (x, y) is completely labeled, then return $(x/(\mathbf{1}^\top x), y/(\mathbf{1}^\top y))$ as a Nash equilibrium

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• All vertices of a simple polytope in \mathbb{R}^d with v vertices and N defining inequalities can be found in time $O(dNv)$ (Avis and Fukuda).

Algorithm 0.4 : VERTEX ENUMERATION(G)

 $Input: A$ nondegenerate bimatrix game G . Output : All Nash equilibria of G. for each pair (x, y) of vertices from $(P \setminus \{0\}) \times (Q \setminus \{0\})$ \int if (x, y) is completely labeled, then return $(x/(\mathbf{1}^\top x), y/(\mathbf{1}^\top y))$ as a Nash equilibrium

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- However, if $m = n$, the best response polytopes can have c^n vertices for some constant c with $1 < c < 2.9$.

Polytopes can be weird and complex!

Figure: Schlegel diagram for the 120-cell.

Source: https://en.wikipedia.org/

Algorithm 0.5 : VERTEX ENUMERATION(G)

 $Input: A$ nondegenerate bimatrix game G . Output : All Nash equilibria of G. for each pair (x, y) of vertices from $(P \setminus \{0\}) \times (Q \setminus \{0\})$ \int if (x, y) is completely labeled, then return $(x/(\mathbf{1}^\top x), y/(\mathbf{1}^\top y))$ as a Nash equilibrium

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Algorithm 0.6 : VERTEX ENUMERATION(G)

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- All vertices of a simple polytope in \mathbb{R}^d with v vertices and N defining inequalities can be found in time $O(dNv)$ (Avis and Fukuda).
- However, if $m = n$, the best response polytopes can have c^n vertices for some constant c with $1 < c < 2.9$.
- We can speed up the search by performing a walk on $(P \setminus \{0\}) \times (Q \setminus \{0\})$ guided by the labels.

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Figure: Carlton E. Lemke (1920–2004) and J. T. Howson (1937–2022).

Source: https://oldurls.inf.ethz.ch

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- The algorithm starts at $(0, 0)$ and alternately follows edges of P and Q.
- At the first step, it chooses a label $k \in A_1 \cup A_2$ and drops it. Then, a new label ℓ is picked up. This label ℓ has a duplicate in the other polytope.

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- Duplicate label is either a new best response, which gets a positive probability, or a pure strategy whose probability became 0 and we move away from its best response facet.

The Lemke–Howson algorithm: pseudocode

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Algorithm 0.8 : LEMKE-HOWSON(G)

 $Input: A$ nondegenerate bimatrix game G . Output : One Nash equilibrium of G. $(x, y) \leftarrow (\mathbf{0}, \mathbf{0}) \in \mathbb{R}^m \times \mathbb{R}^n$ $k \leftarrow$ arbitrary label from $A_1 \cup A_2, l \leftarrow k$, while (*true*) do $\sqrt{ }$ $\begin{array}{c} \end{array}$ $\begin{array}{c} \end{array}$ In P , drop *l* from x and redefine x as the new vertex, redefine l as the newly picked up label. Switch to Q . If $l = k$, stop looping. In Q , drop *l* from y and redefine y as the new vertex, redefine *l* as the newly picked up label. Switch to *P*. If $l = k$, stop looping. Output $(x/(\mathbf{1}^\top x), y/(\mathbf{1}^\top y)).$

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- G has degrees only 1 or 2

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- We define a configuration graph G with the vertices formed by pairs (x, y) of vertices from $P \times Q$ that are k-almost completely labeled (every label from $A_1 \cup A_2 \setminus \{k\}$ is a label of x or y). A pair $\{(x, y), (x', y')\}$ is an edge of G if $(x = x' \& yy' \in E(Q))$ or $(xx' \in E(P)$ & $y = y'$). Clearly, G is finite.
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	- Otherwise, (x, y) has all labels from $A_1 \cup A_2 \setminus \{k\}$ and there is a unique label shared by x and y. Then (x, y) is adjacent to two vertices, as we can drop the duplicate label from x in P or y in Q .

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- Is there an efficient algorithm to find NE?

Figure: A view on the complexity classes classification.

Source: https://complexityzoo.uwaterloo.ca/Complexity Zoo

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Thank you for your attention.