### Algorithmic game theory

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3rd lecture

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# Proof of the Minimax Theorem

#### The Minimax Theorem (Theorem 2.21)

For every zero-sum game, worst-case optimal strategies for both players exist and can be efficiently computed. There is a number v such that, for any worst-case optimal strategies  $x^*$  and  $y^*$ , the strategy profile  $(x^*, y^*)$  is a Nash equilibrium and  $\beta(x^*) = (x^*)^\top M y^* = \alpha(y^*) = v$ .





Figure: John von Neumann (1903–1957) and Oskar Morgenstern (1902–1977).

Sources: https://en.wikiquote.org and https://austriainusa.org

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Recall that β(x) = min<sub>y∈S2</sub> x<sup>T</sup>My and α(y) = max<sub>x∈S1</sub> x<sup>T</sup>My are the best possible payoffs of player 2 to x and of player 1 to y, respectively.

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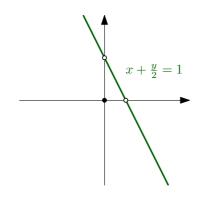
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• We prove the theorem using linear programming.

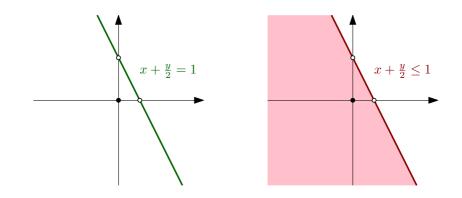
• A hyperplane in  $\mathbb{R}^d$  is a set  $\{x \in \mathbb{R}^d : v^\top x = w\}$  for some  $v \in \mathbb{R}^d$  and  $w \in \mathbb{R}$ .

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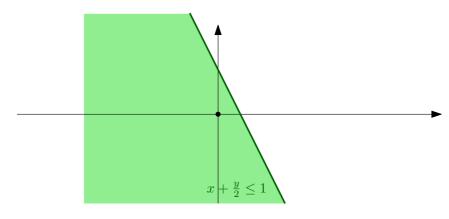
• A (convex) polyhedron *P* in  $\mathbb{R}^d$  is an intersection of finitely many halfspaces in  $\mathbb{R}^d$ .

A (convex) polyhedron P in ℝ<sup>d</sup> is an intersection of finitely many halfspaces in ℝ<sup>d</sup>. That is, P = {x ∈ ℝ<sup>d</sup>: Vx ≤ u} for some V ∈ ℝ<sup>n×d</sup> and u ∈ ℝ<sup>n</sup>, where n is the number of halfspaces determining P.

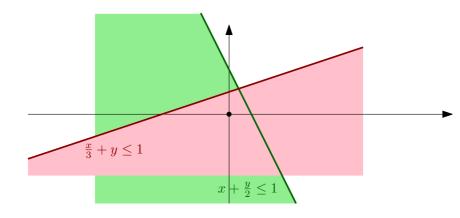
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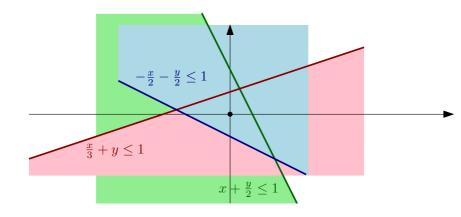
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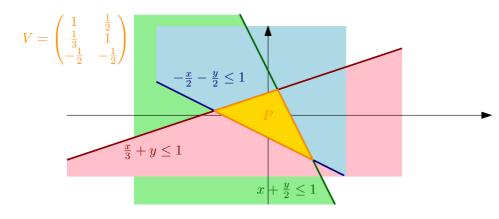
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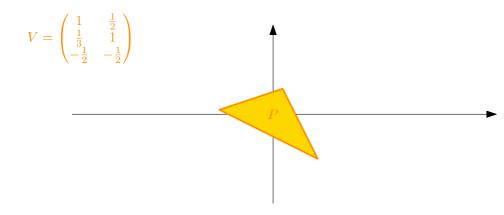
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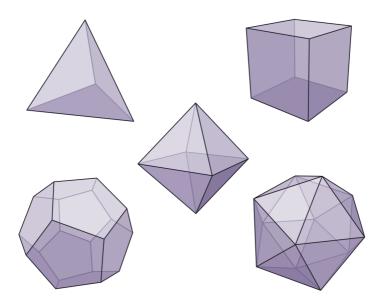


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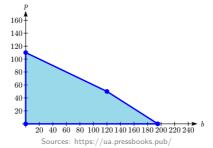
- A linear program is an optimization problem with a linear objective function and linear constraints.
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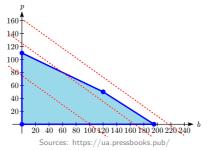
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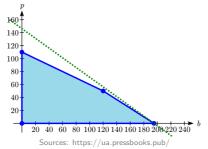
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### Duality of linear programming

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• Dual programs can be constructed for any linear program.

# General recipe for duality

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	Primal linear program	Dual linear program
Variables	$x_1,\ldots,x_m$	$y_1,\ldots,y_n$
Matrix	$A \in \mathbb{R}^{n \times m}$	$A^{ op} \in \mathbb{R}^{m  imes n}$
Right-hand side	$m{b}\in\mathbb{R}^n$	$c \in \mathbb{R}^m$
Objective function	$\max c^\top x$	min $b^{ op}y$
Constraints	$^{\prime}$ th constraint has $\leq$	$y_i \ge 0$
	2	$y_i \leq 0$
	=	$y_i \in \mathbb{R}$
	$x_j \ge 0$	$j$ th constraint has $\geq$
	$x_j \leq 0$	$\leq$
	$x_j \in \mathbb{R}$	=

Table: A recipe for making dual programs.

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Analogously, we can compute a worst-case optimum strategy y\* for 2 using this linear program P' with variables y<sub>0</sub>, y<sub>1</sub>,..., y<sub>n</sub>:

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# Nash equilibria in bimatrix games



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	Testify	Remain silent
Testify	(- <mark>2</mark> ,-2)	(- <mark>3,0</mark> )
Remain silent	( <mark>0</mark> ,-3)	(-1,-1)



Sources: https://sciworthy.com/

# Bimatrix games examples: collaborative projects



Source: https://filestage.io/

# Bimatrix games examples: education, knowledge sharing



Source: https://www.123rf.com/

# Bimatrix games examples: the battle for Gotham's soul

	Cooperate	Detonate
Cooperate	( <mark>0,0</mark> )	( <mark>0</mark> ,1)
Detonate	(1,0)	( <mark>0,0</mark> )



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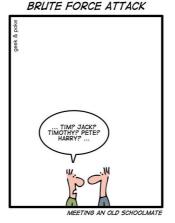
SIMPLY EXPLAINED: BRUTE FORCE ATTACK

Source: https://pinterest.com

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SIMPLY EXPLAINED:

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• Later, we show the currently best known algorithm for this problem.

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In a normal-form game G = (P, A, u) of *n* players, for every player  $i \in P$ , a mixed strategy  $s_i$  is a best response to  $s_{-i}$  if and only if all pure strategies in the support of  $s_i$  are best responses to  $s_{-i}$ .

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- Thus, the problem of finding NE is combinatorial problem, not a continuous one.
- The hearth of the problem is in finding the right supports.
- Once we have the right supports, the precise mixed strategies can be computed by solving a system of algebraic equations (which are linear in the case of two players).

First, assume every a<sub>i</sub> ∈ Supp(s<sub>i</sub>) satisfies u<sub>i</sub>(a<sub>i</sub>; s<sub>-i</sub>) ≥ u<sub>i</sub>(s'<sub>i</sub>; s<sub>-i</sub>) for every s'<sub>i</sub> ∈ S<sub>i</sub>.

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#### Proof of the Best response condition

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$$\forall \mathbf{j} \in A_2 : y_j > 0 \Longrightarrow N_{j,*}^\top \mathbf{x} = \max\{N_{k,*}^\top \mathbf{x} : \mathbf{k} \in A_2\}.$$
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where u and v are two new variables. Note that they attain values  $u = \max\{M_{i,*}y : i \in I\}$  and  $v = \max\{N_{j,*}^{\top}x : j \in J\}$ .

• We have a system S(I, J) of |I| + |J| + 2 variables  $x_1, \ldots, x_{|I|}, y_1, \ldots, y_{|J|}, u, v$  and |I| + |J| + 2 linear equations.

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- The running time is then about  $4^n$  for m = n.

• We show the brute-force algorithm on the Battle of sexes game.

	Football (1)	Opera (2)
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• This yields a unique solution  $(x_1, x_2) = (\frac{2}{3}, \frac{1}{3})$  and  $(y_1, y_2) = (\frac{1}{3}, \frac{2}{3})$ .

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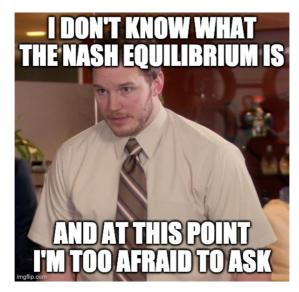
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 $2y_1 = u$ ,  $y_2 = u$ , ;  $y_1 + y_2 = 1$ 

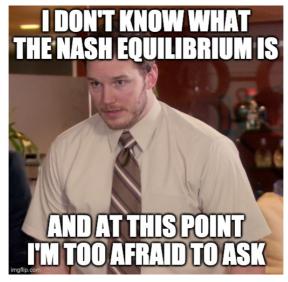
• This yields a unique solution  $(x_1, x_2) = (\frac{2}{3}, \frac{1}{3})$  and  $(y_1, y_2) = (\frac{1}{3}, \frac{2}{3})$ . Since  $x, y \ge 0$  and there is no better pure strategy, we have NE.

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Thank you for your attention.