

Algorithmic game theory

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Multi-parameter mechanism design

Multi-parameter mechanism design

- In **multi-parameter mechanism design**, we have the following setting:
 - n strategic bidders,
 - a finite set Ω of outcomes,
 - each bidder i has a private valuation $v_i(\omega) \geq 0$ for every outcome $\omega \in \Omega$.
- Each bidder i submits his bids $b_i(\omega) \geq 0$ for each $\omega \in \Omega$ and our goal is to design a mechanism that selects an outcome $\omega \in \Omega$ so that it maximizes the **social surplus** $\sum_{i=1}^n v_i(\omega)$.
- The valuations now depend on possible outcomes, so, for example, if bidders compete for a single item, each bidder can have an opinion about each other bidder winning the item as well.
- **Example** (single-item auction): we set $\Omega = \{\omega_1, \dots, \omega_n, \omega_\emptyset\}$ has size $n + 1$ and each outcome ω_i with $i \in \mathbb{N}$ corresponds to the winner i of the item. The last outcome ω_\emptyset corresponds to nobody getting the item. The valuations are $v_i(\omega_j) = 0$ for every $j \neq i$ and $v_i(\omega_i) = v_i$ otherwise.

The Vickrey–Clarke–Groves (VCG) mechanism

VCG mechanism (Theorem 3.18)

In every multi-parameter mechanism design environment, there is a DSIC social-surplus-maximizing mechanism.

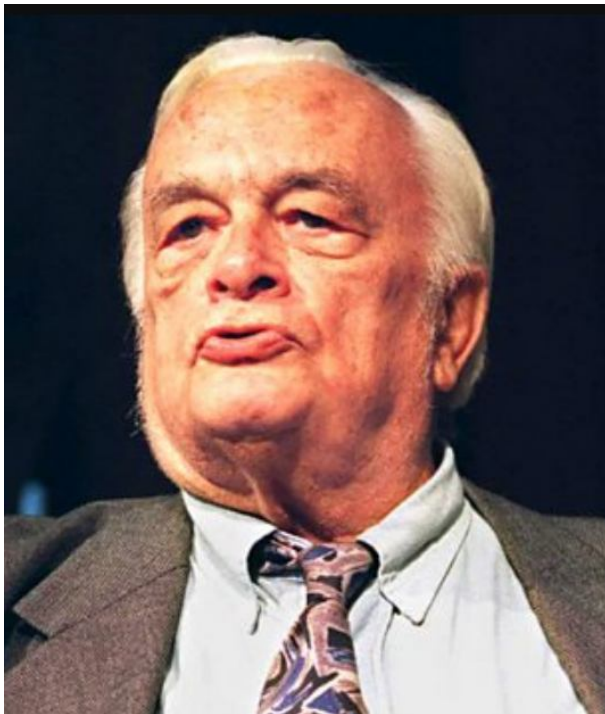


Figure: William Vickrey, Edward H. Clarke, and Theodore Groves.

Sources: : <https://en.wikipedia.org>, <https://www.demandrevelation.com/>, and <https://www.researchate.net/>

- We now present the proof.

VCG mechanism: proof idea

- The **key idea** is to consider the the loss of social surplus inflicted on the other $n - 1$ bidders by the presence of bidder i . For example, in single-item auctions, the winning bidder inflicts a social surplus loss of the second-highest bid to the others.
- We define the payments to force each bidder to care about the others.
- We will see that the following **allocation rule** works

$$x(b) = \operatorname{argmax}_{\omega \in \Omega} \sum_{i=1}^n b_i(\omega)$$

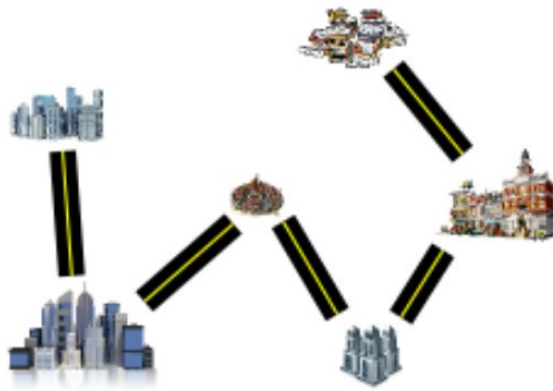
together with this **payment formula**

$$p_i(b) = \max_{\omega \in \Omega} \left\{ \sum_{\substack{j=1 \\ j \neq i}}^n b_j(\omega) \right\} - \sum_{\substack{j=1 \\ j \neq i}}^n b_j(\omega^*),$$

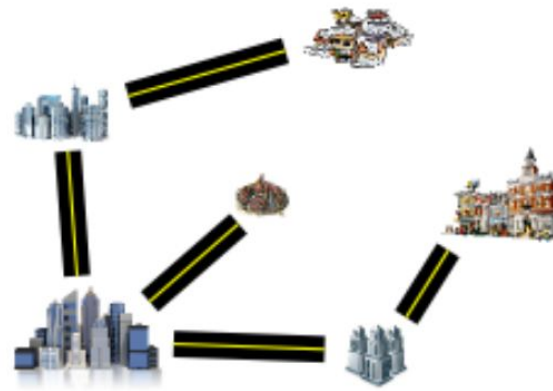
where $\omega^* = x(b)$ is the outcome chosen by our allocation rule x for given bids b .

VCG auction example

- The government wants to construct roads connecting diverse cities, and he wants cities to pay for the roads.



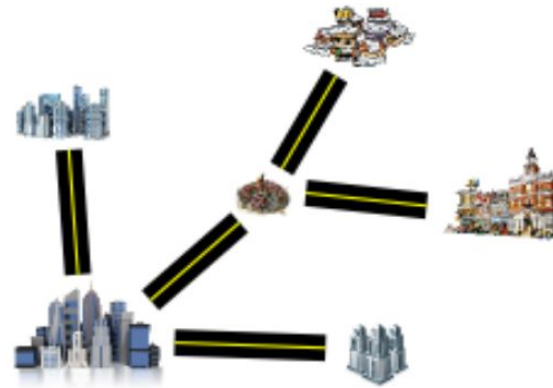
Road Network 1



Road Network 2

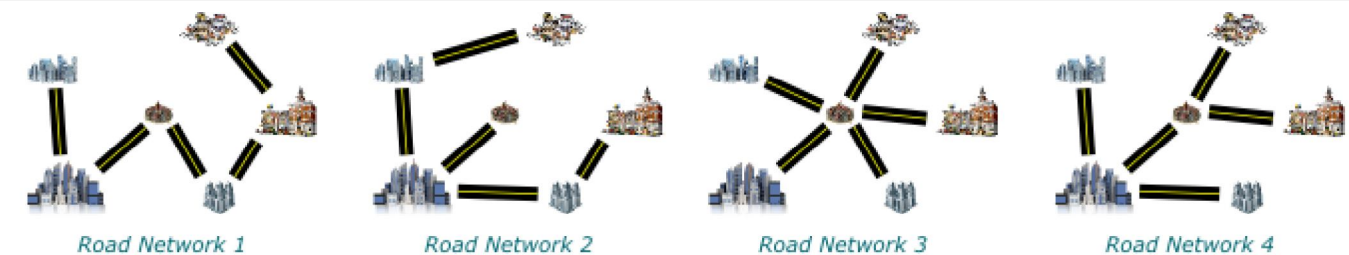








Road Network 3



Road Network 4

VCG auction example



	Road Network 1	Road Network 2	Road Network 3	Road Network 4
	6 M\$	14 M\$	2 M\$	16 M\$
	5 M\$	8 M\$	4 M\$	12 M\$
	2 M\$	1 M\$	20 M\$	4 M\$
	4 M\$	6 M\$	3 M\$	5 M\$
	1 M\$	1 M\$	6 M\$	2 M\$
	1 M\$	2 M\$	2 M\$	3 M\$
Total (social welfare)	19 M\$	32 M\$	37 M\$	42 M\$

Sources: <https://www.science4all.org/article/auction-design/>

- **Cities pay their negative externalities on the collectivity.** Other cities would be happier without the biggest city (NYC, say). How much happier they would be is exactly what NYC must pay.

VCG auction example



	6 M\$	14 M\$	2 M\$	16 M\$
	5 M\$	8 M\$	4 M\$	12 M\$
	2 M\$	1 M\$	20 M\$	4 M\$
	4 M\$	6 M\$	3 M\$	5 M\$
	1 M\$	1 M\$	6 M\$	2 M\$
	1 M\$	2 M\$	2 M\$	3 M\$
Total (social welfare)	19 M\$	32 M\$	37 M\$	42 M\$

Sources: <https://www.science4all.org/article/auction-design/>

- If NYC was not there, then road network number 3 (RN3) would have been chosen, as opposed to RN4. The value of RN3 for the other cities would be 35 M\$, as opposed to the 26 M\$ of RN4. Therefore, the negative externality of NYC is $35 - 26 = 9$ M\$.

VCG mechanism: proof I

- We proceed in two steps. First, we assume, without justification, that bidders truthfully reveal their private information, and figure out which outcome from Ω to pick.
- We maximize the social surplus, so our **allocation rule** needs to pick an outcome that maximizes the social surplus. So, given bids $b = ((b_1(\omega))_{\omega \in \Omega}, \dots, (b_n(\omega))_{\omega \in \Omega})$, we define the allocation rule by

$$x(b) = \operatorname{argmax}_{\omega \in \Omega} \sum_{i=1}^n b_i(\omega).$$

- Second, we need to choose **payment rule** $p = (p_1, \dots, p_n)$ so that the multi-parameter mechanism (x, p) is DSIC.
- We choose p so that our assumption about truthful bidders is justified.
- The key idea turns is considering the the **loss of social surplus inflicted on the other $n - 1$ bidders** by the presence of bidder i .

VCG mechanism: proof II

- Formally, we choose the payment rule as

$$p_i(b) = \max_{\omega \in \Omega} \left\{ \sum_{\substack{j=1 \\ j \neq i}}^n b_j(\omega) \right\} - \sum_{\substack{j=1 \\ j \neq i}}^n b_j(\omega^*)$$

for every bidder i , where $\omega^* = x(b)$ is the outcome chosen by our allocation rule x for given bids b .

- The first term is the surplus of the remaining $n - 1$ bidders if we omit bidder i . The second term is the social surplus if we consider bidder i .
- By definition, the mechanism (x, p) is maximizing social surplus, assuming truthful bids. **It remains to prove that it is DSIC.**
- That is, we need to show that each bidder i maximizes his **utility** $v_i(x(b)) - p_i(b)$ by setting $b_i(\omega) = v_i(\omega)$ for every $\omega \in \Omega$.
- One can show that we have $0 \leq p_i(b) \leq b_i(\omega^*)$ (**Exercise**), hence truthtelling agents are guaranteed non-negative utility.

VCG mechanism: proof III

- We fix bidder i and the bids of other bidders b_{-i} .
- If $x(b) = \omega^*$, then, by the **choice of p** , the utility of bidder i equals

$$v_i(\omega^*) - p_i(b) = \left(v_i(\omega^*) + \sum_{j \neq i} b_j(\omega^*) \right) - \left(\max_{\omega \in \Omega} \left\{ \sum_{j \neq i} b_j(\omega) \right\} \right).$$

- The second term is **independent of b_i** , thus bidder i needs to maximize the first term of the expansion in order to maximize his utility. However, bidder i cannot influence ω^* directly, the mechanism (x, p) gets to choose ω^* so that sums of bids are maximized.
- Best case for bidder i is when the mechanism picks ω^* that maximizes the first term of the expansion, that is, bidder i wants to select

$$\operatorname{argmax}_{\omega \in \Omega} \left\{ v_i(\omega) + \sum_{j \neq i} b_j(\omega) \right\}.$$

- If i bids truthfully, then this agrees with our **choice of x** . Thus, bidding truthfully results in maximizing i 's utility. □

Proof of Myerson's lemma

Myerson's lemma

Myerson's lemma (Theorem 3.8)

In a single-parameter environment, the following three claims hold.

- (a) An allocation rule is **implementable if and only if it is monotone**.
- (b) If an allocation rule x is monotone, then there exists a **unique payment rule** p such that the mechanism (x, p) is DSIC (assuming that $b_i = 0$ implies $p_i(b) = 0$).
- (c) The payment rule p is given by the following **explicit formula**

$$p_i(b_i; b_{-i}) = \int_0^{b_i} z \cdot \frac{d}{dz} x_i(z; b_{-i}) dz$$

for every $i \in \{1, \dots, n\}$.

- We have applied this result many times, but we have not seen its proof yet. Let's fix that.

Proof of Myerson's lemma I

- Let x be an allocation rule and p be a payment rule such that (x, p) is DSIC. We prove all three claims at once use a clever swapping trick.
- The DSIC property says that, for every z ,
$$u_i(z; b_{-i}) = v_i \cdot x_i(z; b_{-i}) - p_i(z; b_{-i}) \leq v_i \cdot x_i(v_i; b_{-i}) - p_i(v_i; b_{-i}).$$
- For two possible bids y and z with $0 \leq y < z$, bidder i might as well have private valuation z and can submit the false bid y if he wants, thus the DSIC condition gives

$$u_i(y; b_{-i}) = z \cdot x_i(y; b_{-i}) - p_i(y; b_{-i}) \leq z \cdot x_i(z; b_{-i}) - p_i(z; b_{-i}) = u_i(z; b_{-i}).$$

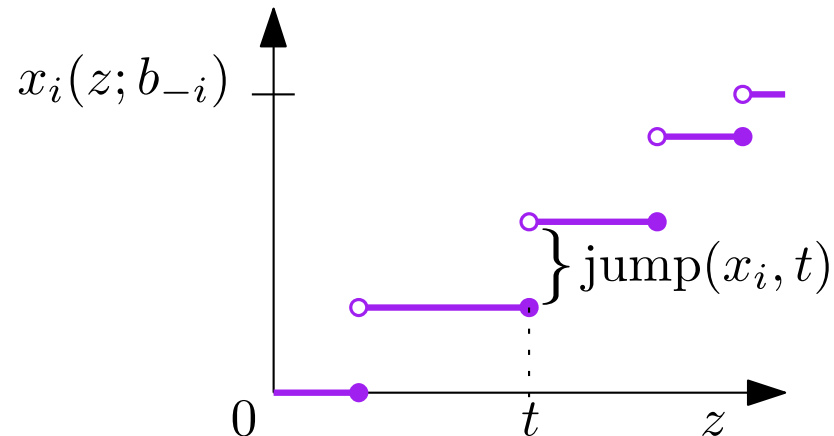
- Analogously, we can have $v_i = y$ and $b_i = z$ and thus (x, p) satisfies
$$u_i(z; b_{-i}) = y \cdot x_i(z; b_{-i}) - p_i(z; b_{-i}) \leq y \cdot x_i(y; b_{-i}) - p_i(y; b_{-i}) = u_i(y; b_{-i}).$$
- By putting these inequalities together, we obtain the following **payment difference sandwich**:

$$z(x_i(y; b_{-i}) - x_i(z; b_{-i})) \leq p_i(y; b_{-i}) - p_i(z; b_{-i}) \leq y(x_i(y; b_{-i}) - x_i(z; b_{-i})).$$

- Since $0 \leq y < z$, we obtain $x_i(y; b_{-i}) \leq x_i(z; b_{-i})$. Thus, if (x, p) is DSIC, then x is monotone.

Proof of Myerson's lemma II

- In the rest of the proof, we assume that the allocation x is monotone.
- Let i and b_{-i} be fixed, so we consider x_i and p_i as functions of z .
- First, we also assume that the function x_i is piecewise constant. Thus, the graph of x_i consists of a finite number of intervals with “jumps” between consecutive intervals:



- For a piecewise constant function f , we use $\text{jump}(f, t)$ to denote the magnitude of the jump of f at point t .
- If we fix z in the payment difference sandwich and let y approach z from below, then both sides become 0 if there is no jump of x_i at z . If $\text{jump}(x_i, z) = h > 0$, then both sides tend to $z \cdot h$.

Proof of Myerson's lemma III

- Thus, if the mechanism (x, p) is supposed to be DSIC, then the following constraint on p must hold for every z :

$$\text{jump}(p_i, z) = z \cdot \text{jump}(x_i, z).$$

- If we combine this constraint with the initial condition $p_i(0; b_{-i}) = 0$, we obtain a formula for the payment function p for every bidder i and bids b_{-i} of other bidders,

$$p_i(b_i; b_{-i}) = \sum_{j=1}^{\ell} z_j \cdot \text{jump}(x_i(\cdot; b_{-i}), z_j),$$

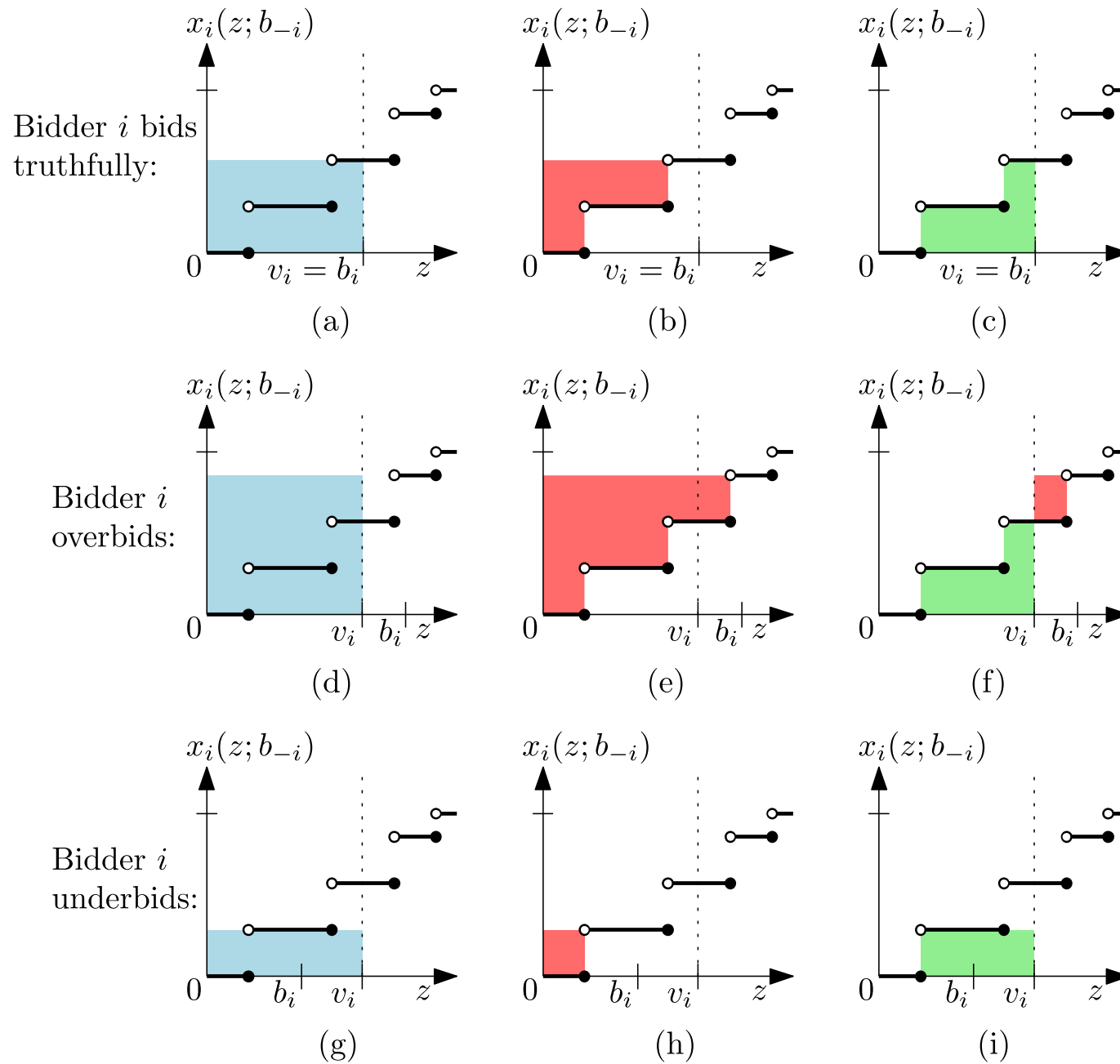
where z_1, \dots, z_ℓ are the breakpoints of the allocation function $x_i(\cdot; b_{-i})$ in the interval $[0, b_i]$.

- With some additional facts from calculus, this argument can be generalized to general monotone functions x_i . We omit the details.

Proof of Myerson's lemma IV

- It remains to show that if x is monotone, then the mechanism (x, p) is indeed DSIC.
- This argument works in general, but we present it only for piecewise constant functions.
- We recall that the utility $u_i(b_i; b_{-i}) = v_i \cdot x_i(b_i; b_{-i}) - p_i(b_i; b_{-i})$.
- Using the expression of the payment, we see that the payment $p_i(b_i; b_{-i})$ of bidder i corresponds to the part of $[0, b_i] \times [0, x_i(b_i; b_{-i})]$ lying to the left of the curve $x_i(\cdot; b_{-i})$.
- It will follow from a picture that it is optimal for bidder i to bid $b_i = v_i$.

Proof of Myerson's lemma by picture



Revelation principle

Going beyond DSIC?

- So far we have considered only **DSIC** mechanisms, as they are easy to play and predict. A natural question is **whether we lose anything by restricting ourselves to these mechanisms**.
- We split the DSIC property into the following two parts:
 - Each bidder has a **dominant strategy**, no matter what his private valuation is.
 - This dominant strategy is **direct revelation** (that is, truthtelling).
- **Example** (auction that satisfies only the first property):
 - Consider a single-item auction, where the seller on given bids (b_1, \dots, b_n) runs a **Vickrey's auction** on bids $(2b_1, \dots, 2b_n)$.
 - Then each bidder has a dominant strategy and thus the first property is satisfied.
 - However, this dominant strategy is not direct revelation, but to bid half of your value.
- So is DSIC too restrictive?

Revelation principle

- **No!** We will see that only the first condition matters while the second one then comes for free.
- Clearly, the first condition is not always satisfied (first-price auctions). Without it, it is hard to predict the behavior of the bidders. Although it sometimes makes sense to relax the first condition.
- The **Revelation principle** says that there is no need to relax the second condition.

Revelation principle (Theorem 3.19)

For every multi-parameter mechanism M in which every bidder has a dominant strategy, no matter what his private valuation is, there is an equivalent mechanism M' in which each bidder has a dominant strategy that is a **direct revelation**.

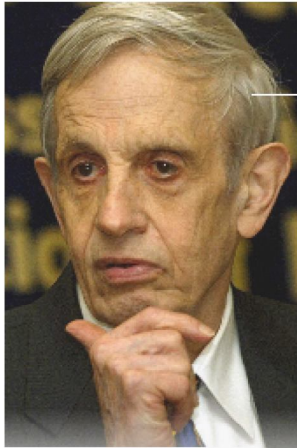
Proof of the Revelation principle

- The proof proceeds by a **simulation argument**.
- For each bidder i and his valuations $v_i(\omega)_{\omega \in \Omega}$, let $s_i(v_i(\omega)_{\omega \in \Omega})$ be the dominant strategy of i in the mechanism M .
- We now construct the mechanism M' that additionally satisfies the second condition:
 - The mechanism M' accepts sealed bids $b_1(\omega)_{\omega \in \Omega}, \dots, b_n(\omega)_{\omega \in \Omega}$ from the bidders.
 - Then, M' submits the bids $s_1(b_1(\omega)_{\omega \in \Omega}), \dots, s_n(b_n(\omega)_{\omega \in \Omega})$ to M and M' outputs the same outcome as M .
- The direct revelation is a dominant strategy in M' , as if a bidder i has valuations $v_i(\omega)_{\omega \in \Omega}$, then submitting any other bid than $v_i(\omega)_{\omega \in \Omega}$ can only result in playing a different strategy than $s_i(v_i(\omega)_{\omega \in \Omega})$ in M' . This, however, can only decrease the utility of i . □

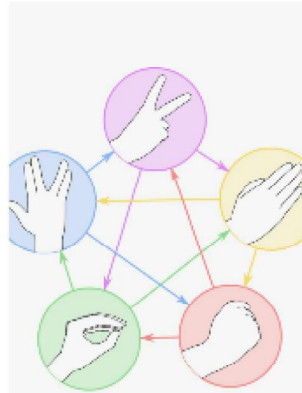
Exams

Exams info

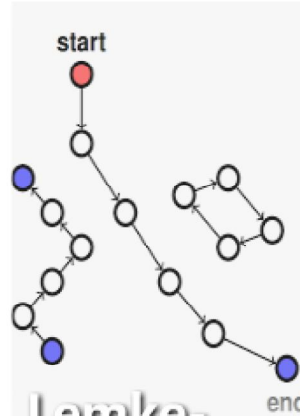
- **Exam format:**
 - Oral exam with preparation, 3 hours max.
 - I will ask about **three topics**, one survey question, one question with proofs, and one exercise.
 - The more points you have, the easier the exam is. If you have at least 25 points, you do not need to solve the exercise part.
- **Dates (so far):**
 - **14.1.** – 9:00–19:00, capacity 30
 - **20.1.** – 9:00–19:00, capacity 30
 - **28.1.** – 9:00–16:00, capacity 20
 - **3.2.** – 9:00–16:00, capacity 20
 - **11.2.** – 9:00–16:00, capacity 20
- **What you should know:** everything that we covered (everything is included in the lecture notes).



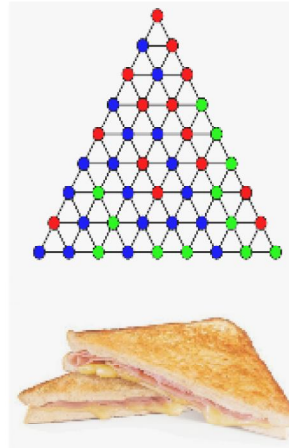
Nash equilibria



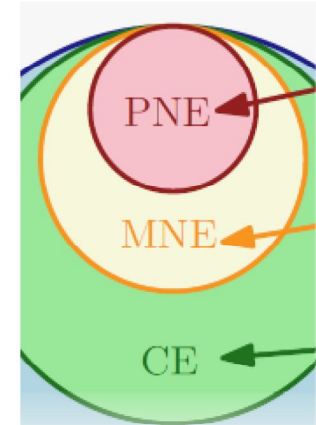
Minimax theorem



Lemke-Howson algorithm



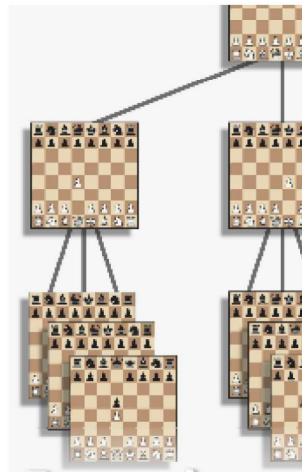
Complexity of NASH



Variants of NE

	0	1	
	1	0	
		Loss	
		1	
		1	
		3	

Regret minimization



Extensive games



Mechanism design



Revenue maximization



VCG mechanism

Thank you for your attention.