

# Algorithmic game theory

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3rd lecture

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# Proof of the Minimax Theorem

# The Minimax Theorem

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- For every zero-sum game, worst-case optimal strategies for both players exist and can be efficiently computed. There is a number  $v$  such that, for any worst-case optimal strategies  $x^*$  and  $y^*$ , the strategy profile  $(x^*, y^*)$  is a Nash equilibrium and  $\beta(x^*) = (x^*)^\top M y^* = \alpha(y^*) = v$ .



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Figure: John von Neumann (1903–1957) and Oskar Morgenstern (1902–1977).

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- Recall that  $\beta(x) = \min_{y \in S_2} x^\top M y$  and  $\alpha(y) = \max_{x \in S_1} x^\top M y$  are the best possible payoffs of player 2 to  $x$  and of player 1 to  $y$ , respectively.

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- Also, the **worst-case optimal strategy**  $\bar{x}$  for player 1, satisfies

$$\beta(\bar{x}) = \max_{x \in S_1} \beta(x).$$

- The **worst-case optimal strategy**  $\bar{y}$  for player 2, satisfies

$$\alpha(\bar{y}) = \min_{y \in S_2} \alpha(y).$$

# Duality of linear programming

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	Primal linear program	Dual linear program
Variables	$x_1, \dots, x_m$	$y_1, \dots, y_n$
Matrix	$A \in \mathbb{R}^{n \times m}$	$A^T \in \mathbb{R}^{m \times n}$
Right-hand side	$b \in \mathbb{R}^n$	$c \in \mathbb{R}^m$
Objective function	$\max c^T x$	$\min b^T y$
Constraints	$i$ th constraint has $\leq$ $\geq$ $=$	$y_i \geq 0$ $y_i \leq 0$ $y_i \in \mathbb{R}$
	$x_j \geq 0$ $x_j \leq 0$ $x_j \in \mathbb{R}$	$j$ th constraint has $\geq$ $\leq$ $=$

Table: A recipe for making dual programs.

# Nash equilibria in bimatrix games



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	Testify	Remain silent
Testify	$(-2,-2)$	$(-3,0)$
Remain silent	$(0,-3)$	$(-1,-1)$

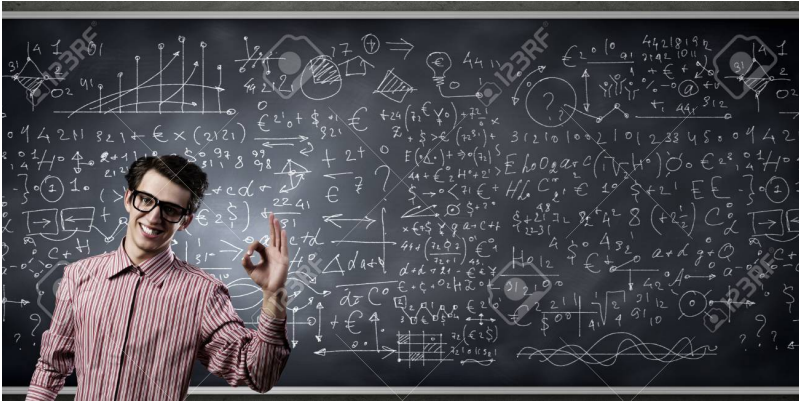


# Bimatrix games examples: collaborative projects



Source: <https://filestage.io/>

# Bimatrix games examples: education, knowledge sharing



Source: <https://www.123rf.com/>

## Bimatrix games examples: the battle for Gotham's soul

	Cooperate	Detonate
Cooperate	(0,0)	(0,1)
Detonate	(1,0)	(0,0)



Sources: <https://www.cbr.com/>

# Nash equilibria in bimatrix games by brute force



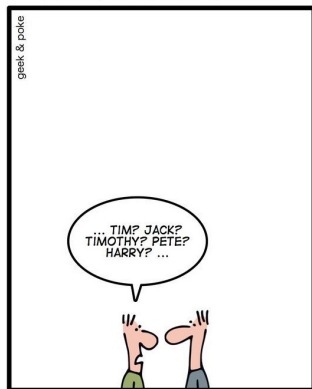
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- We state some observations that yield a **brute-force algorithm**.

*SIMPLY EXPLAINED:  
BRUTE FORCE ATTACK*



*MEETING AN OLD SCHOOLMATE*

Source: <https://pinterest.com>

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- Later, we show the currently **best known algorithm** for this problem.

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- If  $I = \{1, 2\}$  and  $J = \{1, 2\}$ , then we want to solve the following system of 6 equations with 6 variables  $x_1, x_2, y_1, y_2, u, v$ :

$$\begin{aligned}x_1 &= v, & 2x_2 &= v, & x_1 + x_2 &= 1 \\ 2y_1 &= u, & y_2 &= u, & y_1 + y_2 &= 1\end{aligned}$$

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- This yields a unique solution  $(x_1, x_2) = (\frac{2}{3}, \frac{1}{3})$  and  $(y_1, y_2) = (\frac{1}{3}, \frac{2}{3})$ . Since  $x, y \geq \mathbf{0}$  and there is no better pure strategy, we have NE.

# Preliminaries from geometry

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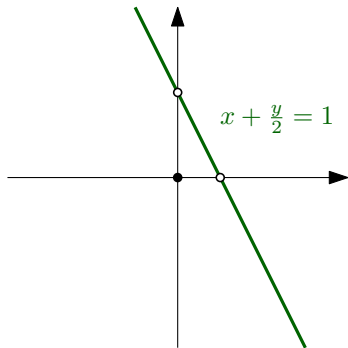
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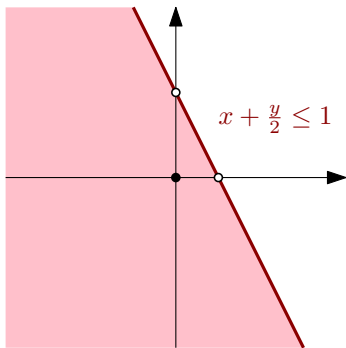
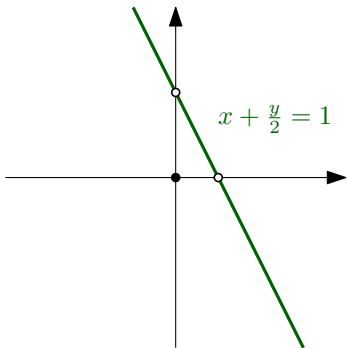
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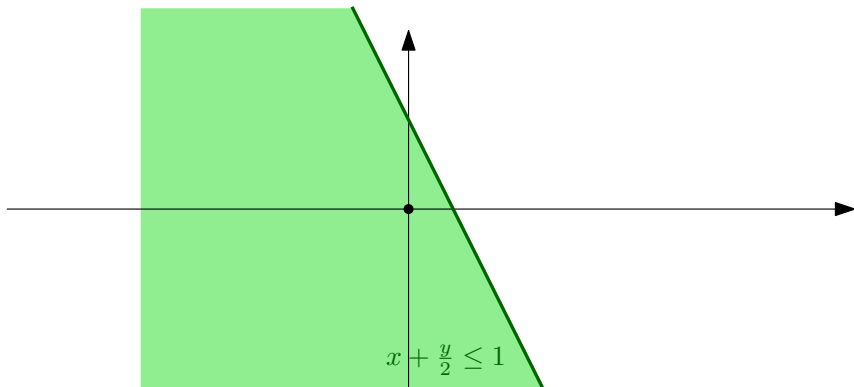
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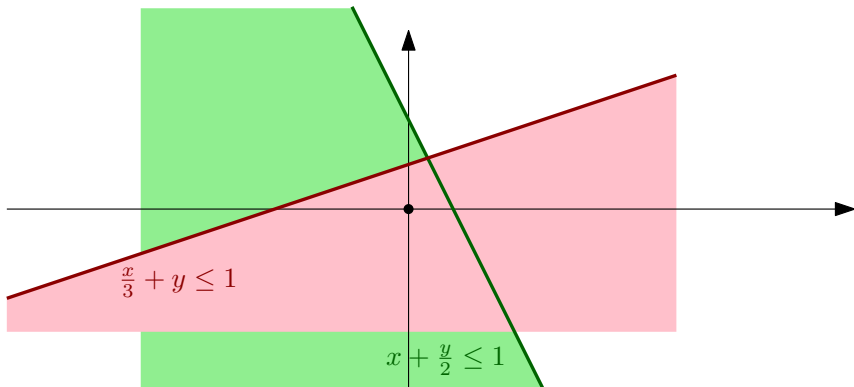
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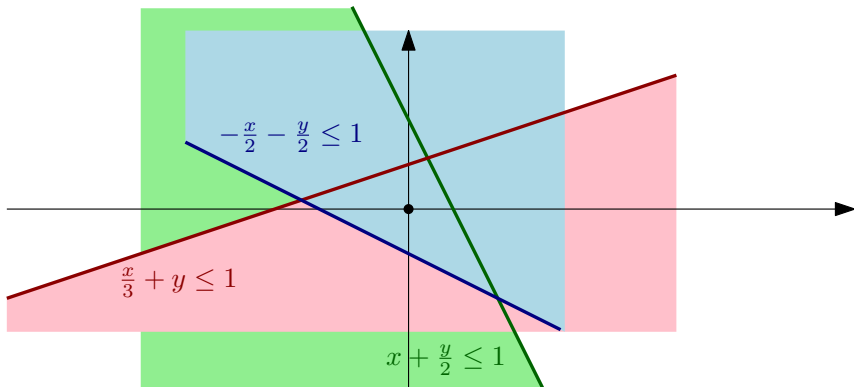
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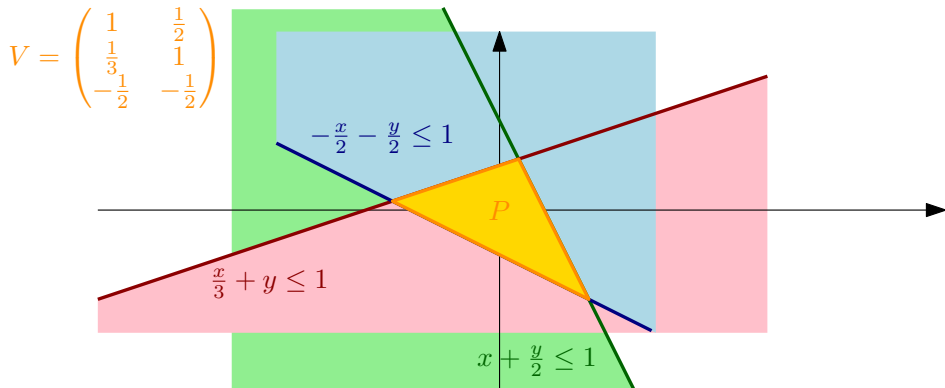
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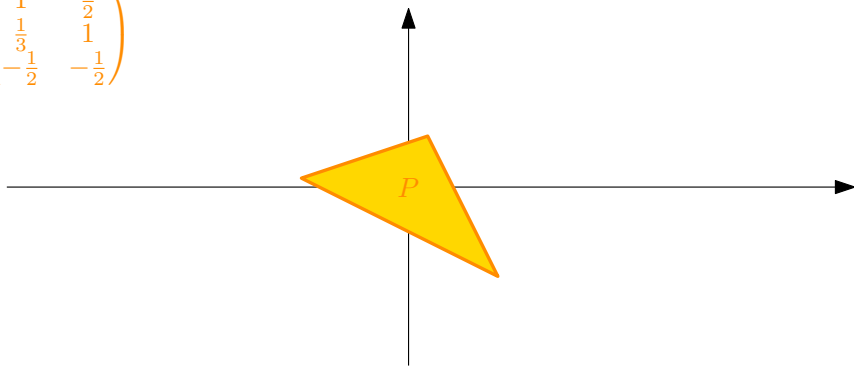
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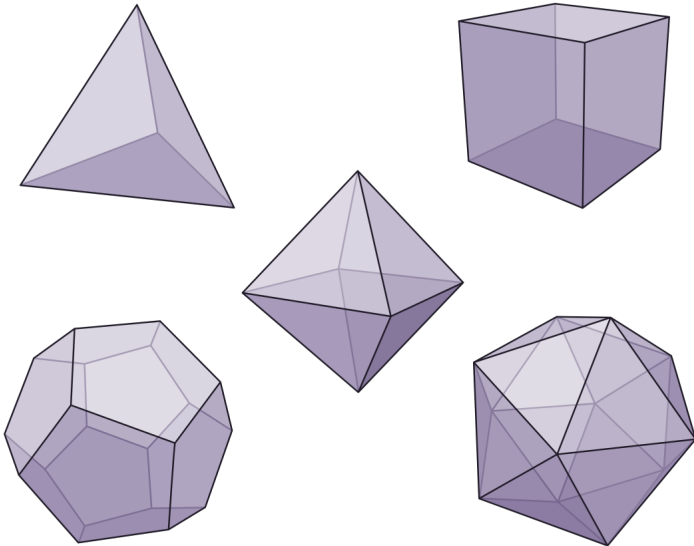
$$V = \begin{pmatrix} 1 & \frac{1}{2} \\ \frac{1}{3} & 1 \\ -\frac{1}{2} & -\frac{1}{2} \end{pmatrix}$$



# Examples of polytopes in $\mathbb{R}^3$

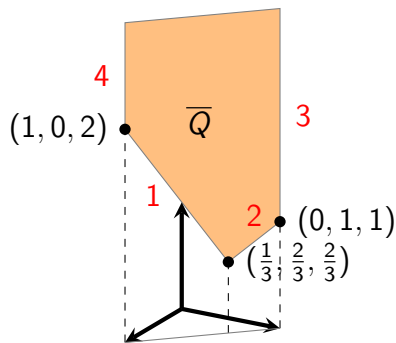
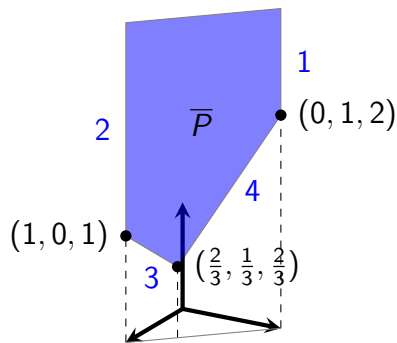


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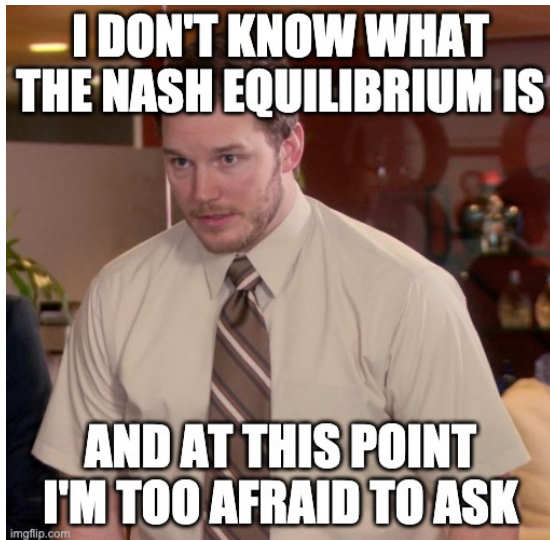
$$\bar{P} = \{(x_1, x_2, v) \in \mathbb{R}^2 \times \mathbb{R} : x_1, x_2 \geq \mathbf{0}, x_1 + x_2 = 1, x_1 \leq v, 2x_2 \leq v\}$$

$$\bar{Q} = \{(y_3, y_4, u) \in \mathbb{R}^2 \times \mathbb{R} : y_3, y_4 \geq \mathbf{0}, y_3 + y_4 = 1, 2y_3 \leq u, y_4 \leq u\}.$$

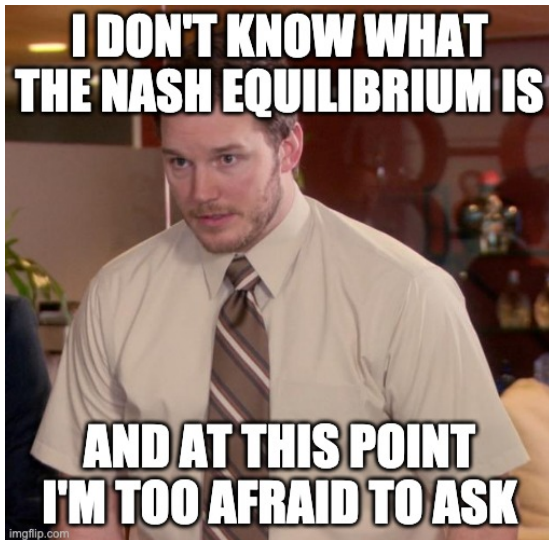


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