

The matching polytope has exponential extension complexity

Thomas Rothvoß

November 27, 2014

presented by Vojtěch Kaluža

Notation.

- The formulas $F \sim \mathcal{A}$ and $F \in_{\mathcal{U}} \mathcal{A}$ means that F is a uniformly random element of \mathcal{A} .
- We use only uniform distribution, no other probability distributions are considered.

Definition (Perfect matching polytope): $P_M = \text{conv}\{\chi_M \in \mathbb{R}^E \mid M \subseteq E \text{ is a perfect matching}\}$
Edmonds $\{x \in \mathbb{R}^E \mid x(\delta(v)) = 1 \ \forall v \in V; x(\delta(U)) \geq 1 \ \forall U \subseteq V, |U| \text{ odd}; x_e \geq 0 \ \forall e \in E\}$.

Definition (Extension complexity): The *extension complexity* $\text{xc}(P)$ of a polytope P is defined as the minimal number of facets of a higher dimensional polytope Q s.t. there is a linear projection π satisfying $\pi(Q) = P$.

Theorem 1 (Rothvoß): For all $n \in \mathbb{N}$, $\text{xc}(P_M) \geq 2^{\Omega(n)}$ in the complete n -node graph.

Fact: If P is a linear projection of a face of P' , then $\text{xc}(P) \leq \text{xc}(P')$.

Corollary 2: Because Yannakakis described a linear projection of a face of P_{TSP} of $O(n)$ -node complete graph onto P_M of n -node complete graph, we have $\text{xc}(P_{TSP}) \geq 2^{\Omega(n)}$, too.

Definition (Slack matrix): Let $P = \text{conv}\{x_1, \dots, x_v\} = \{x \in \mathbb{R}^n \mid Ax \leq b\}$, where $A \in \mathbb{R}^{f \times n}$. We define the *slack matrix* $S \in \mathbb{R}_{\geq 0}^{f \times v}$ as $S_{ij} = b_i - A_{ij}x_j$, i.e. S_{ij} is the slack of the j -th vertex in the i -th inequality.

Definition (Non-negative rank): The *non-negative rank* $\text{rk}_+(S)$ of a matrix S is defined as $\text{rk}_+(S) = \min\{r \mid (\exists U \in \mathbb{R}_{\geq 0}^{f \times r})(\exists V \in \mathbb{R}_{\geq 0}^{r \times v})(S = UV)\}$.

Theorem 3 (Yannakakis 91): Let P be a polytope with vertices $\{x_1, \dots, x_v\}$, $P = \{x \in \mathbb{R}^n \mid Ax \leq b\}$, let S be its slack matrix. Then

- $\text{xc}(P) = \text{rk}_+(S)$
- Moreover, the minimal extended formulation of P can be obtained by factoring $S = UV$, where U, V come from the definition of rk_+ , and writing $P = \{x \in \mathbb{R}^n \mid (\exists y \geq 0)(Ax + Uy = b)\}$

Lemma 4 (Hyperplane separation lower bound): Let $S \in \mathbb{R}_{\geq 0}^{f \times v}$ be the slack matrix of a polytope P and $W \in \mathbb{R}^{f \times v}$ be any matrix. Then

$$\text{xc}(P) \geq \frac{\langle W, S \rangle}{\|S\|_{\infty} \cdot \alpha} \quad \text{where } \alpha = \max\{\langle W, R \rangle \mid R \in \{0, 1\}^{f \times v} \text{ rank 1-matrix}\}.$$

Notation.

- Choose a parameter $k > 3$ odd, $t = \frac{m+1}{2}(k-3) + 3$ is an odd magic constant.
- $\mathcal{M}_{all} = \{M \subseteq E \mid M \text{ is a perfect matching}\}$
- $\mathcal{U}_{all} = \{U \subseteq V \mid |U| = t\}$
- $Q_l = \{(U, M) \in \mathcal{M}_{all} \times \mathcal{U}_{all} \mid |\delta(U) \cap M| = l\}$, μ_l the uniform measure on Q_l
- Rectangle $\mathcal{R} = \mathcal{U} \times \mathcal{M}$ where $\mathcal{U} \subseteq \mathcal{U}_{all}$ and $\mathcal{M} \subseteq \mathcal{M}_{all}$

Lemma 6: For all $k > 3$ odd and for all rectangles \mathcal{R} with $\mu_1(\mathcal{R}) = 0$ we have that $\mu_3(\mathcal{R}) \leq \frac{400}{k^2} \cdot \mu_k(\mathcal{R}) + 2^{-\delta m}$, where $\delta = \delta(k) > 0$ is a constant.

Definition (Partition): A partition is a tuple $T = (A = \dot{\bigcup}_{i=1}^m A_i, C, D, B = \dot{\bigcup}_{i=1}^m B_i)$ with $V = A \dot{\cup} C \dot{\cup} D \dot{\cup} B$, $|C| = |D| = k$ and $|A_i| = k-3$, $|B_i| = 2(k-3)$ for every $i \in [m]$.

Notation.

- $E(T) = \dot{\bigcup}_{i=1}^m E(A_i) \dot{\cup} E(C \cup D) \dot{\cup} \dot{\bigcup}_{i=1}^m E(B_i)$
- $\mathcal{M}(T) = \{M \in \mathcal{M} \mid M \subseteq E(T)\}$
- $\mathcal{M}_{all}(T) = \{M \in \mathcal{M}_{all} \mid M \subseteq E(T)\}$
- $\mathcal{U}(T) = \{U \in \mathcal{U} \mid U \subseteq A \cup C \text{ with } |U \cap A_i| \in \{0, |A_i|\} \forall i \in [m]\}$
- $\mathcal{U}_{all}(T) = \{U \in \mathcal{U}_{all} \mid U \subseteq A \cup C \text{ with } |U \cap A_i| \in \{0, |A_i|\} \forall i \in [m]\}$
- $p_{\mathcal{M},T}(H) = \Pr_{M \sim \mathcal{M}_{all}(T)}[M \in \mathcal{M} \mid H \subseteq M]$
- $p_{\mathcal{M},T}^{ex}(H) = \Pr_{M \sim \mathcal{M}_{all}(T)}[M \in \mathcal{M} \mid M \cap \delta(C) = H]$
- $p_{\mathcal{U},T}(c) = \Pr_{U \sim \mathcal{U}_{all}(T)}[U \in \mathcal{U} \mid c \subseteq U]$, where $c \subseteq C$
- $p_{\mathcal{U},T}^{ex}(c) = \Pr_{U \sim \mathcal{U}_{all}(T)}[U \in \mathcal{U} \mid C \cap U = c]$, where $c \subseteq C$
- $p_{\mathcal{U},T}^{ex}(H) = p_{\mathcal{U},T}^{ex}(V(H) \cap C)$ for a matching $H \subseteq C \times D$

Definition (\mathcal{M} -good): Let T be a partition and H a 3-matching in $C \times D$. Then (T, H) is called \mathcal{M} -good $\iff 0 < \frac{1}{1+\epsilon} p_{\mathcal{M},T}(H) \leq p_{\mathcal{M},T}(F) \leq (1+\epsilon) p_{\mathcal{M},T}(H)$ for every k -matching $F \subseteq E(C \cup D)$ s.t. $H \subseteq F$. Otherwise, it is called \mathcal{M} -bad.

Definition (\mathcal{U} -good): Let T be a partition and H a 3-matching in $C \times D$. Then (T, H) is called \mathcal{U} -good $\iff 0 < \frac{1}{1+\epsilon} p_{\mathcal{U},T}^{ex}(H) \leq p_{\mathcal{U},T}^{ex}(C) \leq (1+\epsilon) p_{\mathcal{U},T}^{ex}(H)$. Otherwise, it is called \mathcal{U} -bad.

Definition (Good): If (T, H) is both \mathcal{U} -good and \mathcal{M} -good, we call it just **good**.

Lemma 7: If (T, H) is \mathcal{M} -good $\implies \frac{1}{1+\epsilon} p_{\mathcal{M},T}(H) \leq p_{\mathcal{M},T}^{ex}(H) \leq (1+\epsilon) p_{\mathcal{M},T}(H)$.

Lemma 8: If T is a partition and $F \subseteq C \times D$ is a k -matching, then $\Pr_{H \sim \binom{F}{3}}[(T, H) \text{ is good}] \leq \frac{100}{k^2}$

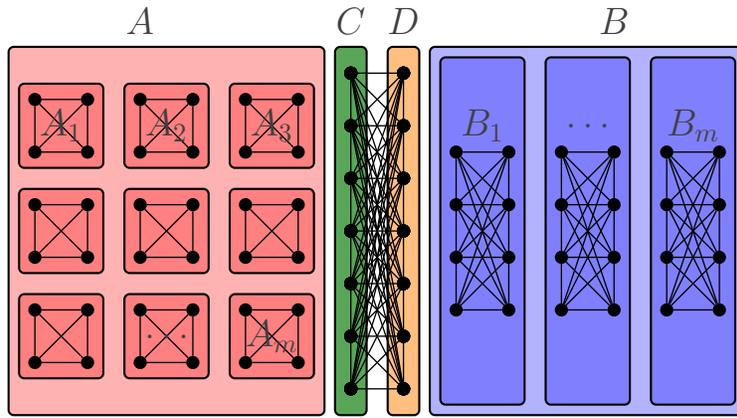


Figure 1: Visualization of a partition T with all edges $E(T)$.

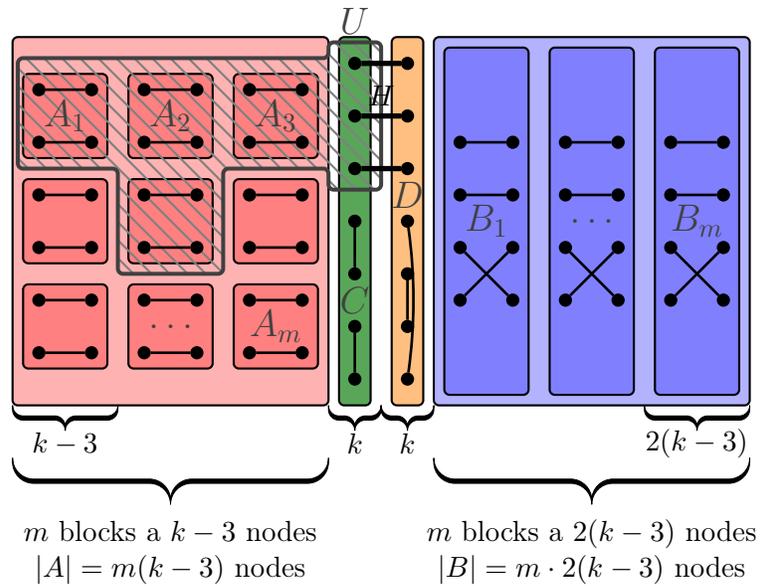


Figure 2: Visualization of a partition T together with one matching $M \in \mathcal{M}(T)$ and one cut $U \in \mathcal{U}(T)$.