

# Graph Classes with Structured Neighbourhoods

Rémy Belmonte    Martin Vatshelle

University of Bergen

June 22, 2011

# Outline

- Why are Interval graphs easy?

# Outline

- Why are Interval graphs easy?
- Representative-size.

# Outline

- Why are Interval graphs easy?
- Representative-size.
- Graph classes with bounded representative-size.

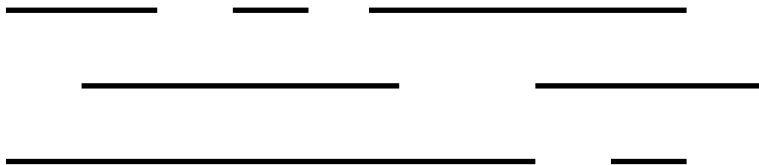
# Outline

- Why are Interval graphs easy?
- Representative-size.
- Graph classes with bounded representative-size.
- Application of our results.

# Outline

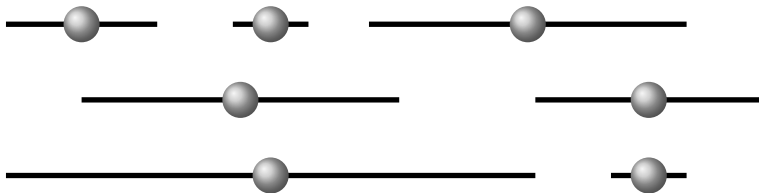
- Why are Interval graphs easy?
- Representative-size.
- Graph classes with bounded representative-size.
- Application of our results.
- Conclusion and future research.

# Interval graphs



- A collection of intervals of the real line.

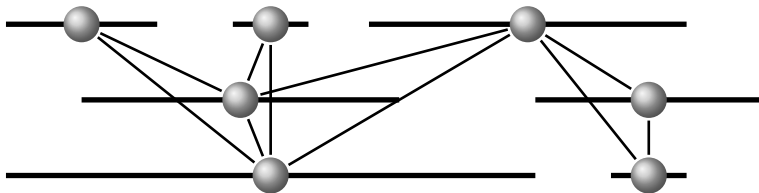
# Interval graphs



- A collection of intervals of the real line.
- Represent each interval by a node.

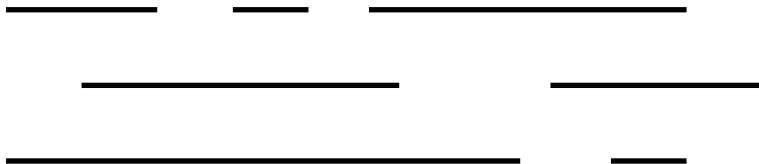


# Interval graphs



- A collection of intervals of the real line.
- Represent each interval by a node.
- If intervals intersect, their nodes are neighbours.

# Dynamic programming on Interval graphs

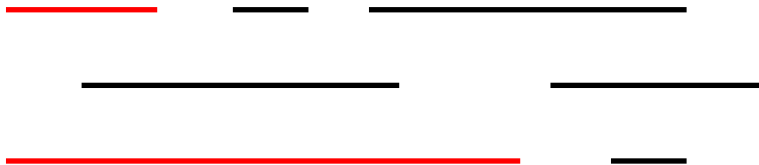


# Dynamic programming on Interval graphs



- Go through intervals from left to right.

# Dynamic programming on Interval graphs



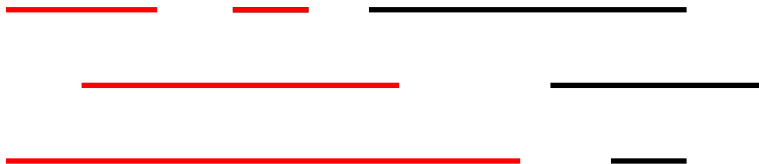
- Go through intervals from left to right.

# Dynamic programming on Interval graphs



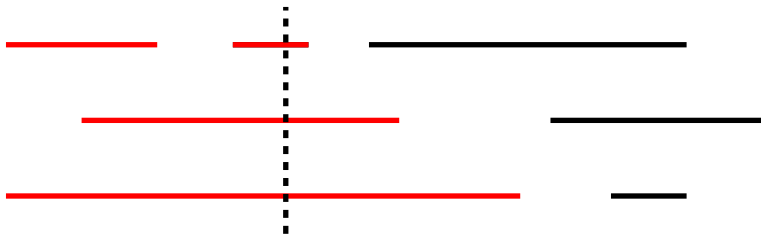
- Go through intervals from left to right.

# Dynamic programming on Interval graphs



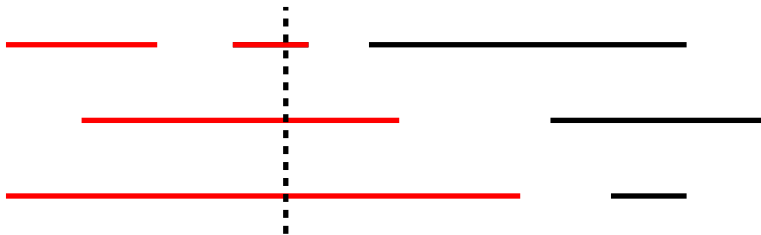
- Go through intervals from left to right.

# Dynamic programming on Interval graphs



- Go through intervals from left to right.
- Keep all the possibly optimal partial solutions.

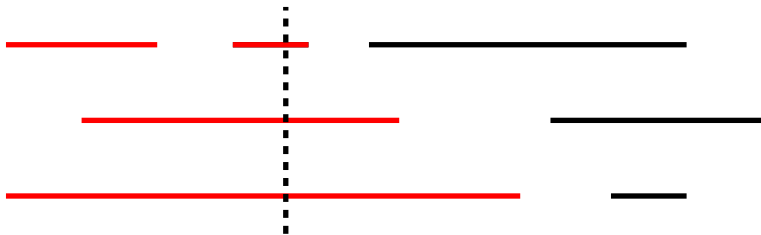
# Dynamic programming on Interval graphs



- Go through intervals from left to right.
- Keep all the possibly optimal partial solutions.
- Two solutions will be equivalent if they have the same neighbourhood across the cut.

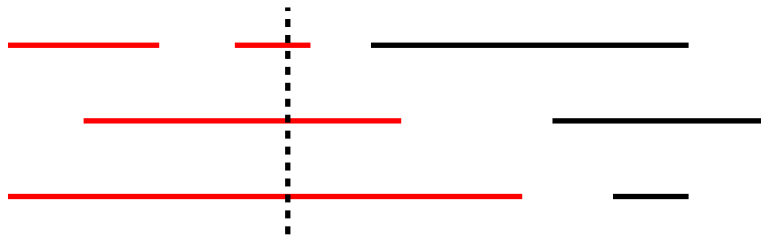


# Dynamic programming on Interval graphs



- Go through intervals from left to right.
- Keep all the possibly optimal partial solutions.
- Two solutions will be equivalent if they have the same neighbourhood across the cut.
- There is at most  $n$  different neighbourhoods.

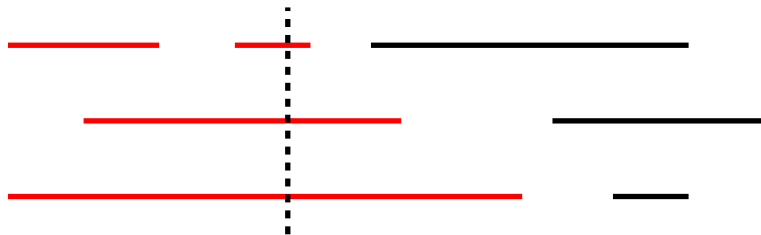
# Representative-size



## Definition (for a set)

Consider a cut  $A, B$  of a graph, and  $S \subseteq A$ , then the representative-size of  $S$  with respect to  $A$  is the minimum size of  $S' \subseteq S$  such that  $N(S) \cap B = N(S') \cap B$ .

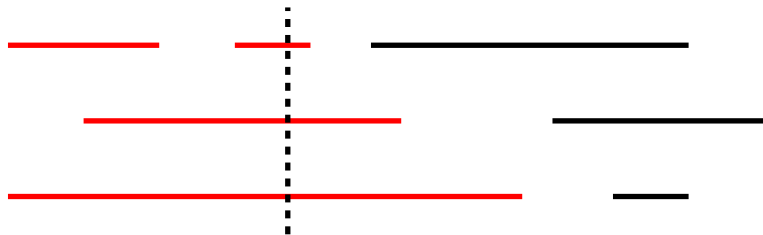
# Representative-size



## Definition (for a cut)

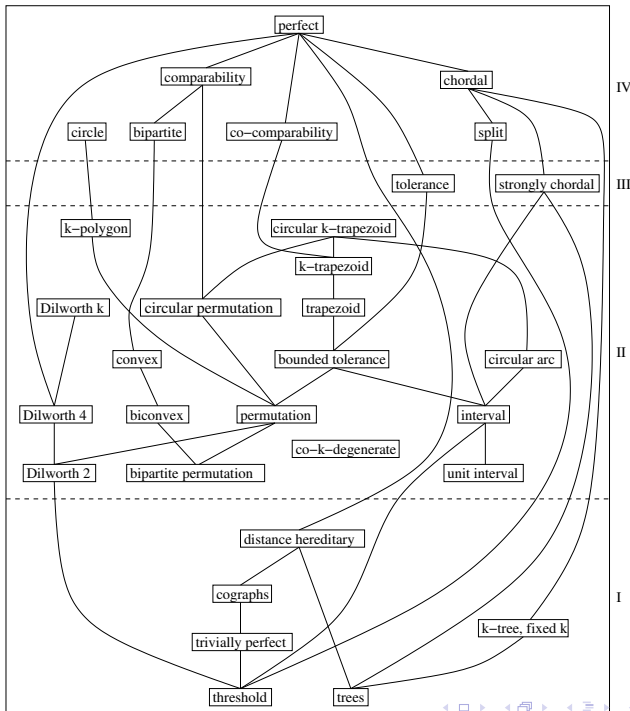
Consider a cut  $(A, B)$  of a graph, then the representative-size of  $(A, B)$  is the maximum representative-size over all  $S \subseteq A$  with respect to  $A$ .

# Representative-size



## Definition (for a graph, linear version)

A graph  $G = (V, E)$  has representative-size  $r$  if one can order the vertices such that for every  $i$  the representative-size of  $(A_i, V \setminus A_i)$  is at most  $r$ , where  $A_i$  is the set containing the  $i$  first vertices.



# Applications of our results

- The graph width parameter Boolean-width was introduced by Bui-Xuan, Telle and Vatshelle [IWPEC 2009]

# Applications of our results

- The graph width parameter Boolean-width was introduced by [BTV'09]
- representative-size  $r \Rightarrow$  boolean-width  $\leq r * \log(n)$

# Applications of our results

- The graph width parameter Boolean-width was introduced by [BTV'09]
- representative-size  $r \Rightarrow$  boolean-width  $\leq r * \log(n)$
- INDEPENDENT SET and DOMINATING SET can be solved in  $c^{\text{boolean-width}(G)} * \text{poly}(n)$  time [BTV'09]



# Applications of our results

- The graph width parameter Boolean-width was introduced by [BTV'09]
- representative-size  $r \Rightarrow$  boolean-width  $\leq r * \log(n)$
- INDEPENDENT SET and DOMINATING SET can be solved in  $c^{\text{boolean-width}(G)} * \text{poly}(n)$  time [BTV'09]

## Theorem

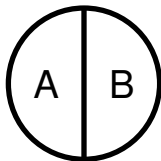
INDEPENDENT SET *and* DOMINATING SET *can be solved in polynomial time on graphs of bounded representative-size.*

# VERTEX PARTITIONING PROBLEMS

The VERTEX PARTITIONING problems was introduced by Telle and Proskurowski. [JDM 1997]

# VERTEX PARTITIONING PROBLEMS

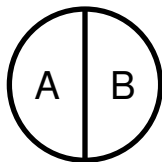
The VERTEX PARTITIONING problems by [TP'97]



INDEPENDENT SET:

# VERTEX PARTITIONING PROBLEMS

The VERTEX PARTITIONING problems by [TP'97]

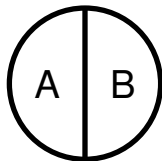


INDEPENDENT SET:

- We ask for a partition into  $(A, B)$  maximizing  $|A|$ .

# VERTEX PARTITIONING PROBLEMS

The VERTEX PARTITIONING problems by [TP'97]

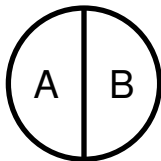


INDEPENDENT SET:

- We ask for a partition into  $(A, B)$  maximizing  $|A|$ .
- Such that every node in  $A$  has 0 neighbours in  $A$ .

# VERTEX PARTITIONING PROBLEMS

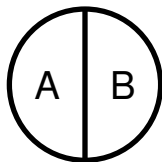
The VERTEX PARTITIONING problems by [TP'97]



DOMINATING SET:

# VERTEX PARTITIONING PROBLEMS

The VERTEX PARTITIONING problems by [TP'97]

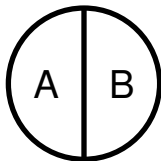


DOMINATING SET:

- We ask for a partition into  $(A, B)$  minimizing  $|A|$ .

# VERTEX PARTITIONING PROBLEMS

The VERTEX PARTITIONING problems by [TP'97]



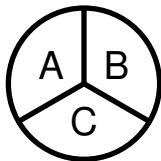
DOMINATING SET:

- We ask for a partition into  $(A, B)$  minimizing  $|A|$ .
- Every node in  $B$  has at least 1 neighbour in  $A$ .



# VERTEX PARTITIONING PROBLEMS

The VERTEX PARTITIONING problems by [TP'97]



3-coloring:

- Every node in A has 0 neighbour in A.
- Every node in B has 0 neighbour in B.
- Every node in C has 0 neighbour in C.

# VERTEX PARTITIONING PROBLEMS

The VERTEX PARTITIONING problems by [TP'97]

In general:

# VERTEX PARTITIONING PROBLEMS

The VERTEX PARTITIONING problems by [TP'97]

In general:

- We ask for a partition into  $p$  parts maximizing or minimizing one part.

# VERTEX PARTITIONING PROBLEMS

The VERTEX PARTITIONING problems by [TP'97]

In general:

- We ask for a partition into  $p$  parts maximizing or minimizing one part.
- For each ordered pair of parts we may put a requirement on the number of neighbours in the other part.

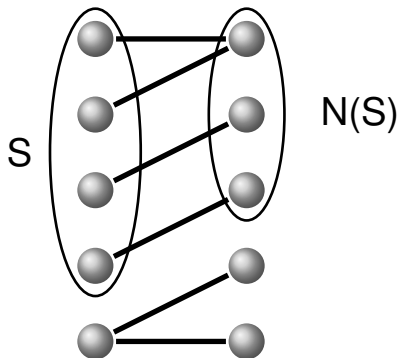
# VERTEX PARTITIONING PROBLEMS

The VERTEX PARTITIONING problems by [TP'97]

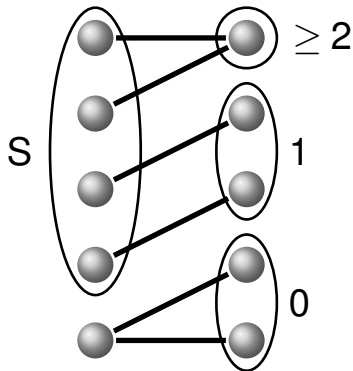
In general:

- We ask for a partition into  $p$  parts maximizing or minimizing one part.
- For each ordered pair of parts we may put a requirement on the number of neighbours in the other part.
- Requirements can be any finite or co-finite set.

# d-neighbourhood



# d-neighbourhood



# d-neighbourhood

BTV'09 use the "number of d-neighbourhoods", denoted  $UN_d(G)$ , which is related to representative-size.



# d-neighbourhood

BTV'09 use the "number of d-neighbourhoods", denoted  $UN_d(G)$ , which is related to representative-size.

## Theorem

$$UN_d \leq n^{d \cdot r}$$

# VERTEX PARTITIONING PROBLEMS

Theorem (ABTRRV, WG2010)

*Every vertex partitioning problem can be solved in time  $O^*(UN_d^{3 \cdot p})$*

# VERTEX PARTITIONING PROBLEMS

## Theorem (ABTRRV, WG2010)

*Every vertex partitioning problem can be solved in time  $O^*(UN_d^{3 \cdot p})$*

## Corollary

*Every vertex partitioning problem can be solved in time  $O^*(n^{3 \cdot d \cdot r \cdot p})$*

# Summary of results

## The problems:

INDEPENDENT SET, DOMINATING SET,  
MAXIMUM INDUCED MATCHING,  
PERFECT CODE,  $k$ -COLOURING,  
 $H$ -COVER/HOMOMORPHISM/ROLE ASSIGNMENT.

## Are polynomial on:

Interval graphs, circular arc graphs,  
permutation graphs, trapezoid graphs,  
Dilworth- $k$  graphs, convex graphs ...

# Open problems

- What is the representative-size of strongly chordal and tolerance graphs?
- Is there a graph-class with unbounded representative-size where ever VERTEX PARTITIONING problem is polynomial?
- Can we compute the representative-size?
- Can the same ideas be used on directed graphs?



Thank you!