## Special complex matrices

Definition: The Hermitian transpose of a complex matrix  $\mathbf{A} \in \mathbb{C}^{m \times n}$  is the matrix  $\mathbf{A}^{H} \in \mathbb{C}^{n \times m}$  where  $(\mathbf{A}^{H})_{i,j} = \overline{a_{j,i}}$ .

Definition: A matrix **A** is *Hermitian* if  $\mathbf{A} = \mathbf{A}^{H}$ .

Definition: A matrix **A** is unitary if  $\mathbf{A}^{-1} = \mathbf{A}^{H}$ .



### Properties

Observation: Hermitian matrices have real diagonal: If  $a_{i,i} = \overline{a_{i,i}}$ , then  $a_{i,i} \in \mathbb{R}$ .

Observation:  $(\mathbf{A}^{H})^{H} = \mathbf{A}$ ,  $(\mathbf{A}\mathbf{B})^{H} = \mathbf{B}^{H}\mathbf{A}^{H}$ 

Observation: If **A** is unitary then  $A^{H}$  is unitary.  $(\mathbf{A}^{H})^{H} = \mathbf{A} = (\mathbf{A}^{-1})^{-1} = (\mathbf{A}^{H})^{-1}$ 

Observation: The product of unitary matrices is unitary: If  $\mathbf{A}^{H} = \mathbf{A}^{-1}$  and  $\mathbf{B}^{H} = \mathbf{B}^{-1}$ , then  $(AB)^{H} = B^{H}A^{H} = B^{-1}A^{-1} = (AB)^{-1}.$ 

Observation: Any unitary **A** satisfies:  $\mathbf{A}^{H}\mathbf{A} = \mathbf{I}$ . I.e. if  $\mathbf{x}^1, \mathbf{x}^2, \dots, \mathbf{x}^n$  are columns of  $\mathbf{A}$ ,  $\mathbf{A} = \begin{vmatrix} \mathbf{x}^1 \\ \mathbf{x}^1 \end{vmatrix} \dots \begin{vmatrix} \mathbf{x}^n \\ \mathbf{x}^n \end{vmatrix}$ then  $(\mathbf{x}^i)^H \mathbf{x}^j = 0$  for  $i \neq j$  and  $(\mathbf{x}^i)^H \mathbf{x}^i = 1$ .

Fact: Any  $\mathbf{x} \in \mathbb{C}^n$  such that  $\mathbf{x}^H \mathbf{x} = 1$ can be completed to a unitary matrix.



#### Diagonalization of Hermitian matrices

Theorem: Every Hermitian matrix **A** has all eigenvalues real. Also, a unitary matrix **R** exists, such that  $\mathbf{R}^{-1}\mathbf{A}\mathbf{R}$  is diagonal.

Example: Diagonalize a Hermitian matrix  $\mathbf{A} = \begin{pmatrix} 1 & 1+i \\ 1-i & 2 \end{pmatrix}$ .  $p_{\mathbf{A}}(t) = \begin{vmatrix} 1-t & 1+i \\ 1-i & 2-t \end{vmatrix} = (1-t)(2-t) - (1-i)(1+i) = t^2 - 3t$ 

Eigenvalues of **A** are  $\lambda_1 = 3$  and  $\lambda_2 = 0$ . The corresponding unitary matrix composed from eigenvectors is:  $\mathbf{R} = \begin{pmatrix} \frac{1}{\sqrt{3}} & \frac{1+i}{\sqrt{3}} \\ \frac{1-i}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{pmatrix}$ 

$$\boldsymbol{R}^{-1} = \boldsymbol{R}^{H} = \begin{pmatrix} \frac{1}{\sqrt{3}} & \frac{1+i}{\sqrt{3}} \\ \frac{1-i}{\sqrt{3}} & -\frac{1}{\sqrt{3}} \end{pmatrix}. \text{ (Indeed } \boldsymbol{R} \text{ is self-inverse: } \boldsymbol{R}^{-1} = \boldsymbol{R}.\text{)}$$

The diagonalization goes by the product:  $\mathbf{R}^{-1}\mathbf{A}\mathbf{R} = \begin{pmatrix} 3 & 0 \\ 0 & 0 \end{pmatrix}$ . If we revert the order of the eigenvalues  $\lambda_1 = 0$ ,  $\lambda_2 = 3$ , then we get:  $\boldsymbol{S} = \begin{pmatrix} \frac{1+i}{\sqrt{3}} & \frac{1}{\sqrt{3}} \\ -\frac{1}{c} & \frac{1-i}{c} \end{pmatrix}, \ \boldsymbol{S}^{-1} = \boldsymbol{S}^{H} = \begin{pmatrix} \frac{1-i}{\sqrt{3}} & -\frac{1}{\sqrt{3}} \\ \frac{1}{c} & \frac{1+i}{c} \end{pmatrix} \text{ and } \boldsymbol{S}^{-1}\boldsymbol{A}\boldsymbol{S} = \begin{pmatrix} 0 & 0 \\ 0 & 3 \end{pmatrix}.$ 

## Proof

By induction on *n*, the theorem holds for n = 1. Denote  $A_n = A$ . In  $\mathbb{C}$ , the matrix  $A_n$  has an eigenvalue  $\lambda$  with an eigenvector x. Scale **x** by the factor  $\frac{1}{\sqrt{x^H x}}$ , to get **x** satisfying  $x^H x = 1$ . Extend (by the fact above)  $\mathbf{x}$  to a unitary matrix  $\mathbf{P}_{n}$ .  $P_n^H A_n P_n$  is Hermitian:  $(P_n^H A_n P_n)^H = P_n^H A_n^H (P_n^H)^H = P_n^H A_n P_n$ . Since  $\mathbf{A}_n \mathbf{x} = \lambda \mathbf{x}$ , the matrix  $\mathbf{A}_n \mathbf{P}_n$  has  $\lambda \mathbf{x}$  as the first column. As  $P_n$  is unitary, the first column of  $P_n^H A_n P_n$  is  $P_n^H A_n x =$  $\boldsymbol{P}_{n}^{H}(\boldsymbol{A}_{n}\boldsymbol{x}) = \boldsymbol{P}_{n}^{H}(\lambda\boldsymbol{x}) = \lambda \boldsymbol{P}_{n}^{H}\boldsymbol{x} = \lambda(1,0,\ldots,0)^{T} = (\lambda,0,\ldots,0)^{T}.$ As  $P_n^H A_n P_n$  is Hermitian,  $\lambda \in \mathbb{R}$  and the rest of the first row is  $\mathbf{0}^T$ . Hence  $P_n^H A_n P_n = \begin{vmatrix} \lambda & 0' \\ 0 & A_{n-1} \end{vmatrix}$ , where  $A_{n-1}$  is Hermitian.

By the induction hypothesis,  $R_{n-1}^{-1}A_{n-1}R_{n-1} = D_{n-1}$ for some unitary matrix  $R_{n-1}$  and a diagonal matrix  $D_{n-1}$ .

Choose 
$$\mathbf{R}_n = \mathbf{P}_n \cdot \begin{bmatrix} 1 & 0^T \\ 0 & \mathbf{R}_{n-1} \end{bmatrix}$$
, products of unitary matrices are  
unitary. Now:  
 $\mathbf{R}_n^{-1} \mathbf{A}_n \mathbf{R}_n = \mathbf{R}_n^H \mathbf{A}_n \mathbf{R}_n = \begin{bmatrix} 1 & 0^T \\ 0 & \mathbf{R}_{n-1}^H \end{bmatrix} \cdot \mathbf{P}_n^H \mathbf{A}_n \mathbf{P}_n \cdot \begin{bmatrix} 1 & 0^T \\ 0 & \mathbf{R}_{n-1} \end{bmatrix} = \begin{bmatrix} 1 & 0^T \\ 0 & \mathbf{R}_{n-1}^H \end{bmatrix} \cdot \begin{bmatrix} \lambda & 0^T \\ 0 & \mathbf{R}_{n-1} \end{bmatrix} \cdot \begin{bmatrix} 1 & 0^T \\ 0 & \mathbf{R}_{n-1} \end{bmatrix} = \begin{bmatrix} \lambda & 0^T \\ 0 & \mathbf{D}_{n-1} \end{bmatrix} = \mathbf{D}_n$ 

Theorem: Every *real symmetric* matrix A has all eigenvalues real. Also, an *orthogonal* matrix R exists, such that  $R^{-1}AR$  is diagonal. By the same proof, only the eigenvector x shall be real. Such x

exists, since the system  $(\mathbf{A} - \lambda \mathbf{I})\mathbf{x} = \mathbf{0}$  has all coefficients real.

# Example

Given 
$$\mathbf{A} = \mathbf{A}_{3} = p_{\mathbf{A}_{3}}(t) = t^{3} - 5t^{2} + 6t$$
,  

$$= \begin{pmatrix} 2 & \frac{2(1+i)}{3} & \frac{-1-i}{3} \\ \frac{2(1-i)}{3} & \frac{2}{3} & \frac{2i}{3} \\ \frac{-1+i}{3} & -\frac{2i}{3} & \frac{7}{3} \end{pmatrix}$$
we scale it to  $\mathbf{x} = \begin{pmatrix} 2 \\ 3, \frac{1}{3}, \frac{2}{3} \end{pmatrix}^{T}$ .  
We extend  $\mathbf{x}$  to unitary  
 $\mathbf{P}_{3} = \begin{pmatrix} \frac{2}{3} & -\frac{2}{3} & -\frac{1}{3} \\ \frac{1}{3} & \frac{2}{3} & -\frac{2}{3} \\ \frac{2}{3} & \frac{1}{3} & \frac{2}{3} \end{pmatrix}$  and get  
Hermitian  $= \begin{pmatrix} \frac{2}{9} & 0 & 0 \\ 0 & 1 & 1+i \\ 0 & 1-i & 2 \end{pmatrix}$   
By induction hypothesis we diagonalize  $\mathbf{R}_{2}^{-1}\mathbf{A}_{2}\mathbf{R}_{2} = \mathbf{D}_{2}$ :  
 $\begin{pmatrix} \frac{1}{3} & \frac{1+i}{3} \end{pmatrix}$  (1 = 1 + i) (2 = 1 + i))

$$\begin{pmatrix} \overline{\sqrt{3}} & \overline{\sqrt{3}} \\ \frac{1-i}{\sqrt{3}} & -\frac{1}{\sqrt{3}} \end{pmatrix} \begin{pmatrix} 1 & 1+i \\ 1-i & 2 \end{pmatrix} \begin{pmatrix} \overline{\sqrt{3}} & \overline{\sqrt{3}} \\ \frac{1-i}{\sqrt{3}} & -\frac{1}{\sqrt{3}} \end{pmatrix} = \begin{pmatrix} 3 & 0 \\ 0 & 0 \end{pmatrix}$$
  
For  
$$\mathbf{R}_{3} = \mathbf{P}_{3} \cdot \boxed{\frac{1}{0} \frac{0^{T}}{\mathbf{R}_{2}}} = \begin{pmatrix} \frac{2}{3} \frac{-3+i}{3\sqrt{3}} \frac{-1-2i}{3\sqrt{3}} \\ \frac{1}{3} \frac{2i}{3\sqrt{3}} \frac{4+2i}{3\sqrt{3}} \\ \frac{2}{3} \frac{3-2i}{3\sqrt{3}} \frac{-1+i}{3\sqrt{3}} \end{pmatrix}$$
 then holds:  $\mathbf{R}_{3}^{-1}\mathbf{A}_{3}\mathbf{R}_{3} = \mathbf{D}_{3} = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 0 \end{pmatrix}$