

Algorithmic game theory

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6th lecture

November 11th 2025



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- Later, we apply these new methods to design new fast algorithms to **approximate correlated equilibria**.
- Today, we introduce the model and some basic algorithms on how to minimize regret.

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- Until specified otherwise, we consider only loss vectors from $\{0, 1\}^N$. This is only to simplify the notation, all presented results can be extended to the general case.

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No Regret Learning (review)

No single action significantly outperforms the dynamic.



	
0	1
1	0

Weather					Loss
Algorithm					1

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Observation 2.45

For any agent A and every $T \in \mathbb{N}$, there is a sequence of T loss vectors and an agent $B \in \mathcal{A}_{all}$ such that $L_A^T - L_B^T \geq T(1 - 1/N)$.

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Algorithm 0.6: GREEDY ALGORITHM(X, T)

Input : A set of actions $X = \{1, \dots, N\}$ and number of steps $T \in \mathbb{N}$.

Output : A probability distribution p^t for every $t \in \{1, \dots, T\}$.

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Output $\{p^t : t \in \{1, \dots, T\}\}$.

Analysis of the Greedy algorithm

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Proposition 2.46

For any sequence of $\{0, 1\}$ -valued loss vectors, the cumulative loss L_{Greedy}^T of the Greedy algorithm at time $T \in \mathbb{N}$ satisfies

$$L_{\text{Greedy}}^T \leq N \cdot L_{\min}^T + (N - 1).$$

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- Proof:

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- **Proof:** At step t , if the Greedy algorithm incurs a loss of 1 and L_{\min}^t does not increase, then at least one action disappears from S^t in the next step.

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- **Proof:** At step t , if the Greedy algorithm incurs a loss of 1 and L_{\min}^t does not increase, then at least one action disappears from S^t in the next step. This occurs at most N times and then L_{\min}^t increases by 1.

Analysis of the Greedy algorithm

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□

- This is **rather weak** since A can perform roughly N times worse than the best action.

Randomized Greedy algorithm

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- There is a good reason for the poor behavior.

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Algorithm 0.19: RANDOMIZED GREEDY ALGORITHM(X, T)

Input : A set of actions $X = \{1, \dots, N\}$ and number of steps $T \in \mathbb{N}$.

Output : A probability distribution p^t for every $t \in \{1, \dots, T\}$.

Randomized Greedy algorithm

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- So it makes sense to introduce some **randomness**. We break ties at random, splitting weights between the currently best actions.

Algorithm 0.20: RANDOMIZED GREEDY ALGORITHM(X, T)

Input : A set of actions $X = \{1, \dots, N\}$ and number of steps $T \in \mathbb{N}$.

Output : A probability distribution p^t for every $t \in \{1, \dots, T\}$.

$p^1 \leftarrow (1/N, \dots, 1/N),$

Randomized Greedy algorithm

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- So it makes sense to introduce some **randomness**. We break ties at random, splitting weights between the currently best actions.

Algorithm 0.21: RANDOMIZED GREEDY ALGORITHM(X, T)

Input : A set of actions $X = \{1, \dots, N\}$ and number of steps $T \in \mathbb{N}$.

Output : A probability distribution p^t for every $t \in \{1, \dots, T\}$.

$p^1 \leftarrow (1/N, \dots, 1/N),$

for $t = 2, \dots, T$

do {

Randomized Greedy algorithm

- There is a good reason for the poor behavior. **No deterministic algorithm can perform significantly better** (Exercise).
- So it makes sense to introduce some **randomness**. We break ties at random, splitting weights between the currently best actions.

Algorithm 0.22: RANDOMIZED GREEDY ALGORITHM(X, T)

Input : A set of actions $X = \{1, \dots, N\}$ and number of steps $T \in \mathbb{N}$.

Output : A probability distribution p^t for every $t \in \{1, \dots, T\}$.

$p^1 \leftarrow (1/N, \dots, 1/N),$

for $t = 2, \dots, T$

do $\left\{ \begin{array}{l} L_{min}^{t-1} \leftarrow \min_{j \in X} \{L_j^{t-1}\}, \end{array} \right.$

Randomized Greedy algorithm

- There is a good reason for the poor behavior. **No deterministic algorithm can perform significantly better** (Exercise).
- So it makes sense to introduce some **randomness**. We break ties at random, splitting weights between the currently best actions.

Algorithm 0.23: RANDOMIZED GREEDY ALGORITHM(X, T)

Input : A set of actions $X = \{1, \dots, N\}$ and number of steps $T \in \mathbb{N}$.

Output : A probability distribution p^t for every $t \in \{1, \dots, T\}$.

$p^1 \leftarrow (1/N, \dots, 1/N),$

for $t = 2, \dots, T$

do $\begin{cases} L_{min}^{t-1} \leftarrow \min_{j \in X} \{L_j^{t-1}\}, \\ S^{t-1} \leftarrow \{j \in X : L_j^{t-1} = L_{min}^{t-1}\}, \end{cases}$

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- There is a good reason for the poor behavior. **No deterministic algorithm can perform significantly better** (Exercise).
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Algorithm 0.24: RANDOMIZED GREEDY ALGORITHM(X, T)

Input : A set of actions $X = \{1, \dots, N\}$ and number of steps $T \in \mathbb{N}$.

Output : A probability distribution p^t for every $t \in \{1, \dots, T\}$.

$p^1 \leftarrow (1/N, \dots, 1/N),$

for $t = 2, \dots, T$

do
$$\begin{cases} L_{\min}^{t-1} \leftarrow \min_{j \in X} \{L_j^{t-1}\}, \\ S^{t-1} \leftarrow \{i \in X : L_i^{t-1} = L_{\min}^{t-1}\}, \\ p_i^t \leftarrow 1/|S^{t-1}| \text{ for every } i \in S^{t-1} \text{ and } p_i^t \leftarrow 0 \text{ otherwise.} \end{cases}$$

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- There is a good reason for the poor behavior. **No deterministic algorithm can perform significantly better** (Exercise).
- So it makes sense to introduce some **randomness**. We break ties at random, splitting weights between the currently best actions.

Algorithm 0.25: RANDOMIZED GREEDY ALGORITHM(X, T)

Input : A set of actions $X = \{1, \dots, N\}$ and number of steps $T \in \mathbb{N}$.

Output : A probability distribution p^t for every $t \in \{1, \dots, T\}$.

$p^1 \leftarrow (1/N, \dots, 1/N)$,

for $t = 2, \dots, T$

do
$$\begin{cases} L_{\min}^{t-1} \leftarrow \min_{j \in X} \{L_j^{t-1}\}, \\ S^{t-1} \leftarrow \{i \in X : L_i^{t-1} = L_{\min}^{t-1}\}, \\ p_i^t \leftarrow 1/|S^{t-1}| \text{ for every } i \in S^{t-1} \text{ and } p_i^t \leftarrow 0 \text{ otherwise.} \end{cases}$$

Output $\{p^t : t \in \{1, \dots, T\}\}$.

Analysis of the Randomized greedy algorithm

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Proposition 2.48

For any sequence of $\{0, 1\}$ -valued loss vectors, the cumulative loss L_{RG}^T of the Randomized greedy algorithm at time $T \in \mathbb{N}$ satisfies

$$L_{\text{RG}}^T \leq (1 + \ln N) \cdot L_{\min}^T + \ln N.$$

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- **Proof** (sketch): We proceed as in the previous proof. For $j \in \mathbb{N}$, let t_j be the time step t at which the loss L_{\min}^t first reaches value j . We estimate the **loss of the algorithm between steps t_j and t_{j+1}** .

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$$L_{\text{RG}}^T \leq (1 + \ln N) \cdot L_{\min}^T + (1/N + 1/(N - 1) + \dots + 1/(|S^T| + 1)).$$

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$$L_{\text{RG}}^T \leq (1 + \ln N) \cdot L_{\min}^T + (1/N + 1/(N - 1) + \dots + 1/(|S^T| + 1)).$$

Polynomial weights algorithm

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Algorithm 0.30: POLYNOMIAL WEIGHTS ALGORITHM(X, T, η)

Input : A set of actions $X = \{1, \dots, N\}$, $T \in \mathbb{N}$, and $\eta \in (0, 1/2]$.

Output : A probability distribution p^t for every $t \in \{1, \dots, T\}$.

Polynomial weights algorithm

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- We overcome this issue by assigning larger **weights** to actions that are close to the best one.

Algorithm 0.31: POLYNOMIAL WEIGHTS ALGORITHM(X, T, η)

Input : A set of actions $X = \{1, \dots, N\}$, $T \in \mathbb{N}$, and $\eta \in (0, 1/2]$.

Output : A probability distribution p^t for every $t \in \{1, \dots, T\}$.

$w_i^1 \leftarrow 1$ for every $i \in X$,

Polynomial weights algorithm

- This is better, but still not optimal. The losses are greatest when the sets S^t are small since the loss can be viewed as proportional to $1/|S^t|$.
- We overcome this issue by assigning larger **weights** to actions that are close to the best one.

Algorithm 0.32: POLYNOMIAL WEIGHTS ALGORITHM(X, T, η)

Input : A set of actions $X = \{1, \dots, N\}$, $T \in \mathbb{N}$, and $\eta \in (0, 1/2]$.

Output : A probability distribution p^t for every $t \in \{1, \dots, T\}$.

$w_i^1 \leftarrow 1$ for every $i \in X$,

$p^1 \leftarrow (1/N, \dots, 1/N)$,

Polynomial weights algorithm

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Algorithm 0.33: POLYNOMIAL WEIGHTS ALGORITHM(X, T, η)

Input : A set of actions $X = \{1, \dots, N\}$, $T \in \mathbb{N}$, and $\eta \in (0, 1/2]$.

Output : A probability distribution p^t for every $t \in \{1, \dots, T\}$.

$w_i^1 \leftarrow 1$ for every $i \in X$,

$p^1 \leftarrow (1/N, \dots, 1/N)$,

for $t = 2, \dots, T$

do {

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- This is better, but still not optimal. The losses are greatest when the sets S^t are small since the loss can be viewed as proportional to $1/|S^t|$.
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Algorithm 0.34: POLYNOMIAL WEIGHTS ALGORITHM(X, T, η)

Input : A set of actions $X = \{1, \dots, N\}$, $T \in \mathbb{N}$, and $\eta \in (0, 1/2]$.

Output : A probability distribution p^t for every $t \in \{1, \dots, T\}$.

$w_i^1 \leftarrow 1$ for every $i \in X$,

$p^1 \leftarrow (1/N, \dots, 1/N)$,

for $t = 2, \dots, T$

do $\left\{ \begin{array}{l} w_i^t \leftarrow w_i^{t-1}(1 - \eta \ell_i^{t-1}), \end{array} \right.$

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- This is better, but still not optimal. The losses are greatest when the sets S^t are small since the loss can be viewed as proportional to $1/|S^t|$.
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Algorithm 0.35: POLYNOMIAL WEIGHTS ALGORITHM(X, T, η)

Input : A set of actions $X = \{1, \dots, N\}$, $T \in \mathbb{N}$, and $\eta \in (0, 1/2]$.

Output : A probability distribution p^t for every $t \in \{1, \dots, T\}$.

$w_i^1 \leftarrow 1$ for every $i \in X$,

$p^1 \leftarrow (1/N, \dots, 1/N)$,

for $t = 2, \dots, T$

do
$$\begin{cases} w_i^t \leftarrow w_i^{t-1}(1 - \eta \ell_i^{t-1}), \\ W^t \leftarrow \sum_{i \in X} w_i^t, \end{cases}$$

Polynomial weights algorithm

- This is better, but still not optimal. The losses are greatest when the sets S^t are small since the loss can be viewed as proportional to $1/|S^t|$.
- We overcome this issue by assigning larger **weights** to actions that are close to the best one.

Algorithm 0.36: POLYNOMIAL WEIGHTS ALGORITHM(X, T, η)

Input : A set of actions $X = \{1, \dots, N\}$, $T \in \mathbb{N}$, and $\eta \in (0, 1/2]$.

Output : A probability distribution p^t for every $t \in \{1, \dots, T\}$.

$w_i^1 \leftarrow 1$ for every $i \in X$,

$p^1 \leftarrow (1/N, \dots, 1/N)$,

for $t = 2, \dots, T$

do
$$\begin{cases} w_i^t \leftarrow w_i^{t-1}(1 - \eta \ell_i^{t-1}), \\ W^t \leftarrow \sum_{i \in X} w_i^t, \\ p_i^t \leftarrow w_i^t / W^t \text{ for every } i \in X. \end{cases}$$

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Output $\{p^t : t \in \{1, \dots, T\}\}$.

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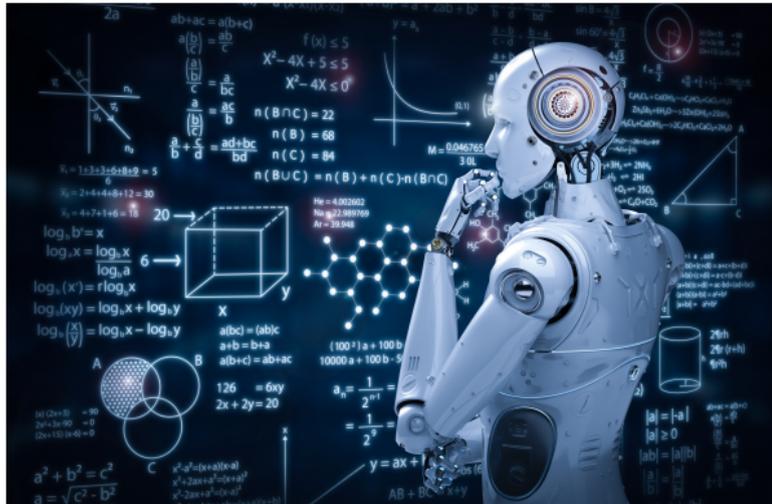
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- We do not need to know T in advance (**Exercise**).



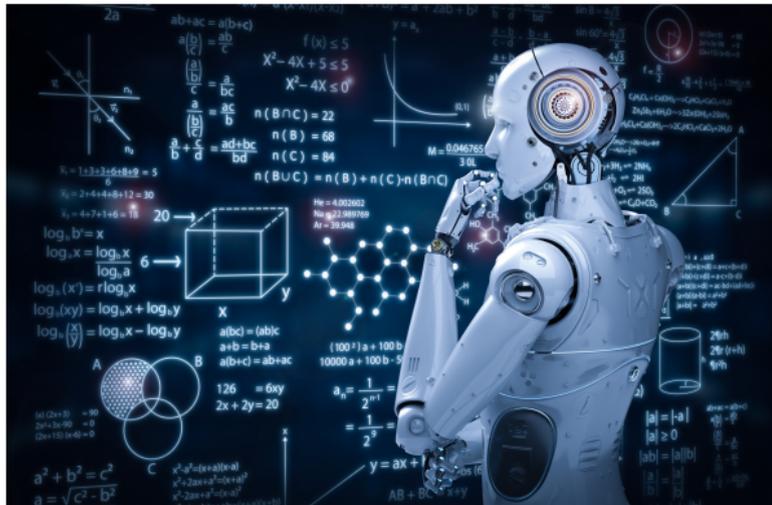
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- There are other algorithms producing small external regret, for example, the **Regret matching algorithm**.

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Algorithm 0.40: NO-REGRET DYNAMICS(G, T, ε)

Input : A normal-form game $G = (P, A, C)$ of n players, $T \in \mathbb{N}$, and $\varepsilon > 0$.

Output : A prob. distribution p_i^t on A_i for each $i \in P$ and $t \in \{1, \dots, T\}$.

for every step $t = 1, \dots, T$

do $\left\{ \begin{array}{l} \text{Each player } i \in P \text{ independently chooses a mixed strategy } p_i^t \\ \text{using an algorithm with average regret at most } \varepsilon, \text{ with actions} \\ \text{corresponding to pure strategies.} \\ \text{Each player } i \in P \text{ receives a loss vector } \ell_i^t = (\ell_i^t(a_i))_{a_i \in A_i}, \text{ where} \\ \ell_i^t(a_i) \leftarrow \mathbb{E}_{a_{-i} \sim p_{-i}^t} [C_i(a_i; a_{-i})] \text{ for the product distribution} \\ p_{-i}^t = \prod_{j \neq i} p_j^t. \end{array} \right.$

Output $\{p^t : t \in \{1, \dots, T\}\}$.



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Algorithm 2.6.4: NO-REGRET DYNAMICS(G, T, ε)

Input : A normal-form game $G = (P, A, C)$ of n players, $T \in \mathbb{N}$ and $\varepsilon > 0$.

Output : A probability distribution p_i^t on A_i for each $i \in P$ and $t \in \{1, \dots, T\}$.

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do { Each player $i \in P$ independently chooses a mixed strategy p_i^t using an algorithm with average regret at most ε , with actions corresponding to pure strategies.
Each player $i \in P$ receives a loss vector $\ell_i^t = (\ell_i^t(a_i))_{a_i \in A_i}$, where $\ell_i^t(a_i) \leftarrow \mathbb{E}_{a_{-i}^t \sim \sigma_{-i}^t} [C_i(a_i; a_{-i}^t)]$ for the product distribution $\sigma_{-i}^t = \prod_{j \neq i} p_j^t$.

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Sources: Students of MFF UK

Thank you for your attention.