

Algorithmic game theory

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5th lecture

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Nash equilibria in bimatrix games

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- **Is there a chance to get an efficient algorithm?**
- **NASH** = the problem of finding NE in bimatrix games.
- Today, we discuss the **computational complexity of NASH**.

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- Without proof (but you can find it in the lecture notes).

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 - Thus, G can be exponentially large with respect to the input.
- Let **PPAD** be a complexity class consisting of problems that admit a polynomial-time reduction to END-OF-THE-LINE.

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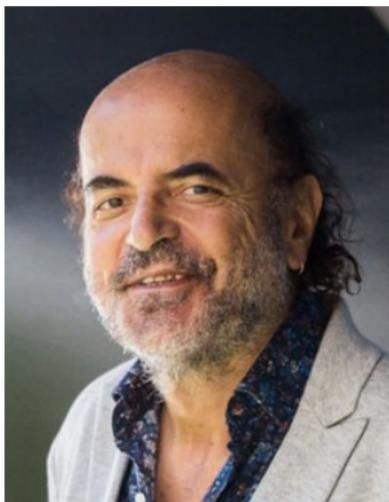


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- Abbreviation for “Polynomial Parity Arguments on Directed graphs”.
- This complexity class contains a lot of well-known problems.

Problems from PPAD: End-of-the-line

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- For an oriented graph G with max. indegree and outdegree 1 and a source in G , find a target in G . The graph is given by a polynomial-time computable function $f(v)$ that returns predecessor and successor of v .

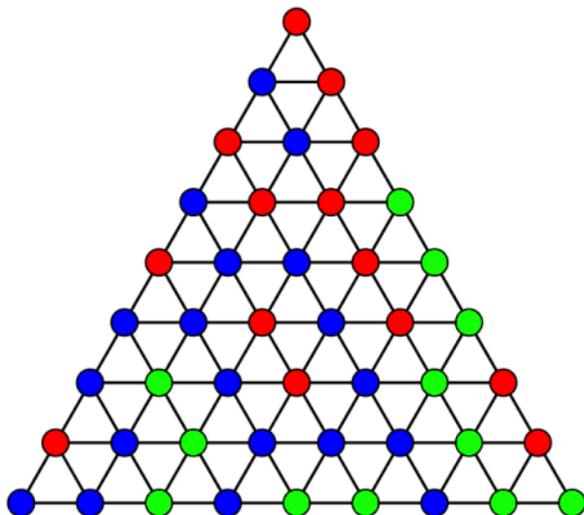
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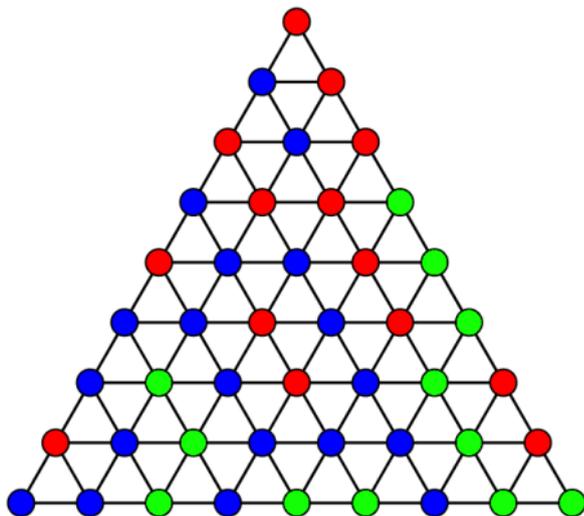
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Source: <https://lesswrong.com>

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- Discrete version of the **Brouwer's fixed point theorem**.

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- An approximate version of the following theorem is in PPAD: For each $d \in \mathbb{N}$, a non-empty compact convex set K in \mathbb{R}^d , and a continuous mapping $f: K \rightarrow K$, there exists $x_0 \in K$ such that $f(x_0) = x_0$.



Figure: L. E. J. Brouwer (1881–1966).

Problems from PPAD: Ham sandwich theorem



Source: <https://www.seekpng.com/>

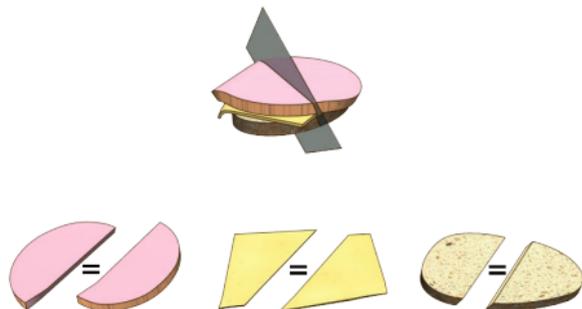
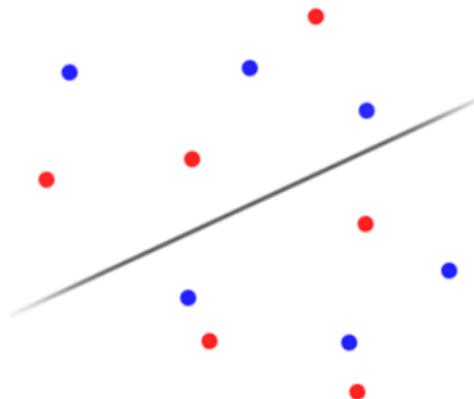
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Sources: <https://ejarzo.github.io> and <https://curiosamathematica.tumblr.com>

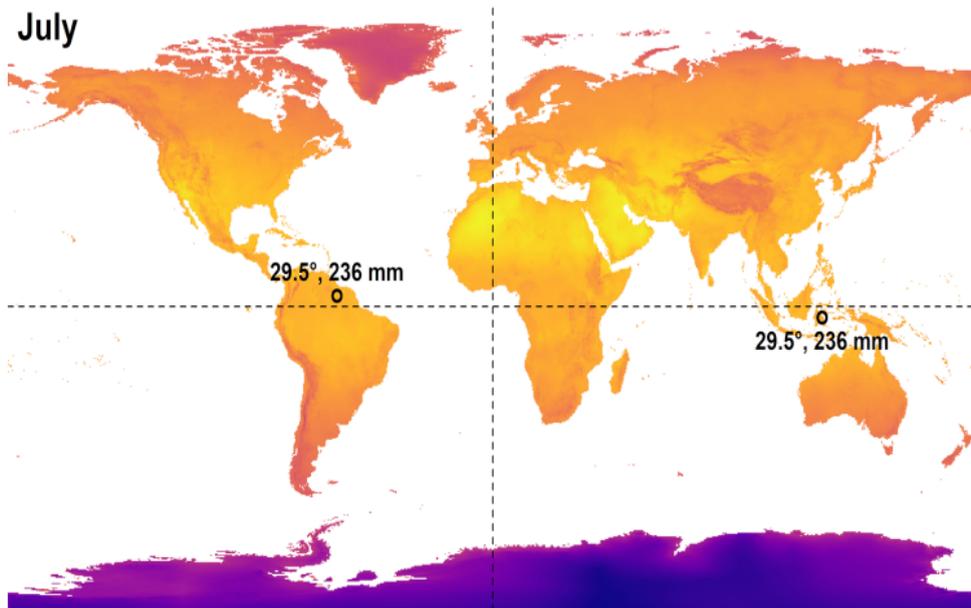
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Source: <https://scientificgems.wordpress.com/>

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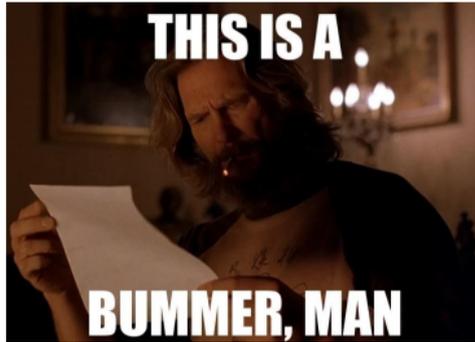
The problem **NASH is PPAD-complete**.

- One of the main breakthroughs in algorithmic game theory.
- We omit the proof, as it is complicated (the papers have over 50 and 70 pages, respectively).

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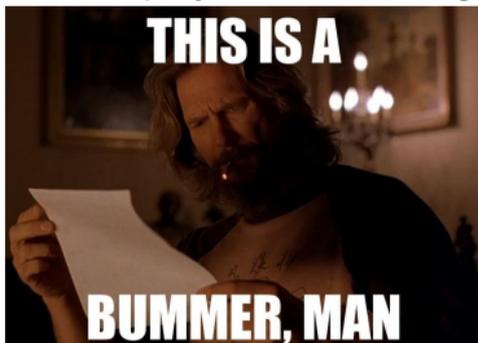
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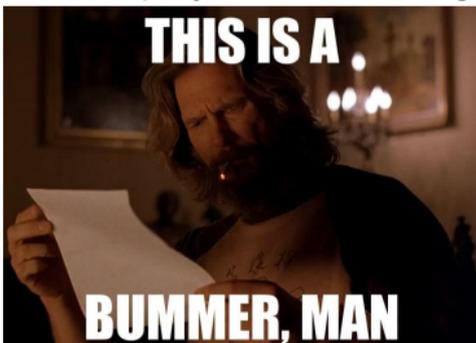
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- This seems to be a **problem with the concept of NE**. “How can we expect the players to find a Nash equilibrium, if our computers cannot?”
- We introduce **other solution concepts** that possess some qualities of NE and yet are easier to compute.

Other notions of equilibria

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 - The second one will have a rather complicated definition at first sight, but we will later learn to appreciate it and see that it might be even **more natural than NE!**

ϵ -Nash equilibria

ε -Nash equilibria

- For $\varepsilon > 0$, a strategy profile $s = (s_1, \dots, s_n)$ in a normal-form game $G = (P, A, u)$ is an ε -Nash equilibrium (ε -NE) if, for every player $i \in P$ and every $s'_i \in S_i$, we have $u_i(s_i; s_{-i}) \geq u_i(s'_i; s_{-i}) - \varepsilon$.

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 - ε -NE always exist by Nash's theorem

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- Advantages:
 - Easy-to-understand definition
 - ε -NE always exist by Nash's theorem (every NE is ε -NE).

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- For $\varepsilon > 0$, a strategy profile $s = (s_1, \dots, s_n)$ in a normal-form game $G = (P, A, u)$ is an ε -Nash equilibrium (ε -NE) if, for every player $i \in P$ and every $s'_i \in S_i$, we have $u_i(s_i; s_{-i}) \geq u_i(s'_i; s_{-i}) - \varepsilon$.
 - That is, no other strategy can improve the payoff by more than ε .
 - If we allowed $\varepsilon = 0$, we would get the standard NE.
- Advantages:
 - Easy-to-understand definition
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- For $\epsilon > 0$, a strategy profile $s = (s_1, \dots, s_n)$ in a normal-form game $G = (P, A, u)$ is an ϵ -Nash equilibrium (ϵ -NE) if, for every player $i \in P$ and every $s'_i \in S_i$, we have $u_i(s_i; s_{-i}) \geq u_i(s'_i; s_{-i}) - \epsilon$.
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- Disadvantages:
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 - We will see that his concept is also somehow computationally difficult.

Algorithmic aspects of ε -Nash equilibria

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Theorem 2.37 (Lipton, Markakis, and Mehta, 2003)

Let $G = (P, A, u)$ be a normal-form game of two players, each having m actions, such that the payoff matrices have entries in $[0, 1]$. For every $\varepsilon > 0$, there is an **algorithm for computing ε -NE of G in time $m^{O(\log m/\varepsilon^2)}$** .

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- I no longer present the proof (see the lecture notes).

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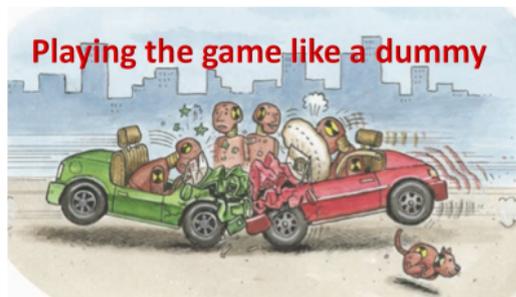
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Example of correlated equilibria: Game of Chicken

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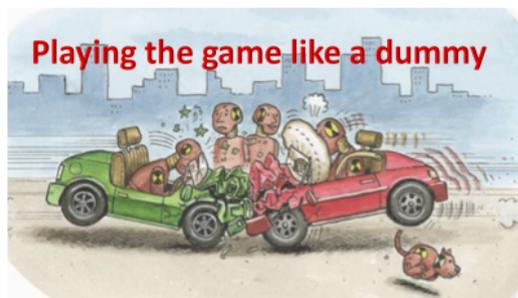
	Stop	Go
Stop	$(0,0)$	$(-1,1)$
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Sources: <https://peakd.com/>

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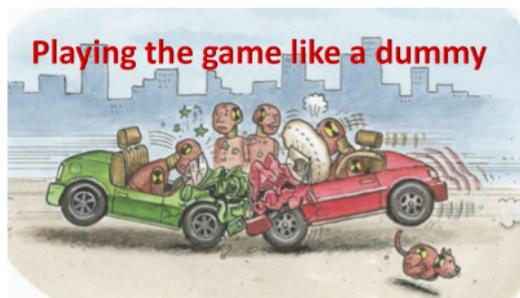


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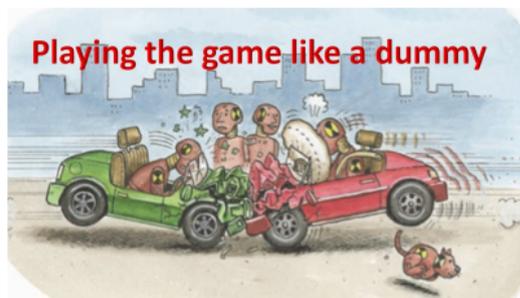


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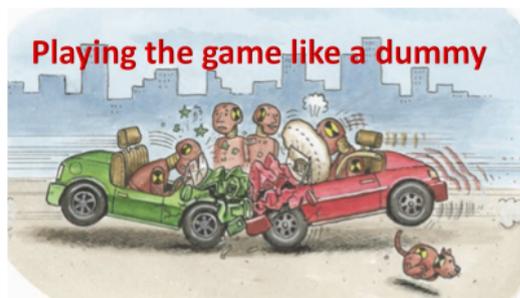


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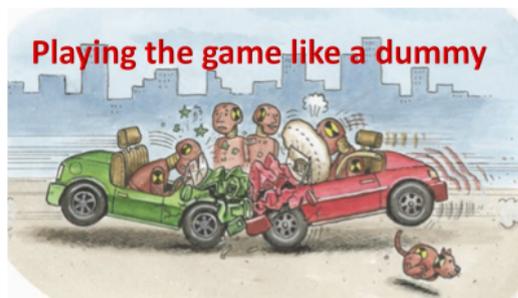


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 - If 1 follows the suggestion "go", then he gets 1 while deviating gives him 0.

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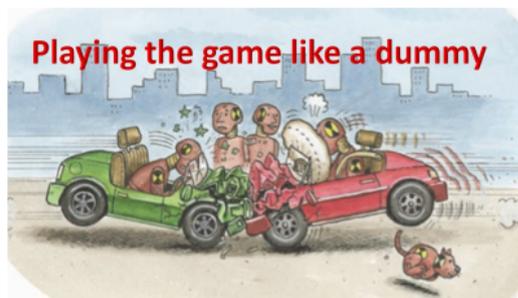


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 - If 1 follows the suggestion "go", then he gets 1 while deviating gives him 0.
 - If 1 follows the suggestion "stop", then he gets $-1/2$ while deviating gives him $-9/2$.
 - By symmetry, driver 2 does not deviate as well.





Source: Students of MFF UK

Example of correlated equilibria: Battle of sexes

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	Football	Opera
Football	(2,1)	(0,0)
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 - If the husband follows the suggestion “football”, then he gets 2 while deviating gives him 0.

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Sources: <https://media.istockphoto.com/>

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- Consider a trusted third party, a **mother-in-law**. The mother-in-law flips a coin and chooses (F, F) or (O, O) independently at random with probability $1/2$. **The mother-in-law gives CE.**
 - If the husband follows the suggestion “football”, then he gets 2 while deviating gives him 0.
 - If the husband follows the suggestion “opera”, then he gets 1 while deviating gives him 0.
 - By symmetry, the wife does not deviate as well.

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- The objective function can be arbitrary as long as it is linear.



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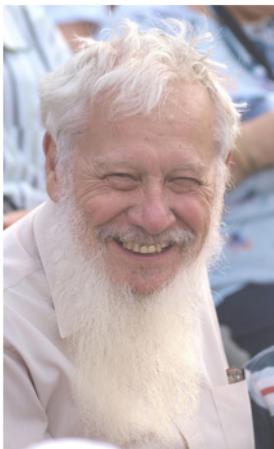


Figure: **Robert Aumann** (born 1930).

Sources: <https://en.wikipedia.org> and <https://slideslive.com/38910863/strategic-information-theory>

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Thank you for your attention.