Overview

- Directive forward
- Standard units,
- Pointers.

It is typical that one function calles another but

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- until we find the forward directive!
- This directive is placed after the function prototype:

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- sometimes functions also call each other.
- Problem: In Pascal we can only use a function once it has been defined.
- Cyclic dependences seem unsolvable...
- until we find the forward directive!
- This directive is placed after the function prototype:
- procedure two(a:integer);forward;

Forward example:

```
program qq;
   procedure two(a:integer);forward;
   procedure one(a:integer);
    begin
          two(a);
   end;
   procedure two(a:integer);
    begin
          one(a);
   end;
   begin
          one(1):
           {Let us ignore that this program does
   not make a lot of sense!}
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    and
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```

circular (instead of nil point at the first)

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- without head/tail

- circular (instead of nil point at the first)
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- without head/tail
- bidirectional (pointers next and prev).

 Queue is a data structure that organizes its elements in a FIFO-way,

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- Buffer is a data structure that organizes its elements in a LIFO-way,
- it is equipped with functions push and pop (or pull).
- It is possible to implement them using arrays,...
- but it is much better to use linked lists!

Buffer Implementation I/III

```
type pbuf=^buf;
buf=record
    val:integer;
    next:pbuf;
end;
var head:pbuf;
procedure init;
begin head:=nil;
end;
```

Buffer

Implementation II/III

```
type pbuf=^buf;
buf=record
     val:integer;
     next:pbuf;
end;
var head:pbuf;
procedure push(what:integer);
var tmp:pbuf;
begin
     new(tmp);
     tmp<sup>^</sup>.val:=what;
     tmp^.next:=head;
     head:=tmp;
```

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end:

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Buffer

Implementation III

```
function pop:integer;
var tmp:pbuf;
begin
     tmp:=head;
     if head<>nil then
     begin pop:=head^.val;
          head:=tmp^.next;
          dispose(pom);
     end else
     begin writeln('Error!');
          pop:=-1;
     end;
```

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Queue

```
type=pq=^queue;
queue=record
    val:integer;
    next:pq;
end;
var head,tail:pq;
procedure init;
begin
    head:=nil; tail:=nil; end;
```

```
procedure enqueue(what:integer);
var tmp:pq;
begin if head=nil then
     begin new(head);
           tail:=head;
           head<sup>^</sup>.next:=nil;
           head^.val:=what;
     end else
     begin new(tmp);
           tmp^.next:=nil;
           tmp<sup>^</sup>.val:=what;
           head^.next:=tmp;
           head:=tmp;
     end;
end;
```

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```
function dequeue:integer;
   var tmp:pq;
   begin if head=nil then
          begin dequeue:=-1;
          end else
          begin if head=tail then
                 begin dequeue:=tail^.val;
                       dispose(tail);
                       head:=nil; tail:=nil;
                 end else
                 begin dequeue:=tail^.val;
                       tmp:=tail;
                       tail:=tail^.next;
                       dispose(tmp);
                 end;
          end;
   end;
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Switch two neighboring elements Switch an element in a linked list with its neighbor

```
procedure swap(var head:ll;what:ll);
var tmp:ll;
begin tmp:=head;
      if head=what then
      begin head:=head^.next;
            tmp^.next:=head^.next;
            head^.next:=tmp;
      end else
      begin while(tmp^.next<>what) do
                  tmp:=tmp^.next;
            tmp^.next:=what^.next;
            what^.next:=tmp^.next^.next;
            tmp^.next^.next:=what;
```

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Dynamic data structures

The examples sometimes omit singularities (empty list, an element not in the list, one-element-list...). All this would be implemented by several tests for nil.

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Good exercise: Bubblesort over linked list.

Dynamic data structures

- The examples sometimes omit singularities (empty list, an element not in the list, one-element-list...). All this would be implemented by several tests for nil.
- Good exercise: Bubblesort over linked list.
- Organizing (an ordered) linked list (functions insert, delete and member that work with the ordered linked list).

A linked list may be ordered (with respect to the values of the elements, w.l.o.g. in a non-decreasing order).

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- For such lists we usually implement functions:
 - member says whether an element with an appropriate key is in the list,
 - insert inserts an element into a list,
 - delete deletes an element from a list.
- Example see webpage (or we are going to write it here).
Self-organizing lists – lists that get modified by accessing them.

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Move-front rule, transposition rule:

- Self-organizing lists lists that get modified by accessing them.
- Move-front rule, transposition rule:
- When accessing a member, we move it to the beginning or change with its (immediate) predecessor, respectively.

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- Self-organizing lists lists that get modified by accessing them.
- Move-front rule, transposition rule:
- When accessing a member, we move it to the beginning or change with its (immediate) predecessor, respectively.
- Idea: Usually we are accessing the same element repeatedly (in a short time) but our interests are changing.

■ In a linked list, it is a problem to search for an element.

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■ It takes a linear time, we want something better.

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- We want to implement a data structure where binary search is possible.

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- The natural idea is to create a binary search tree (smaller values in the left subtree, larger in the right one).

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- The natural idea is to create a binary search tree (smaller values in the left subtree, larger in the right one).
- How does one implement this?
- Each element gets more than one ancestor (left, right).

Tree representation

in Pascal

```
type tree=^vertex;
    vertex=record
    val:longint;
    left:tree;
    right:tree;
    ...
end;
```

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- But if we build it badly, it collapses into a linked list.

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- If we build it well, it becomes more efficient than a linked list.
- But if we build it badly, it collapses into a linked list.
- How do we build a balanced binary search tree (and how to keep the tree balanced)?
- A balanced BST is a tree where for each element the # elements in the left subtree (of this element) and the #

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Find a median and make it the root of the tree.

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- Find a median and make it the root of the tree.
- Build a balanced BST on all smaller elements (recursively),

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- build a balanced BST on all larger elements (recursively),
- set these trees to be siblings of the root.

BST – data structures

- We are going to build from an array (uninteresting [obvious])
- Dynamic data structure that represents nodes [vertices] of the tree:

```
type pbst:^bst;
    bst=record
    val:longint;
    left:pbst;
    right:pbst;
```

Building a balanced BST (pseudocode)

```
function build(array):pbst;
begin
      if empty(array) then build:=nil; else begin
            med:=median(array);
            small:=smaller(med,array);
            large:=larger(med,array);
            new(root):
            root^.hod:=med;
            root^.left:=build(small);
            root^.right:=build(large);
            build:=root:
      end;
```

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end;

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Further operations on balanced BST

member, insert, delete

```
Operation member is simple:
function member(what:longint,where:pbst):pbst;
begin if where=nil then member:=nil
else if where^.val=what then member:=where
else if where^.val>what then
member:=member(where^.left)
else member:=member(where^.right);
```

end;

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- Beware of the algorithm's implicit logic using trichotomy (i.e., the third branch ensures that where^.val<what)</p>
- Function insert and delete are almost unimplementable (it would be necessary to destruct the whole tree).

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far from being balanced!

```
procedure insert(what, where);
begin {Marginal cases!}
      while((( what<where^,val) and
(where<sup>^</sup>.left<>nil)) or
             ((what>where<sup>^</sup>.val)and
(where^.right<>nil)))
             if(what<where^.val) then
where:=where^.left
             else where:=where^.right;
      if(what=where^.val) then error("Already
there!");
      if(what<where^.val) then
      begin new(where^.left);
             kam:=where^.left:
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                                                         3
```

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BST – delete – bad version

Find an element,

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BST – delete – bad version

Find an element,

■ if it has out-degree at most 1, delete it (or bypass it).

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BST - delete - bad version

- Find an element,
- if it has out-degree at most 1, delete it (or bypass it).
- With an out-degree 2, add its left son as the left son of the left-most element in the right subtree,

now the erased element has an out-degree 1.

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- With an out-degree 2, add its left son as the left son of the left-most element in the right subtree,

now the erased element has an out-degree 1.

- What's wrong?
- In a short time the tree looks like a linked list.

BST – delete – correct version

Find an element,



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BST - delete - correct version

Find an element,

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BST - delete - correct version

- Find an element,
- With an out-degree at most 1, delete it (or bypass it).
- Otherwise find the left-most element in the right subtree and switch these elements.

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BST - delete - correct version

- Find an element,
- With an out-degree at most 1, delete it (or bypass it).
- Otherwise find the left-most element in the right subtree and switch these elements.
- We violate the property of a BST for a while!

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delete it (bypass).

BST - delete - correct version

- Find an element,
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- Otherwise find the left-most element in the right subtree and switch these elements.
- We violate the property of a BST for a while!
- \blacksquare Now, the deleted vertex (on the incorrect location) has an out-degree at most 1 \Rightarrow
- delete it (bypass).
- Instead of the left-most element in the right subtree we may use the right-most element in the left subtree (as it has the closest value to the erased element). This way we keep the pivoting properties of the erased element.

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Generally, it is an unpleasant problem.

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- Generally, it is an unpleasant problem.
- Because of this, AVL-trees which have a slightly relaxed notion of balancedness got introduced.

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AVL – Adelson-Velskij and Landis.

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- after insert and delete we perform the balance-renewing operations.
- For each vertex we define a value balance saying depth_right - depth_left, permitted values are -1, 0 and 1.

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Problem appears with balance WLOG 2.

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- Problem appears with balance WLOG 2.
- We start solving on the bottom-most level with this balance.

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- We explore two possibilities, the remaining 2 are symmetric.

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The tree may be falling "to the side" or "to the interior".

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- The tree may be falling "to the side" or "to the interior".
- In the former case we use a rotation, in the latter a double-rotation.

Rotation Tree is falling "to the side".



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Double-rotation

Tree is falling "to the interior".



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Analysis and remarks

rotation, double-rotation, depths

• While inserting, one rotation (or double-rotation) suffices.

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■ While inserting, one rotation (or double-rotation) suffices.

Delete may start a cascade of rotations (the distortion is travelling towards the root).

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Number of elements in an AVL-tree with depth *n*:

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- thus the depth is logarithmic w.r.t. number of elements.

Another method how to keep the tree sufficiently spread.

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Programování I

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FIXME!!!

A-B-trees, k-ary tree canonical representation.

Passing a function as an argument.

A queue and a buffer,

graph-searching algorithms (including graph representation). Odstrasujici priklady (slidy10.tex for mathematicians).

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