

Overview

- Directive forward
- Standard units,
- Pointers.

Directive forward

- It is typical that one function calls another but
- sometimes functions also call each other.
- Problem: In Pascal we can only use a function once it has been defined.
- Cyclic dependences seem unsolvable...
- until we find the `forward` directive!
- This directive is placed after the function prototype:
- `procedure two(a:integer);forward;`

Forward example:

```
program qq;
procedure two(a:integer);forward;
procedure one(a:integer);
begin
    two(a);
end;
procedure two(a:integer);
begin
    one(a);
end;
begin
    one(1);
    {Let us ignore that this program does
not make a lot of sense!}
end;
```

Linked list typology

- circular (instead of `nil` point at the first)
- with a head (first element is not a member)
- with a tail (last element is not a member)
- without head/tail
- bidirectional (pointers `next` and `prev`).

A Queue and a Buffer

- Queue is a data structure that organizes its elements in a FIFO-way,
- it is equipped with functions `enqueue` and `dequeue`.
- Buffer is a data structure that organizes its elements in a LIFO-way,
- it is equipped with functions `push` and `pop` (or `pull`).
- It is possible to implement them using arrays,...
- but it is much better to use linked lists!

Buffer

Implementation I/III

```
type pbuf = ^buf;
buf = record
    val: integer;
    next: pbuf;
end;
var head: pbuf;
procedure init;
begin head := nil;
end;
```

Buffer

Implementation II/III

```
type pbuf=^buf;
buf=record
    val:integer;
    next:pbuf;
end;
var head:pbuf;
procedure push(what:integer);
var tmp:pbuf;
begin
    new(tmp);
    tmp^.val:=what;
    tmp^.next:=head;
    head:=tmp;
end;
```

Buffer

Implementation III

```
function pop:integer;
var tmp:pbuf;
begin
    tmp:=head;
    if head<>nil then
    begin pop:=head^.val;
        head:=tmp^.next;
        dispose(pom);
    end else
    begin writeln('Error!');
        pop:=-1;
    end;
end;
```


Queue

Implementation

```
type=pq=^queue;
queue=record
    val:integer;
    next:pq;
end;
var head,tail:pq;
procedure init;
begin
    head:=nil;      tail:=nil; end;
```

```
procedure enqueue(what:integer);
var tmp:pq;
begin if head=nil then
    begin new(head);
        tail:=head;
        head^.next:=nil;
        head^.val:=what;
    end else
    begin new(tmp);
        tmp^.next:=nil;
        tmp^.val:=what;
        head^.next:=tmp;
        head:=tmp;
    end;
end;
```

```
function dequeue:integer;
var tmp:pq;
begin if head=nil then
    begin dequeue:=-1;
    end else
    begin if head=tail then
        begin dequeue:=tail^.val;
            dispose(tail);
            head:=nil; tail:=nil;
        end else
        begin dequeue:=tail^.val;
            tmp:=tail;
            tail:=tail^.next;
            dispose(tmp);
        end;
    end;
end;
```

Switch two neighboring elements

Switch an element in a linked list with its neighbor

```
procedure swap(var head:ll;what:ll);
var tmp:ll;
begin tmp:=head;
      if head=what then
      begin head:=head^.next;
           tmp^.next:=head^.next;
           head^.next:=tmp;
      end else
      begin while(tmp^.next<>what) do
           tmp:=tmp^.next;
           tmp^.next:=what^.next;
           what^.next:=tmp^.next^.next;
           tmp^.next^.next:=what;
      end; end;
```

Dynamic data structures

- The examples sometimes omit singularities (empty list, an element not in the list, one-element-list...). All this would be implemented by several tests for `nil`.
- Good exercise: Bubblesort over linked list.
- Organizing (an ordered) linked list (functions `insert`, `delete` and `member` that work with the ordered linked list).

Ordered list

- A linked list may be ordered (with respect to the values of the elements, w.l.o.g. in a non-decreasing order).
- For such lists we usually implement functions:
 - `member` – says whether an element with an appropriate key is in the list,
 - `insert` – inserts an element into a list,
 - `delete` – deletes an element from a list.
- Example – see webpage (or we are going to write it here).

Further data structures

- Self-organizing lists – lists that get modified by accessing them.
- Move-front rule, transposition rule:
- When accessing a member, we move it to the beginning or change with its (immediate) predecessor, respectively.
- Idea: Usually we are accessing the same element repeatedly (in a short time) but our interests are changing.

Trees

- In a linked list, it is a problem to search for an element.
- It takes a linear time, we want something better.
- We want to implement a data structure where binary search is possible.
- The natural idea is to create a binary search tree (smaller values in the left subtree, larger in the right one).
- How does one implement this?
- Each element gets more than one ancestor (left, right).

Tree representation

in Pascal

```
type tree = ^vertex;
      vertex = record
          val: longint;
          left: tree;
          right: tree;
          ...
      end;
```

Binary search trees

- A binary tree is a tree in which each element has at most two ancestors.
- A binary search tree is a binary tree which for each element with a key K contains values with keys smaller than K in the left subtree and values with the key larger than K in the right subtree.
- In this way it becomes possible to search efficiently in a tree. Advantages/disadvantages?
- If we build it well, it becomes more efficient than a linked list.
- But if we build it badly, it collapses into a linked list.
- How do we build a balanced binary search tree (and how to keep the tree balanced)?
- A balanced BST is a tree where for each element the # elements in the left subtree (of this element) and the # elements in the right subtree differ at most by 1.

Building a balanced BST

- Find a median and make it the root of the tree.
- Build a balanced BST on all smaller elements (recursively),
- build a balanced BST on all larger elements (recursively),
- set these trees to be siblings of the root.

BST – data structures

- We are going to build from an array (uninteresting [obvious])
- Dynamic data structure that represents nodes [vertices] of the tree:

```
type pbst: ^bst;  
    bst=record  
        val: longint;  
        left: pbst;  
        right: pbst;
```

Building a balanced BST

(pseudocode)

```
function build(array):pbst;
begin
    if empty(array) then build:=nil; else begin
        med:=median(array);
        small:=smaller(med,array);
        large:=larger(med,array);
        new(root);
        root^.hod:=med;
        root^.left:=build(small);
        root^.right:=build(large);
        build:=root;
    end;
end;
```

Further operations on balanced BST

member, insert, delete

- Operation member is simple:

```
function member(what:longint,where:pbst):pbst;  
begin if where=nil then member:=nil  
      else if where^.val=what then member:=where  
           else if where^.val>what then  
                member:=member(where^.left)  
           else member:=member(where^.right);  
end;
```

- Beware of the algorithm's implicit logic using trichotomy (i.e., the third branch ensures that $where^.val < what$)
- Function insert and delete are almost unimplementable (it would be necessary to destruct the whole tree).

Binary search tree

far from being balanced!

```
procedure insert(what,where);
begin {Marginal cases!}
    while((( what<where^.val) and
(wHERE^.left<>nil)) or
        ((what>where^.val)and
(wHERE^.right<>nil)))
        if(what<where^.val) then
where:=where^.left
        else where:=where^.right;
    if(what=where^.val) then error("Already
there!");
    if(what<where^.val) then
begin new(where^.left);
    kam:=where^.left;
```

BST – delete – bad version

- Find an element,
- if it has out-degree at most 1, delete it (or bypass it).
- With an out-degree 2,
add its left son as the left son of the left-most element in the right subtree,
now the erased element has an out-degree 1.
- What's wrong?
- In a short time the tree looks like a linked list.

BST – delete – correct version

- Find an element,
- With an out-degree at most 1, delete it (or bypass it).
- Otherwise find the left-most element in the right subtree and switch these elements.
- We violate the property of a BST for a while!
- Now, the deleted vertex (on the incorrect location) has an out-degree at most 1 \Rightarrow
- delete it (bypass).
- Instead of the left-most element in the right subtree we may use the right-most element in the left subtree (as it has the closest value to the erased element). This way we keep the pivoting properties of the erased element.

Balancedness

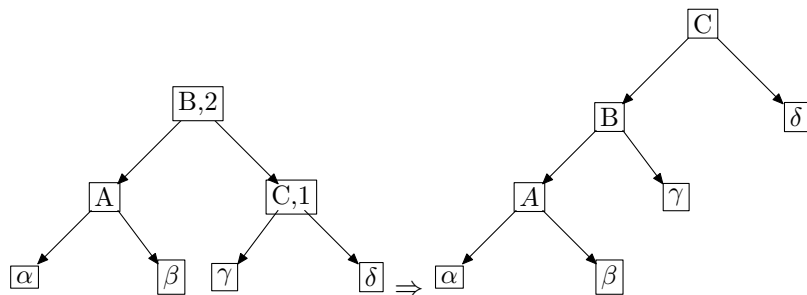
- Generally, it is an unpleasant problem.
- Because of this, AVL-trees which have a slightly relaxed notion of balancedness got introduced.
- An AVL-tree is a BST where for each element the depth of the left subtree differs at most by 1 from the depth of the right subtree.
- AVL – Adelson-Velskij and Landis.
- Operations `member`, `insert` and `delete` are the same as for BST, just
- after `insert` and `delete` we perform the balance-renewing operations.
- For each vertex we define a value `balance` saying `depth_right - depth_left`, permitted values are -1, 0 and 1.

Balance-renewing operations

- Problem appears with balance WLOG 2.
- We start solving on the bottom-most level with this balance.
- We explore two possibilities, the remaining 2 are symmetric.
- The tree may be falling "to the side" or "to the interior".
- In the former case we use a rotation, in the latter a double-rotation.

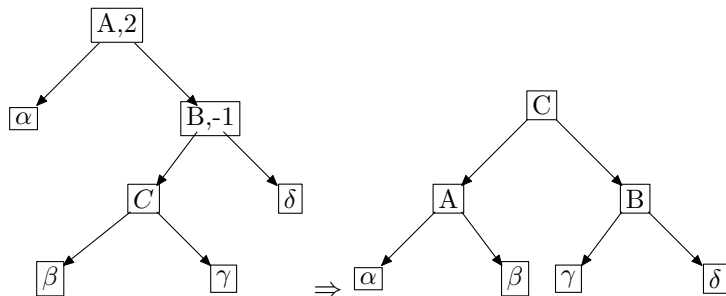
Rotation

Tree is falling "to the side".



Double-rotation

Tree is falling "to the interior".



Analysis and remarks

rotation, double-rotation, depths

- While inserting, one rotation (or double-rotation) suffices.
- Delete may start a cascade of rotations (the distortion is travelling towards the root).
- Number of elements in an AVL-tree with depth n :
- Depth of the sons differs at most by one, thus:
$$T(n) \geq T(n-1) + T(n-2),$$
- Thus the number of elements is at least the n th Fibonacci number,
- thus the depth is logarithmic w.r.t. number of elements.

Red-black trees

- Another method how to keep the tree sufficiently spread.
- Each vertex is colored red or black.
- Red vertices must not appear one after another,
- and the number of black vertices is the same for any path from the root to all the leaves.
- Result: any subtree has a depth of at most twice that of its neighbor.
- The tree is administrated using rotations, double-rotations and recoloring.
- Exact rules get lectured on Algorithms.
- The depth is also logarithmic w.r.t. number of elements.

FIXME!!!

A-B-trees, k -ary tree canonical representation.

Passing a function as an argument.

A queue and a buffer,

graph-searching algorithms (including graph representation).

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