# Uncertainty Principles, Extractors, and Explicit Embeddings of L2 into L1 

Piotr Indyk

October 1, 2006

## 1 Introduction

The area of geometric functional analysis ${ }^{1}$ is concerned with studying the properties of geometric (normed) spaces. A typical question in the area is: for two spaces $X$ and $Y$, equipped with norms $\|\cdot\|_{X}$ and $\|\cdot\|_{Y}$, under which conditions is there an embedding $F: X \rightarrow Y$ such that for any $p, q \in X$, we have $\|p-q\|_{X} \leq\|F(p)-F(q)\|_{Y} \leq C\|p-q\|_{Y}$ for some constant ${ }^{2} C \geq 1$ ? A ubiquitous tool for constructing such embeddings is the probabilistic method: the mapping is chosen at random from some distribution, and one shows that it "works" with high probability. Unfortunately, this approach does not lead to a concrete (or explicit) example of an embedding.

A prototypical problem in the area is that of embedding $l_{2}^{n}$ into $l_{1}^{m}$. It is known [FLM77] that there exist embeddings with both the distortion and the "dimension blowup" $m / n$ bounded by a constant. However, the proof of that theorem is probabilistic: one shows that a "random" mapping preserves the distance between a fixed pair of points with high probability, and concludes that the same holds for any pair of points if the aforementioned probability is high enough.

The problem of finding an explicit mapping with similar properties has been a subject of several studies (see Table 1). For constant distortion the best known result, attributed to Rudin [Rud60], guarantees $m=O\left(n^{2}\right)$; see also [LLR94] for an alternative proof. The problem of finding an explicit embedding with "low" distortion and dimension blowup has been posed, e.g., in [JS01] (Section 2.2), or in [Mil00] (Problem 8), or in [Mat04] (Problem 2.1).


[^0]In this paper we make progress on this question: for any $1>\eta>1 / \log n$, we give an explicit ${ }^{3}$ construction of an embedding of $l_{2}^{n}$ into $l_{1}^{m}$ with distortion $1+\eta$, with $m=n 2^{O\left((\log \log n)^{2}\right)}=n^{1+o(1)}$. Thus, our result matches the parameters of the non-explicit construction up to a sub-linear factor in the dimension bound.

### 1.1 Applications

As a consequence of our result we obtain, for any constant $\epsilon>0$, a randomized "Las Vegas" ( $1+\epsilon$ )approximate data structure for the near neighbor problem in $\mathbb{R}^{n}$ under the $l_{2}$ norm. Our data structure has query time polynomial in $n$, and uses space polynomial in the input size. Such result was known for the $l_{1}$ norm [Ind00a] (refer to that paper for a detailed description of the problem and the results). The extension to the $l_{2}$ norm follows immediately from our embedding.

In a similar fashion, our result implies a deterministic polynomial-time reduction from several approximate lattice problems under $l_{2}$ norm to analogous problems under $l_{1}$ norm, with only $1+\epsilon$ loss in the approximation factor. Previously known reductions incurred a loss of a $\sqrt{3}$ factor. The reduction applies to problems such as the Shortest Vector Problem and the Closest Vector Problem. See [RR06] for more on this topic.

### 1.2 Our techniques

Our embedding is constructed using the recursive "divide and conquer" approach. The main step is provided by the following theorem (see Preliminaries for the notation).

Theorem 1.1. For any constants $\zeta, \kappa>0$, there is an explicit linear mapping $F: \mathbb{R}^{n} \rightarrow \mathbb{R}^{m}$, $m=n \log ^{O(1)} n / \zeta^{O(1)}$, a scaling factor $S>0$ and an explicit partitioning of the coordinate set $[m]$ into "block" sets $B_{1} \ldots B_{b}$, each of size $n^{1 / 2+\kappa} 2^{(\log \log n)^{O(1)}} / \zeta^{O(1)}$, such that for any $x \in \mathbb{R}^{n}$, $\|x\|_{2}=1$, we have

$$
(1-O(\zeta)) S \leq \sum_{j=1}^{b}\left\|(F x)_{B_{j}}\right\|_{2} \leq S
$$

By applying this theorem $O(\log \log n)$ times we obtain a mapping $H: \mathbb{R}^{n} \rightarrow \mathbb{R}^{m^{\prime}}, m^{\prime}=n^{1+o(1)}$, and blocks $B_{1} \ldots B_{b^{\prime}}$ of constant size, such that for any $x$ as above we have

$$
\sum_{j=1}^{b^{\prime}}\left\|(H x)_{B_{j}}\right\|_{2}=S\left(1 \pm \eta^{\prime}\right)
$$

for some $\eta^{\prime}>0$. Since for any $y \in \mathbb{R}^{O(1)}$ we have $\|y\|_{2} \leq\|y\|_{1} \leq O(1) \cdot\|y\|_{2}$, the mapping $H$ preserves the norm of any unit vector $x$ up to a constant factor. ${ }^{4}$ The constant-distortion embedding follows in a standard way from the properties of a norm.

How to construct the mapping $F$ ? We proceed in two steps. In the first step, a vector $x$ is mapped into $D x \in \mathbb{R}^{m^{\prime}}, m^{\prime}=\Theta(n)$, such that (i) the mapping $D$ preserves the $l_{2}$ norm, and (ii) most of the "mass" $\|D x\|_{2}$ of $D x$ is "spread" over a "large" set $S$ of coordinates. That is, for any "small"

[^1]set of coordinates $S$, we have $\left\|(D x)_{S}\right\|_{2}<\delta\|D x\|_{2}$ for some constant $1>\delta>0$. Such properties are often called uncertainty principles [DS89]. We note that several probabilistic constructions of mappings with such properties have been discovered recently, e.g., in [Don06, CRT06] and [AC06] ${ }^{5}$. See Section 4 for more information on this topic.

The key parameter of such mappings is the upper bound on the size of "a small set of coordinates". In particular, if the upper bound was linear, then $D$ itself would have the desired embedding properties. Indeed, consider a set $S$ consisting of $s=\mathrm{cm}^{\prime}$ largest (in magnitude) coordinates in $D x$, for some constant $c>0$. From the hypothetical properties of $D$, it would follow that $\left\|(D x)_{\left[m^{\prime}\right]-S}\right\|_{2} \geq \sqrt{1-\delta^{2}}\|x\|_{2}=\Omega\left(\|x\|_{2}\right)$. At the same time, for any $i \in\left[m^{\prime}\right]-S$ we would have that $\left|(D x)_{i}\right|^{2} \leq\|D x\|_{2}^{2} / s=O\left(\|x\|_{2}^{2} / n\right)$. Therefore at least $\Omega(n)$ entries $(D x)_{i}$ would have absolute values of $\Theta\left(\|x\|_{2} / \sqrt{n}\right)$, which would imply that $\|D x\|_{1}=\Omega\left(\sqrt{n}\|x\|_{2}\right)$. At the same time, we have $\|D x\|_{1} \leq \sqrt{m^{\prime}}\|D x\|_{2}=O\left(\sqrt{n}\|x\|_{2}\right)$. Therefore, the mapping $D$ would have constant distortion (after scaling it by a factor of $1 / \sqrt{n}$ ).

Unfortunately, we do not know how to explicitely construct such a mapping $D$ that works for sets $S$ of linear size. However, we do know how to handle sets of size up to $\Theta(\sqrt{n})$. The existence of such mappings, together with an explicit construction (for some $\delta>0$ ), was discovered by [DS89]; see Section 4 for further discussion. Here, we require this property for any $\delta>0$. We show that a certain explicit construction of "highly orthogonal" configuration of vectors in $\mathbb{R}^{n}$ [CS73, WF89] can be used to construct such mapping $D$.

In the second step, the coordinates of the vector $D x$ are duplicated, rearranged, and partitioned into $b$ "buckets" (note that these operations preserve the $l_{2}$ norm of a vector up to a scaling factor). The goal of this step is to ensure that the resulting vector $F x$ has the property that, for "most" buckets $B_{j}$, we have $\left\|(F x)_{B_{j}}\right\|^{2} \approx\|F x\|_{2} / b$. Note that this is possible only if the "mass" $\|D x\|_{2}$ is "spread" over more than $b$ coordinates, which is achieved using the aforementioned properties of the mapping $D$.

The rearrangement is done using an extractor, i.e., an expanding bipartite graph, in which the left vertex set is much larger than the right vertex set; see Section 3 for more information on extractors. Many explicit constructions of extractors are known [Sha04]. To use an extractor in our construction, however, we require that the maximum degree of any right vertex is at most a constant factor away from the average degree of the right vertices. Although this property does not have to hold in general, one can "enforce"it by removing a few edges and vertices of an extractor. This "trimming" procedure is simple and can be performed in time polynomial (in fact, linear) in the size of the graph.

Combining the "spreading" and "rearranging" steps yields the embedding of Theorem 1.1.

## 2 Preliminaries

In the paper we use $n$ to denote the dimension of the "guest" space $l_{2}$. We assume that $n=2^{2 l}$ for an integer $l>0$; this can be easily achieved by padding extra dimensions with 0 's.

We use $[n]$ to denote the set $\{1 \ldots n\}$. For any $x \in \mathbb{R}^{n}$, and $S \subset[n]$, we use $x_{S}$ to denote the projection of $x$ on $S$; that is, $\left(x_{1}, \ldots, x_{n}\right)_{\left\{i_{1}, \ldots, i_{s}\right\}}=\left(x_{i_{1}}, \ldots, x_{i_{s}}\right)$.

It will be convenient to perform arithmetic operations (such as addition or subtraction) on two vectors $x$ and $y$ even if their dimensions different. Given vectors $x: X \rightarrow \mathbb{R}$ and $y: Y \rightarrow \mathbb{R}$, and

[^2]an operation $\otimes$, the value of $x \otimes y$ is equal to $x^{\prime} \otimes y^{\prime}$, where $x^{\prime}: X \cup Y \rightarrow \mathbb{R}$ is an extension of $x$ obtained by padding the dimensions in $Y-X$ with 0 's; $y^{\prime}$ is defined analogously.

In a graph $G$ with the set of edges $E$, we use $\Gamma_{G}(i)$ to denote the sequence of vertices adjacent to the vertex $i$ in $G$ (in any fixed order).

Consider any set $S \subset \Sigma^{n}$ for some set $\Sigma$. We say that the uniform distribution over $S$ (or just $S$ ) is $k$-wise independent, if for any $|K| \leq k, z \in \Sigma^{k}, \operatorname{Pr}_{x \in S}\left[x_{K}=z\right]=|\Sigma|^{-k}$.

## 3 Extractors

Our construction utilizes extractors. They are defined as follows.
Definition 3.1. A bipartite graph $G=(A, B, E), A=[a], B=[b]$, with each left node having degree $d$, is called an $(\epsilon, l)$-extractor, if it satisfies the following property. Consider any distribution $\mathcal{P}$ over $A$ such that for any $i \in A, \operatorname{Pr}_{\mathcal{P}}[i] \leq 1 / l$. Let $j$ be a random variable over $B$ obtained by choosing a vertex $i$ from $A$, choosing $t$ uniformly at random from [d], and setting $j=\Gamma_{G}(i)_{t}$. Let $G(\mathcal{P})$ be the resulting distribution of the random variable $j$, and let $\mathcal{I}$ be the uniform distribution over $B$. We require that $G(\mathcal{P})$ and $I$ are $\epsilon$-close, i.e., that $\|G(\mathcal{P})-\mathcal{I}\|_{1} \leq \epsilon$, where both distributions are interpreted as vectors in $\mathbb{R}^{b}$.

It is useful to observe that if $\mathcal{P}$ is a uniform distribution over some set $A^{\prime} \subset A$, then, for any $j \in B$, the value of $\operatorname{Pr}_{G(\mathcal{P})}[j]$ is proportional to the number of neighbors of $j$ that belong to $A^{\prime}$.

There exist several explicit constructions of extractors which guarantee the left degree $d=$ $2^{(\log \log a)^{O(1)}} / \epsilon^{O(1)}$ (see [Sha04] for an overview). Here we use the construction of [Zuc97], with parameters $l=a^{\lambda}, b=a^{\lambda-\kappa}$ and $d=(\log a)^{O(1)}$, for any constants $\lambda, \kappa \in(0,1)$.

In our applications we also need an upper bound on the right degree $\Delta$ of the extractor. To this end we show ${ }^{6}$ that one can achieve $\Delta=O(a d / b)$ by taking any extractor $G$ and applying the following "trimming" procedure. Let $a v g=a d / b$ be the average right degree of $G$, and let $t>1$, $\delta>0$ be constants determined later.

1. Select $B^{\prime} \subset B$ containing nodes with degree higher than $t \cdot$ avg.
2. Select $A^{\prime} \subset A$ containing nodes with more than $\delta d$ neighbors in $B^{\prime}$.
3. Construct an induced subgraph $G^{\prime}=\left(A-A^{\prime}, B-B^{\prime}, E^{\prime}\right)$ of $G$.
4. For any node $i \in A-A^{\prime}$ with $d_{i}=\left|\Gamma_{G^{\prime}}(i)\right|<d$, add $d-d_{i}$ edges incident to $i$. Let $E^{\prime \prime}$ be the set of all of those edges. The right endpoints of the edges are chosen such that each right vertex is incident to at most $\left\lceil\left|E^{\prime \prime}\right| /\left|B-B^{\prime}\right|\right\rceil$ of the edges. For example, we can set the $s$-th edge of $E^{\prime \prime}$ to be incident to the node $\left(s \bmod \left|B-B^{\prime}\right|\right)+1$.

From the construction it follows that each left node of $G^{\prime}$ has degree $d$, and that the right degree of $G^{\prime}$ is $O\left(a d / b+a d /\left|B-B^{\prime}\right|\right)$. The rest is shown in the following claim.

Claim 3.2. Set $t=2$ and $\delta=4 \epsilon$. Then the graph $G^{\prime}$ has a/2 left vertices, $b / 2$ right vertices, and is an $(\delta+\epsilon, l)$-extractor.

[^3]Proof. First, observe that at most $b / t$ nodes in $B$ have degree higher than $t \cdot a v g$, so $\left|B-B^{\prime}\right| \geq b / 2$. Let $F$ be the set of edges incident to $B^{\prime}$, and let $\mathcal{P}$ be a uniform distribution over $A$. In this case $\frac{|F|}{|E|}=\sum_{j \in B^{\prime}} \operatorname{Pr}_{G(\mathcal{P})}[j]$. Moreover, the probability of choosing $j \in B^{\prime}$ with respect to distribution $G(\mathcal{P})$ is at least $t / b$, which exceeds the average $1 / b$ by at least $(t-1) / b$. Since

$$
\sum_{j \in B^{\prime}} \operatorname{Pr}_{G(\mathcal{P})}[j](1-1 / t) \leq \sum_{j \in B^{\prime}} \operatorname{Pr}_{G(\mathcal{P})}[j]-1 / b \leq \epsilon
$$

it follows that $\frac{|F|}{|E|}(1-1 / t) \leq \epsilon$, or $\frac{|F|}{|E|} \leq \epsilon\left(1+\frac{1}{t-1}\right)=2 \epsilon$. Therefore, at most $2 \epsilon / \delta=1 / 2$ fraction of nodes in $A$ have more than $\delta d$ edges leading to $B^{\prime}$, so $\left|A-A^{\prime}\right| \geq a / 2$. Finally, each node in $A-A^{\prime}$ is incident to at most $\delta d$ new edges $E^{\prime \prime}$. Thus, for any distribution $\mathcal{P}$ over $A^{\prime}$, we have $\left\|G(\mathcal{P})-G^{\prime}(\mathcal{P})\right\|_{1} \leq \delta$. It follows that $G^{\prime}$ is an $(\delta+\epsilon, l)$-extractor.

## 4 Uncertainty principles

Let $H$ be a normalized $n \times n$ Hadamard matrix. That is, all entries of $H$ are either $-1 / \sqrt{n}$ or $1 / \sqrt{n}$, and the rows of $H$ are mutually orthogonal. Thus, the rows of $H$ form an orthonormal basis for $\mathbb{R}^{n}$. In addition, let $I$ be the $n \times n$ identity matrix.

The pair of matrices $(I, H)$ has the following nice property: for each row $u$ of $I$ and row $v$ of $H$, we have $|u \cdot v| \leq 1 / \sqrt{n}$. In general, consider any collection $H_{1} \cup \ldots \cup H_{L}$ of $n \times n$ orthonormal matrices, and let $D$ be an $n \cdot L \times n$ matrix obtained by concatenating the rows of those matrices ( $D$ is often called a dictionary). The coherence of $D$ is defined as the maximum, over all rows $u, v$ of $D$, of $|u \cdot v|$. In particular, the coherence of the concatenation of matrices $I$ and $H$ has coherence $1 / \sqrt{n}$, while the coherence of any orthonormal matrix is 0 .

In [DS89] the authors show a relation between the coherence of $D$, and the sparsity of the representation $D x$ of any vector $x \in \mathbb{R}^{n}$. Specifically, they consider a dictionary $D$ obtained from the identity matrix $I$ and a Fourier matrix; such a dictionary $D$ has coherence $1 / \sqrt{n}$. They show that, for any $x \in \mathbb{R}^{n}, D x$ must have at least $2 \sqrt{n}$ non-zero elements. They also show a more general fact: there exists $c>0$, such that for any set $S$ of coordinates of $D x$ of size at most $c \sqrt{n}$, the ratio $\frac{\left\|(D x)_{S}\right\|_{2}}{\|D x\|_{2}}$ is bounded away from 1 (although not arbitrarily close to 0 ).

This phenomenon is akin to an uncertainty principle: a signal cannot be concentrated in both the time and the frequency domain.

This result was generalized [DH01] to dictionaries $D$ consisting of two arbitrary orthonormal matrices $H_{1}, H_{2}$. They show that, for any $x \in \mathbb{R}^{n}$, the vector $D x$ must have at least $1 / M$ nonzero entries, where $M$ is the coherence of $D$. This theorem was later extended in [GN03] to concatenations of $L$ orthonormal matrices $H_{1} \ldots H_{L}$.

In this paper, we exploit a general version of the uncertainty principle phenomenon, stated as Lemma 4.2 below. We start from the following observation.

Claim 4.1. Consider any $N \times n$ dictionary $D$ with coherence $M$, and a submatrix $D_{S}$ consisting of at most $s$ rows in $D$. For any unit vector $x \in \mathbb{R}^{n}$, we have $\left\|D_{S} x\right\|_{2}^{2} \leq 1+M s$.
Proof. We need to upper-bound the 2-norm $\left\|D_{S}\right\|_{2}$ of $D_{S}$, which is equal to the square root of the largest eigenvalue $\lambda(G)$ of the Gram matrix $G=D_{S} \times D_{S}^{T}$. Clearly, for $i, j \in[s], i \neq j$, we have $G_{i i}=1$ and $\left|G_{i j}\right| \leq M$. It follows that $|\lambda(G)| \leq|\lambda(I)|+|\lambda(G-I)| \leq 1+M s$, since all entries of $G-I$ are in the range $[-M, M]$.

Note: a related proof has appeared in [Tro04] (Proposition 4.3).
Assume now that $D$ is obtained by concatenating $L$ orthonormal matrices $H_{1} \ldots H_{L}$. Clearly, for any unit vector $x \in \mathbb{R}^{n}$, we have $\|D x\|_{2}^{2}=L$. At the same time, for any set of coordinates $S \subset[L n],|S|=s$, we have $\left\|(D x)_{S}\right\|_{2}^{2} \leq 1+M s$ (Claim 4.1). This shows the following lemma.

Lemma 4.2. Let $D$ be a dictionary obtained by concatenating rows of $L$ orthonormal $n \times n$ matrices $H_{1} \ldots H_{L}$ with coherence $M$. Then, for any set of coordinates $S \subset[L n],|S|=s$, and any unit vector $x \in \mathbb{R}^{n}$, we have

$$
\left\|(D x)_{S}\right\|_{2}^{2} \leq(1+M s)\|D x\|_{2}^{2} / L
$$

It remains to construct dictionaries with small coherence. Fortunately, if $n=2^{2 k}$ for an integer $k>0$, then there exist explicit constructions of a dictionary $D$ consisting of the rows of $L=n / 2+1$ orthonormal matrices $H_{1} \ldots H_{L}$, such that the coherence of $D$ is $1 / \sqrt{n}$. The constructions appear in [CS73, WF89, CCKS00]; see [HSP06] for a simplified description of the construction (In a nutshell: each $H_{i}$ is either an identity matrix, or is equal to $H \times D_{i}$, where $H$ is the Hadamard matrix, and $D_{i}$ 's are carefully chosen diagonal matrices.) Therefore, for $s=\sqrt{n}$, we have $M s \leq 1$, and any $s$ coordinates of $D x$ can contain at most $\sqrt{2 / L}$ fraction of the "mass" $\|D x\|_{2}$.

Corollary 4.3. Let $n=2^{2 k}$ for an integer $k>0$. For any $\delta>2 / \sqrt{n}$, there exists an explicit construction of a dictionary $D$ consisting of the rows of $L=2 / \delta^{2}$ orthonormal $n \times n$ matrices $H_{1} \ldots H_{L}$, such that for any unit vector $x \in \mathbb{R}^{n}$, and any set $S \subset[n L],|S| \leq s=\sqrt{n}$, we have $\left\|(D x)_{S}\right\|_{2} \leq \delta\|D x\|_{2}$.

## 5 The construction

Our construction utilizes the observation of Corollary 4.3. Fix $\delta>0$ to be some constant, and let $L=O\left(1 / \delta^{2}\right)$ and $s=\sqrt{n}$ be as in the latter corollary. In addition, we use an $(\epsilon, l)$-extractor $G$ with $A=[L n]$ and $B=[b]$ for $b=n^{1 / 2-\kappa}, \kappa>0, l=(1-\delta)^{2} s / L$, left degree $d=(\log a)^{O(1)}$ and right degree $\Delta=O(n L d / b)$. The values of $\delta$ and $\epsilon$ are set at the end of the following proof of the the Theorem 1.1. For convenience, we restate the theorem below, using the notation introduced above.

Theorem 1.1. For any $\zeta, \kappa>0$, there is an explicit linear mapping $F: \mathbb{R}^{n} \rightarrow \mathbb{R}^{m}, m=O(n L d)=$ $n \log { }^{O(1)} n / \zeta^{O(1)}$, and a partitioning of the coordinates set $[m]$ into sets $B_{1} \ldots B_{b}$, each of size $O(\Delta)=O(n L d / b)=n^{1 / 2+\kappa} 2^{(\log \log n)^{O(1)}} / \zeta^{O(1)}$, such that for any $x \in \mathbb{R}^{n},\|x\|_{2}=1$, we have

$$
(1-O(\zeta)) \sqrt{L d b} \leq \sum_{j=1}^{b}\left\|(F x)_{B_{j}}\right\|_{2} \leq \sqrt{L d b}
$$

Proof. The mapping $F$ is constructed as

$$
F x=\oplus_{j=1}^{b}(D x)_{\Gamma_{G}(j)}
$$

where $\oplus$ is the direct sum operator (i.e., concatenation).
Let $y=D x$. Observe that $\|y\|_{2}=\sqrt{L}$. In the following we show that the mapping has constant expansion as well as constant contraction, with respect to the norm of the host space.

Expansion. Let $y^{d}=\oplus_{i=1}^{d} y$. Note that $\left\|y^{d}\right\|_{2}=\sqrt{L d}$. We can interpret $F x$ as a vector $y^{d}$ partitioned into $d$ blocks, and use the following lemma.

Lemma 5.1. For any $x \in \mathbb{R}^{n}$, and any partitioning $P_{1} \ldots P_{b}$ of $[n]$, we have

$$
\sum_{t=1}^{b}\left\|x_{P_{t}}\right\|_{2} \leq \sqrt{b}\|x\|_{2}
$$

Proof. Construct a vector $y \in \mathbb{R}^{b}$ such that $y_{j}=\left\|x_{P_{t}}\right\|_{2}$. Observe that $\|y\|_{1}=\sum_{t=1}^{b}\left\|x_{P_{t}}\right\|_{2}$ and $\|x\|_{2}^{2}=\sum_{t=1}^{b}\left\|x_{P_{t}}\right\|_{2}^{2}=\sum_{t=1}^{b} y_{t}^{2}=\|y\|_{2}^{2}$. Since $\|y\|_{1} \leq \sqrt{b}\|y\|_{2}$, the lemma follows.

From Lemma 5.1 it follows that

$$
\sum_{i=1}^{b}\left\|y_{\Gamma_{G}(i)}\right\|_{2} \leq \sqrt{b}\left\|y^{d}\right\|_{2}=\sqrt{L d b}
$$

Contraction. Let $S \subset[L n]$ be the set of indices of the $s$ largest (in magnitude) entries of $y$. Consider the vector $z=y_{[L n]-S}$ interpreted as a vector in $\mathbb{R}^{L n}$. Let $\rho=\|z\|_{2}$. From Lemma 4.3 we know that $\rho \geq \sqrt{L}(1-\delta)$. At the same time, for each $i=1 \ldots L n$, we have $z_{i}^{2} \leq\|y\|_{2}^{2} / s=L / s$.

We use $z$ to construct a probability distribution $\mathcal{P}$ over [Ln], by defining $p_{i}=z_{i}^{2} /\|z\|_{2}^{2}=z_{i}^{2} / \rho^{2}$. It follows that $p_{i} \leq \frac{L / s}{\rho^{2}} \leq 1 / l$. Therefore, $\mathcal{P}$ satisfies the conditions on using the extractor $G$. This implies that the distribution $\mathcal{Q}=G(\mathcal{P})$ over $B$ is $\epsilon$-close to the uniform distribution over $B$.

For any $j \in B$, the probability $q_{j}$ with respect to $\mathcal{Q}$ is equal to

$$
q_{j}=1 / d \cdot \sum_{i \in \Gamma_{G}(j)} p_{i}=\frac{1}{\rho^{2} d} \cdot \sum_{i \in \Gamma_{G}(j)} z_{i}^{2}=\frac{1}{\rho^{2} d}\left\|z_{\Gamma_{G}(j)}\right\|_{2}^{2}
$$

Since $\mathcal{Q}$ is $\epsilon$-close to the uniform distribution, we get

$$
\sum_{j=1}^{b}\left|\frac{1}{\rho^{2} d}\left\|z_{\Gamma_{G}(j)}\right\|_{2}^{2}-1 / b\right| \leq \epsilon
$$

Therefore, for at least $b(1-\alpha)$ indices $j$, we have $\frac{1}{\rho^{2} d}\left\|z_{\Gamma_{G}(j)}\right\|_{2}^{2} \geq(1-\epsilon / \alpha) / b$, or, $\left\|z_{\Gamma_{G}(j)}\right\|_{2} \geq$ $\sqrt{(1-\epsilon / \alpha) \rho^{2}} \sqrt{d / b}$. Therefore

$$
\sum_{j}\left\|y_{\Gamma_{G}(j)}\right\|_{2} \geq \sum_{j}\left\|z_{\Gamma_{G}(j)}\right\|_{2} \geq b(1-\alpha) \sqrt{\rho^{2}(1-\epsilon / \alpha)} \sqrt{d / b} \geq(1-\alpha) \sqrt{(1-\delta)^{2}(1-\epsilon / \alpha)} \cdot \sqrt{L d b}
$$

Setting $\alpha=\delta=\zeta$, and $\epsilon=\zeta^{2}$ finishes the proof.
Corollary 5.2. For any $1>\eta>0$ there is an explicit embedding of $l_{2}^{n}$ into $l_{1}^{m}$,

$$
m=\left(\log { }^{O(1)}(n) / \eta^{O(1)}\right)^{O(\log \log n)} \cdot 1 / \eta^{O(\log 1 / \eta)}
$$

with distortion $1+O(\eta)$.

Proof. Apply Theorem 1.1 $O(\log \log n)$ times with $\zeta=\eta / \log \log n$ to reduce each block size to a constant $n^{\prime}=\Theta(1 / \eta)$. Within each block use the embedding of [Ind00b] which embeds $l_{2}^{n^{\prime}}$ into $l_{1}^{n^{\prime O\left(\log n^{\prime}\right)}}$ with distortion $1+\eta$. The total distortion is at most $(1+\eta)(1+\eta / \log \log n)^{O(\log \log n)}=$ $1+O(\eta)$. The dimension blowup is at most

$$
\left(\log { }^{O(1)}(n) / \zeta^{O(1)}\right)^{O(\log \log n)} \cdot 1 / \eta^{O(\log 1 / \eta)}
$$

Note that the latter bound is at most $2^{O\left((\log \log n)^{2}\right)}$ for $\eta=1 / \log n$.

## Acknowledgments

The author would like to thank: Salil Vadhan, for answering numerous questions about extractors; Martin Strauss, for discussions about dictionaries; Assaf Naor, Tasos Sidiropoulos and David Woodruff, for many helpful comments on early drafts of this paper.

## References

[AC06] N. Ailon and B. Chazelle. Approximate nearest neighbors and the Fast JohnsonLindenstrauss Transform. Proceedings of the Symposium on Theory of Computing, 2006.
[AM06] S. Artstein-Avidan and V. D. Milman. Logarithmic reduction of the level of randomness in some probabilistic geometric constructions. Journal of Functional Analysis, 235:297329, 2006.
[CCKS00] A. R. Calderbank, P. J. Cameron, W. M . Kantor, and J. J. Seidel. Z4-Kerdock codes, orthogonal spreads and extremal euclidean line-sets. Proceedings of the London Mathematical Society, 2000.
[CRT06] E. Candes, J. Romberg, and T. Tao. Robust uncertainty principles: Exact signal reconstruction from highly incomplete frequency information. IEEE Transactions on Information Theory, 52:489-509, 2006.
[CS73] P. J. Cameron and J.J. Seidel. Quadratic forms over GF(2). Indag. Math, 1973.
[DH01] D. Donoho and X. Huo. Uncertainty principles and ideal atomic decomposition. Transactions on Information Theory, 47:2845-2862, 2001.
[Don06] D. Donoho. Compressed sensing. IEEE Transactions on Information Theory, 52(4):1289 - 1306, 2006.
[DS89] D. Donoho and P. Stark. Uncertainty principles and signal recovery. SIAM Journal on Applied Mathematics, 1989.
[FLM77] T. Figiel, J. Lindenstrauss, and V. D. Milman. The dimension of almost spherical sections of convex bodies. Acta Mathematica, 139:53-94, 1977.
[GN03] R. Gribonval and M. Nielsen. Sparse representations in unions of bases. IEEE Transactions on Information Theory, 2003.
[HSP06] R. W. Heath, T. Strohmer, and A. J. Paulraj. On quasi-orthogonal signatures for CDMA systems. IEEE Transactions on Information Theory, 52:1217-1226, 2006.
[Ind00a] P. Indyk. Dimensionality reduction techniques for proximity problems. Proceedings of the Ninth ACM-SIAM Symposium on Discrete Algorithms, 2000.
[Ind00b] P. Indyk. Stable distributions, pseudorandom generators, embeddings and data stream computation. Proceedings of the Symposium on Foundations of Computer Science, 2000.
[JS01] W.B. Johnson and G. Schechtman. Finite dimensional subspaces of $l_{p}$. In W.B. Johnson and J. Lindenstrauss, editors, Handbook of the Geometry of Banach Spaces, pages 837870. Elsevier, 2001.
[LLR94] N. Linial, E. London, and Y. Rabinovich. The geometry of graphs and some of its algorithmic applications. Proceedings of 35th Annual IEEE Symposium on Foundations of Computer Science, pages 577-591, 1994.
[Mat04] J. Matoušek. Collection of open problems on low-distortion embeddings of finite metric spaces. Available at http://kam.mff.cuni.cz/ ${ }^{\text {matousek/metrop.ps.gz, } 2004 .}$
[Mil00] V. Milman. Topics in asymptotic geometric analysis. GAFA - Geometric and Functional Analysis, pages 792-815, 2000.
[RR06] O. Regev and R. Rosen. Lattice problems and norm embeddings. Proceedings of the Symposium on Theory of Computing, 2006.
[Rud60] W. Rudin. Trigonometric series with gaps. J. Math. Mech., 9:203-227, 1960.
[Sha04] R. Shaltiel. Recent developments in extractors. In Current trends in theoretical computer science. The Challenge of the New Century. Vol 1: Algorithms and Complexity, 2004.
[Sza06] S. Szarek. Convexity, complexity and high dimensions. Proceedings of the International Congress of Mathematicians, 2006.
[Tro04] J. Tropp. Topics in sparse approximation. Ph.D. dissertation, Computational and Applied Mathematics, UT-Austin, 2004.
[WF89] W.K. Wooters and B. D. Fields. Optimal state-determination by mutually unbiased measurements. Annals of Physics, 191:363-381, 1989.
[WZ99] A. Wigderson and D. Zuckerman. Expanders that beat the eigenvalue bound: Explicit constructions and applications. Combinatorica, 1999.
[Zuc97] D. Zuckerman. Randomness-optimal oblivious sampling. Random Structures and Algorithms, 11:345-367, 1997.


[^0]:    ${ }^{1}$ See [Sza06] for a very recent overview of the area.
    ${ }^{2} C$ is called the distortion of the mapping $F$.

[^1]:    ${ }^{3}$ Formally, in this paper, the term "explicit" is defined as "constructible in time that is polynomial in $n$ ". See Section 1.2 for an overview of the construction.
    ${ }^{4}$ Alternatively, one can use the embedding of [Ind00b] within each block, to ensure that the distortion is arbitrarily close to 1 . This is the approach we use to obtain our main result.

[^2]:    ${ }^{5}$ In fact, this work has been inspired by the result of [AC06].

[^3]:    ${ }^{6}$ This fact was apparently known, but we were unable to locate an appropriate reference. However, the paper [WZ99] provides such a proof for somewhat simpler combinatorial objects called dispersers.

