

ELLIPSOID ALGORITHM - PART 3

7/12/2020

Goal: find $x \in P = \{x \in \mathbb{R}^n \mid Cx \leq d\}$

Assumptions: • P is bounded, i.e., $\exists K > 0$ s.t. $P \subseteq \{x \in \mathbb{R}^n \mid -K \leq x_i \leq K, i=1,\dots,n\}$

• if non-empty, then P has full dimension

1. $E_0 = E(z_0, C_0)$ for $R = \sqrt{n} \cdot 2^{\langle C, d \rangle - n^2}$, $C_0 = R \cdot I$, $z_0 = 0$, $k=0$

2. While $z_k \notin P$ (violated inequality: $C^T x \leq \dots$)

$$E_{k+1} = E(z_{k+1}, C_{k+1}) \text{ for } z_{k+1} = z_k - \frac{1}{n+1} \frac{C_k c}{\sqrt{C^T C_k c}}$$

$$C_{k+1} = \frac{n^2}{n^2 - 1} \left(C_k - \frac{2}{n+1} \cdot \frac{C_k^T C c^T C_k}{\sqrt{C^T C_k c}} \right)$$

$$k = k + 1$$

if k "too large", output P is empty, STOP

3. OUTPUT z_k

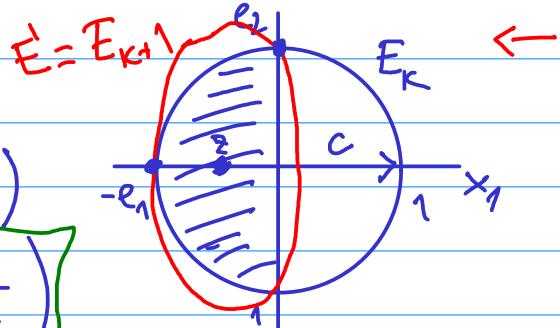
Invariant: $P \subseteq E$; in every iteration

We can handle the simple case:

$$E_k = E(0, I), c = e_1 = (1, 0, \dots, 0)$$

$$\Rightarrow E_{k+1} = E(z, z) \text{ for } z = \left(\frac{-1}{n+1}, 0, \dots, 0 \right)$$

$$Z = \text{diag} \left(\frac{n^2}{(n+1)^2}, \frac{n^2}{n^2}, \dots, \frac{n^2}{n^2-1} \right)$$



We know: $V_{\text{vol}}(E_{k+1}) \leq e^{-\frac{1}{2(n+1)}} V_{\text{vol}}(E_k)$

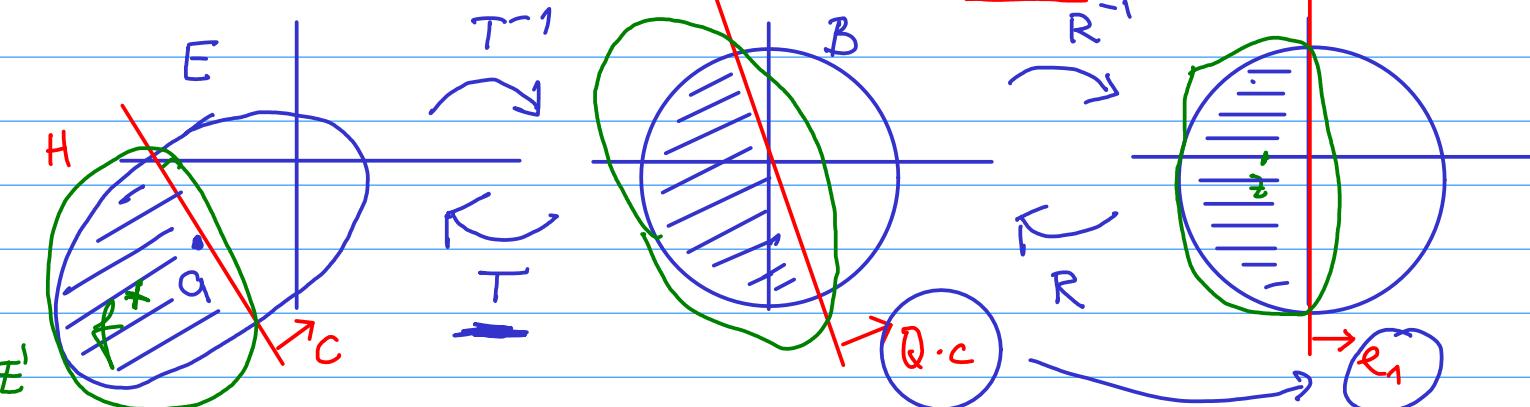
General case

$$\text{Given: } E = E(a, A) = Q \cdot E(0, I) + a \quad \text{where } Q = A'^{1/2}$$

$$H = \{x \in \mathbb{R}^n \mid C^T x \leq d\} = \{x \in \mathbb{R}^n \mid C^T(x-a) \leq d\}$$

Looking for

$E' = E(f, C) \supseteq E \cap H$ with $\text{vol}(E')$ as small as possible



We know: $T(y) = Q \cdot y + a$

$$H_n E \subseteq T(R(E(\frac{-e_1}{n+1}, z)))$$

$$T^{-1}(x) = Q^{-1}(x - a)$$

$$R(e_1) = \frac{Qc}{\|Qc\|}$$

$$\rightarrow f = a - \frac{1}{n+1} \cdot \frac{Ac}{\sqrt{c^T A c}}$$

center of next ellipsoid E'

$$\rightarrow x - f = x - T(R(z)) = x - a - QRz = QR(R^{-1}Q^{-1}(x - a) - z)$$

Fact: For rotation matrix R : $R^T R = I$; i.e., $R^{-1} = R^T$

Recall that $(Xu)^T = u^T X^T$, $(XYV)^{-1} = V^{-1}Y^{-1}X^{-1}$

Proof of the Half ellipsoid lemma from previous lecture

$$E = E(f, C) = \left\{ T(Ry) \mid (y - z)^T Z^{-1} (y - z) \leq 1 \right\} = \text{Subst. } K = TR(y) \\ \stackrel{x}{=} \left\{ x \in \mathbb{R}^n \mid (R^{-1}T^{-1}(x) - z)^T Z^{-1} (R^{-1}T^{-1}(x) - z) \leq 1 \right\}$$

$$\stackrel{\text{by def}}{=} \left\{ x \in \mathbb{R}^n \mid (R^{-1}Q^{-1}(x - a) - z)^T Z^{-1} (R^{-1}Q^{-1}(x - a) - z) \leq 1 \right\}$$

$$\stackrel{\text{by def}}{=} \left\{ x \in \mathbb{R}^n \mid (R^{-1}Q^{-1}(x - f))^T Z^{-1} (R^{-1}Q^{-1}(x - f)) \leq 1 \right\}$$

$$= \left\{ x \in \mathbb{R}^n \mid (x - f)^T (Q^{-1}R^{-1}Z^{-1}R^{-1}Q^{-1})(x - f) \leq 1 \right\}$$

$$C = Q \cdot R \cdot Z \cdot R^T \cdot Q^T$$

$$"C^{-1}" = I - \begin{pmatrix} \frac{2}{n+1} & \dots & 0 \\ \vdots & \ddots & 0 \\ 0 & \dots & 0 \end{pmatrix}$$

$$= \frac{n^2}{n^2 - 1} \cdot Q \cdot R \cdot \begin{pmatrix} \frac{n-1}{n+1} & 0 & & \\ 1 & 1 & \ddots & \\ & \ddots & \ddots & 1 \end{pmatrix} \cdot R^T \cdot Q^T$$

$$\begin{pmatrix} 1 & 0 & \dots & 0 \\ 0 & \ddots & & 0 \\ \vdots & & \ddots & 0 \end{pmatrix} = e_1 e_1^T$$

$$= \frac{n^2}{n^2 - 1} \underbrace{(Q \cdot R \cdot I \cdot R^T \cdot Q^T)}_{= Q \cdot R \cdot e_1 \cdot e_1^T \cdot R^T \cdot Q^T} - \frac{2}{n+1} Q \cdot R \cdot e_1 \cdot e_1^T \cdot R^T \cdot Q^T$$

$$= \frac{n^2}{n^2 - 1} \left(A - \frac{2}{n+1} \frac{A \cdot C \cdot \frac{C^T A^T}{\|Qc\|}}{\|Qc\|} \right)$$

$$= \frac{n^2}{n^2 - 1} \left(A - \frac{2}{n+1} \frac{A c c^T A^T}{c^T A c} \right)$$



When to stop?

Recall:

Fact 1: For an integer matrix $C : |\det C| \leq 2^{\langle C \rangle - n}$.

Fact 2: Let $T(x) = Q \cdot x + t$

Then for $X \subseteq \mathbb{R}^n$, $\text{vol}(T(X)) = |\det Q| \cdot \text{vol}(X)$.

Lemma: If $P = \{x \mid Cx \leq d\}$ has full dimension and C, d are integral, then

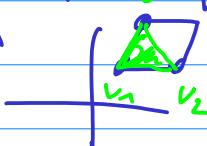
$$\text{vol}(P) \geq 2^{-(n+\epsilon) \langle C \rangle + n^3}$$

Proof (sketch): P full dimension \Rightarrow

exist v_0, v_1, \dots, v_n affine independent vertices of P

$$\text{vol}(\text{conv}(v_0, v_1, \dots, v_n)) \leq \text{vol}(P)$$

let $e_i = (0, \dots, 1, \dots, 0)$, $i=1, \dots, n$
 \uparrow -th coordinate



$$\text{conv}(v_0, v_1, \dots, v_n) = T(\text{conv}(0, e_1, \dots, e_n)),$$

where

$$T(x) = v_0 +$$

$$\begin{pmatrix} 1 & | & | & | \\ v_1 - v_0 & v_2 - v_0 & \dots & v_n - v_0 \\ | & | & | & | \end{pmatrix} x = Hx$$

$$T(e_i) = v_0 + v_i - v_0 = v_i$$

$$T(0) = v_0$$

Fact 3: $\text{vol}(\text{conv}(0, e_1, \dots, e_n)) = \frac{1}{n!}$

Thus,

$$\text{vol}(P) \geq \text{vol}(\text{conv}(v_0, v_1, \dots, v_n)) = \frac{1}{n!} |\det H| =$$

$$\begin{aligned} &= \frac{1}{n!} \left| \det \begin{pmatrix} 1 & | & | & | \\ v_1 & v_2 & \dots & v_n \\ | & | & | & | \end{pmatrix} \right| = \frac{1}{n!} \left| \det \begin{pmatrix} 1 & 1 & | & | & | \\ v_0 & v_1 & \dots & v_n \\ | & | & | & | \end{pmatrix} \right| = \\ &\quad \text{Fact 2,3} \\ &= \frac{1}{n!} \left| \det \begin{pmatrix} 1 & 1 & \dots & 1 \\ v_0 & v_1 & \dots & v_n \\ | & | & \dots & | \end{pmatrix} \right| = \\ &\quad \text{add the first column to every other} \end{aligned}$$

by theory of polyhedra we know:

Consider a vertex v_i : v_i is a unique solution of a system $C_i x = d_i$ for a subsystem $C_i x \leq d_i$ of $C x \leq d$

by Cramer's rule: $v_{i,j} := \frac{\det(C_{i,j})}{\det(C_i)}$

regular integer matrix

$$= \frac{1}{n!} \cdot \frac{\det(C_0 \cdot \det C_1 \cdots \det C_n)}{\det(u_0 \ u_1 \ \cdots \ u_n)} \geq 1$$

C_i with j -th column replaced by d_i

where $u_i = v_i \cdot \det C_i$

Fact 1

$$\geq \frac{1}{n!} \left(\frac{1}{2^{C} - n^2} \right)^{n+1} \geq 2^{-n \log n} \cdot 2^{-(n+1)C + n^3}$$

Theorem: If $P = \{x \mid Cx \leq d\}$ is full dimensional and non-empty, for C, d integral, then the algorithm will find $x \in P$ in at most

$$\rightarrow k = 2(n+1)(2(n+1)C + nD) - n^3$$

Proof-hints: $\text{vol}(E_0) \leq (2R)^n$ for $R = \sqrt{n} \cdot 2^{C,D} - n^2$

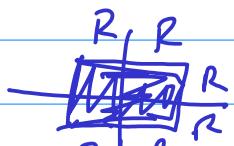
$$\text{vol}(P) \geq \dots \quad \text{by previous lemma}$$

$$\text{vol}(E_{k+1}) \leq e^{-\frac{1}{2(n+1)}} \cdot \text{vol}(E_k)$$

Have to get rid of the simplifying assumptions

• P is bounded: replace P by $P \cap \{-R \leq x \leq R\}$

:



• P is of full dimension

Lemma 3: $Ax \leq b$ has a solution iff

$Ax \leq b + \mathbb{I} \cdot \varepsilon$ has a solution for

$$\varepsilon = \frac{1}{2m \cdot 2^{C,D} - n^2}, \text{ where } A, b \text{ are integral}$$

$A \in \mathbb{Z}^{m \times n}$



Theorem: The LP problem is solvable in polynomial time.

Khachiyan, 1979

Final remarks: we ignore rounding issues -

$$f \geq a - \frac{1}{n+1} \cdot \frac{\|A\|}{\sqrt{c^T A c}} \dots \text{irrational number}$$

- by the application of the Lemmas, we only get YES/NO answer to the Decision version of LP, but there is a way how to get back to the Search LP.
- the algorithm is not very efficient for real-life problems
- theoretically important as it can deal with enormously large system given a separation oracle - an algorithm that can check in poly time whether $x \in P$, and if not, find a violated constraint.