

SET COVER - RECAP

GREEDY ALG. FOR SC

- (1)  $I := \emptyset, E := \emptyset$
- (2) while  $E \neq \{1, 2, \dots, n\}$  do
  - for  $j \in \{1, \dots, m\}$  s.t.  $S_j \not\subseteq E$ , define  $p_j = \frac{c_j}{|S_j \setminus E|}$
  - $l = \arg \min p_j$
  - $\rightarrow I := I \cup \{l\}, E := E \cup S_l$
  - $z_e := p_j \quad \forall e \in S_j \setminus E$
- (3) OUTPUT  $I$

LP Relaxation for SET COVER

(P)  $\min \sum_{j=1}^m c_j x_j$

$\sum_{j: e \in S_j} x_j \geq 1 \quad \forall e$

$x_j \geq 0$

(D)  $\max \sum_{e=1}^n y_e$

$\sum_{e \in S_j} y_e \leq c_j \quad \forall j$

$y_e \geq 0$

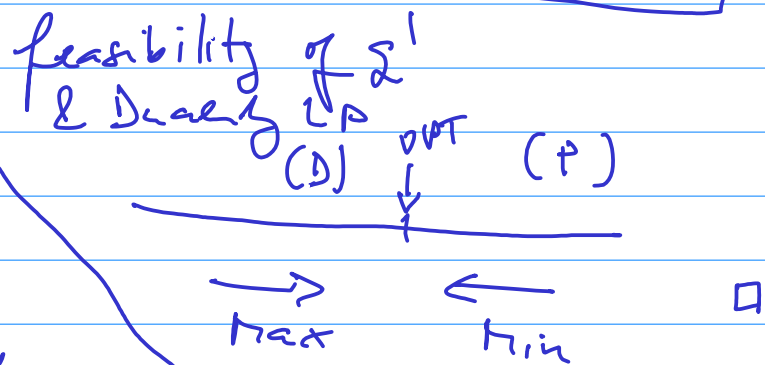
Define  $z' = \frac{1}{H_g} z$  where  $H_n = 1 + \frac{1}{2} + \frac{1}{3} + \dots + \frac{1}{n} \sim \ln n$

$z'$  is a feasible solution for (D).

**THM:** GREEDY-SC is  $H_g$ -approximation algorithm.

Proof:

$$\sum_{j \in I} c_j = \sum_{e=1}^n y_e = H_g \sum_{e=1}^n z'_e \leq H_g \cdot \text{OPT}_{LP} \leq H_g \cdot \text{OPT}$$



REMARKS:



every el ... cost 1  
 GREEDY ...  $(\ln n - 1)$  sets  
 OPT ... 2

ANALYSIS asymp. tight

THM (2014): For any  $\epsilon < 1$ , there is no  $(c \cdot \ln n)$ -approx. algorithm for SET COVER, unless  $P=NP$ .

recall:  $f = \max_{i \in [1, \dots, n]} |\{j \mid i \in S_j\}|$

PRIMAL LP-SC ALG.

(1) solve LP (P) ...  $x^*$

(2)  $I = \{j \mid x_j^* \geq \frac{1}{f}\}$

(3) output  $I$

THM: PRIMAL LP-SC is an  $f$ -approximation alg.

Proof: feasibility  
 as for each  $e: \sum_{j: e \in S_j} x_j^* \geq 1$

$\Rightarrow$  in feasible  $x^*$ , at least one set  $S_j$  has  $x_j^* \geq \frac{1}{f}$

cost:  $\sum_{j \in I} c_j \leq \frac{1}{f} \sum_{j \in I} c_j \leq f \cdot \text{LP-OPT} \leq f \cdot \text{OPT}$

DUAL LP-SC ALG.

(1) solve LP (D) ...  $y^*$

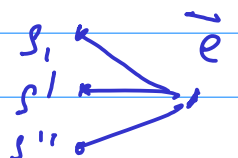
(2)  $I = \{j \mid \sum_{e \in S_j} y_e^* = c_j\}$

(3) output  $I$

THM: DUAL LP-SC is an  $f$ -approximation algorithm.

Proof: feasibility: assume that there is  $\bar{e} \in [1, \dots, n]$  that is not covered by  $I$

For each  $S_j$  containing  $\bar{e}: \sum_{e \in S_j} y_e^* < c_j$



let  $\epsilon = \min_{j: \bar{e} \in S_j} (c_j - \sum_{e \in S_j} y_e^*)$

Note:  $\epsilon > 0$

Define  $y_e^i = \begin{cases} y_e^* & \text{for } e \in \bar{e} \\ y_e^* + \epsilon & \end{cases}$

$y^i$  is a feasible solution for (D).

a contradiction!

As  $y_{\bar{e}}^i > y_{\bar{e}}^*$ ,  $\sum_{e=1}^n y_e^i > \sum_{e=1}^n y_e^* \downarrow \text{OPT}$

cost:  $\sum_{j \in I} c_j = \sum_{j \in I} \sum_{e \in S_j} y_e^* = \sum_{e \in E} \underbrace{|\{j \mid j \in I : e \in S_j\}|}_{\leq f} y_e^* \leq f \left( \sum_{e=1}^n y_e^* \right) \leq f \cdot \text{OPT}$

PRIMAL-DUAL SC ALG.

Invariant:  $y$  is a feasible solution for (D)

(1)  $y_e = 0 \quad \forall e \in \{1, \dots, n\}; I := \emptyset; E := \emptyset$

(2) while there exists  $\bar{e} \notin E$  do F-covered elements

$$\epsilon = \min_{j: \bar{e} \in S_j} (c_j - \sum_{e \in S_j} y_e)$$

$y_{\bar{e}} := y_{\bar{e}} + \epsilon$   
 for each  $j$  s.t. ( $\bar{e} \in S_j$  and  $\sum_{e \in S_j} y_e = c_j$ ):  $I := I \cup \{j\}$   
 $E := E \cup S_j$

(3) OUTPUT  $I$

**THEM**: Primal-Dual SC alg. is an  $f$ -approximation alg.

Proof: time - in each iteration, at least one new element covered  $\Rightarrow$  poly

feasibility of  $I$ : as in the previous analysis from the description of the alg.

cost  $\sum_{j \in I} c_j = \sum_{j \in I} \sum_{e \in S_j} y_e \leq f \cdot \sum_{e=1}^n y_e \leq f \cdot \text{LP-OPT} \leq f \cdot \text{OPT}$

# INDEPENDENT SET PROBLEM

$G=(V,E)$  : find  $I \subset V$  s.t.  $I$  is ind. set

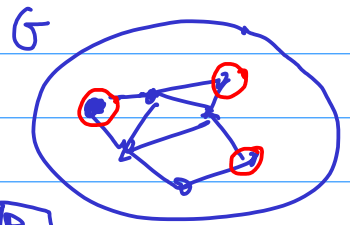
MAXIMUM IND. SET PROBLEM - find  $I$  of maximum size.

It holds:  $\forall \epsilon > 0$ , there is no  $n^{1-\epsilon}$ -approximation algorithm for the maximum ind. set problem, unless  $P=NP$ .

MAXIMAL IND. SET - an ind. set that cannot be extended

MODEL:

PRAM --- Parallel RAM



processors  $P_1, \dots, P_k$   
each local memory

$[P_1] [P_2] \dots [P_k]$

global memory

GLOBAL MEM.

$d_v \dots$  degree of  $v$

synchronized computation:

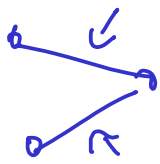
each step: global read

local computation

global write (no conflicts)

## PARAL - MAXIMAL IS

1.  $I := \emptyset$  ;  $V' := V$  ;  $G' := G$
2. while  $(V' \neq \emptyset)$  do
3. in parallel for  $\forall v \in V'$ : if  $d_v = 0$ , then  $I := I \cup \{v\}$   
 $V' := V' \setminus \{v\}$
4. in parallel for  $\forall v \in V'$  mark  $v$  with prob  $\frac{1}{2d_v}$   
(independ. for different vertices & iterations)
5. in parallel for  $\forall \{u,v\} \in E(G')$ : if both  $u,v$  marked, then unmark the lower degree vertex of  $u,v$



(break ties arbitrarily)

let  $S$  be the set of marked vertices and  $N(S)$  be their neighbours

6.  $I := I \cup S$  ;  $V' := V' \setminus (S \cup N(S))$  ;  $G' := G[V']$   
 7. OUTPUT  $\underline{I}$  induced by  $V'$

Let  $G_j = (V_j, E_j)$  --- the graph  $G'$  after iteration  $j$ .